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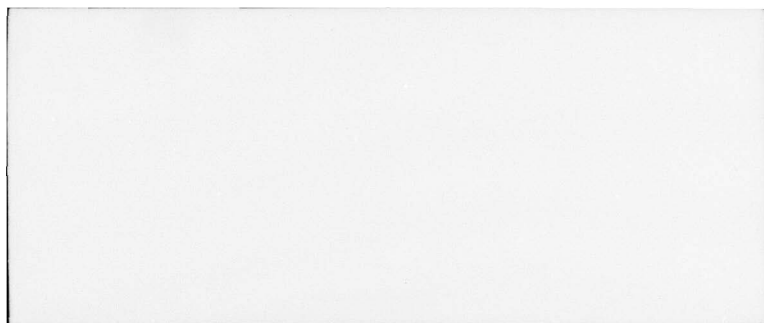
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I. INTRODUCTION

I. INTRODUCTION

↙ This report contains selected documentation of the MICOM real-time STINGER simulation. Sections II and III describe the MAIN program which serves as a driver for pre- and post-real-time computation, respectively. Other codes which support these computations are presented in Sections VI, VII, VIII, IX. The real-time computations are performed by Subroutines FLIGHT and REALT which are documented in Section IV. The interconnection of various computation elements is described in Section V which is titled Real-Time I/O.

In Appendix A the aforementioned code is presented. Then, in Appendix B a restructured version is given. The restructured documentation can be of considerable value. However, this value will only be realized from future development.

↗

II. PROGRAM MAIN (PRE-REAL-TIME)

II. PROGRAM MAIN (Pre-Real-Time)

Program MAIN provides both pre- and post-real-time functions. However, for purpose of documentation, program MAIN will be treated as two separate pieces of code dealing with pre- and post-real-time functions. In this section, pre-real-time computations performed by program MAIN are documented. Portions of program MAIN not included in this section are discussed in the next section.

Functionally, program MAIN serves to connect on a macroscopic level several physically separateable modules of code. In some cases however, computer implementation does not lead to a strictly modular code. Therefore, some portions of program MAIN involve the micro-codes which are, in concept, portions of other major modules.

Non-real time data input to the STINGER digital computer program is organized into three distinct levels. These three levels of data input are related to frequency of data change during normal simulation activities. Specifically, data can be input to the program in the following ways.

- Data card or DDS commands
- Block Data
- Inline computer code

Data input via block data or inline computer code requires careful attention to the particular code affected. Pre-programmed diagnostics and informative printout will not generally reveal errors in such modifications.

More information concerning pre-real time data processing is contained in the Sections titled SUBROUTINE KSCALE, INIT, and GUID.

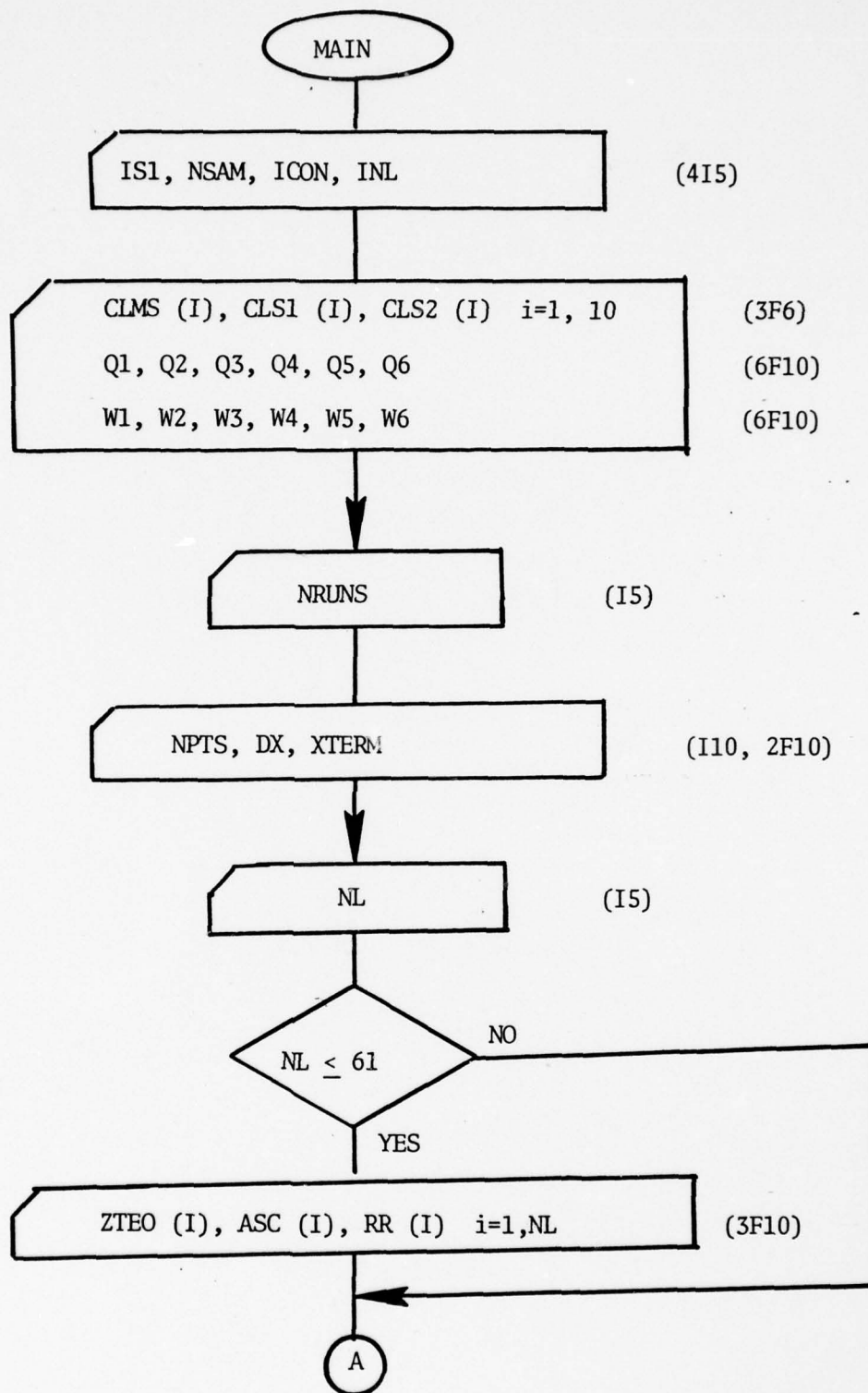
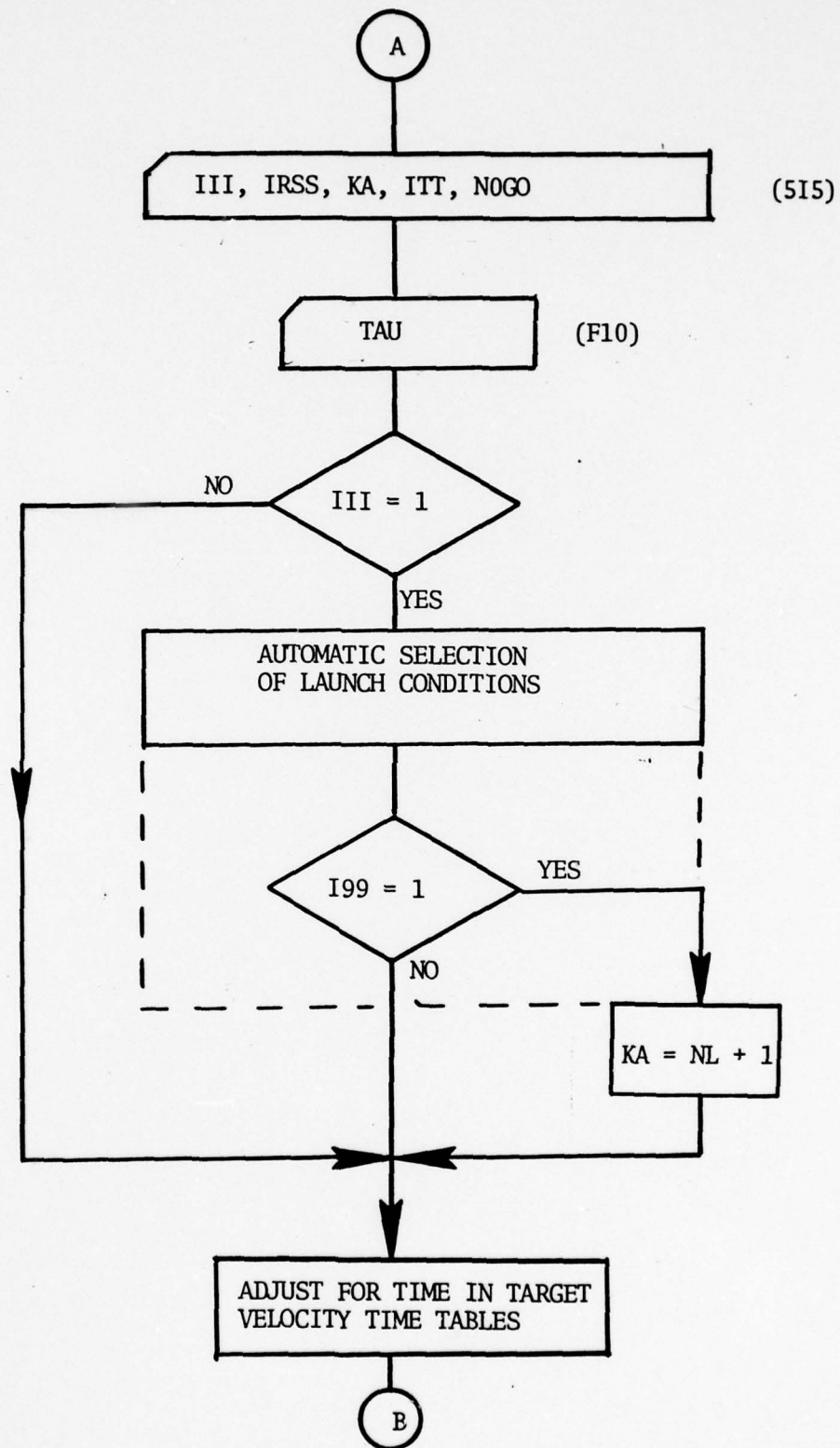
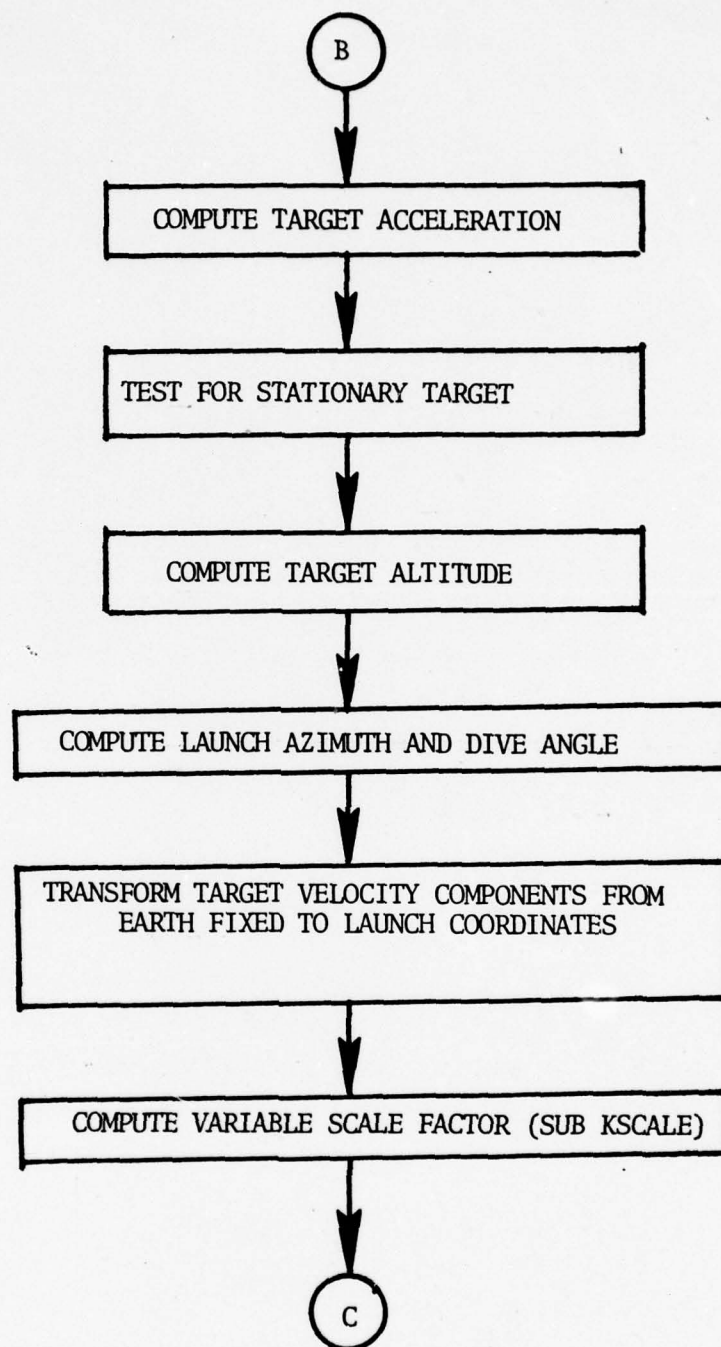
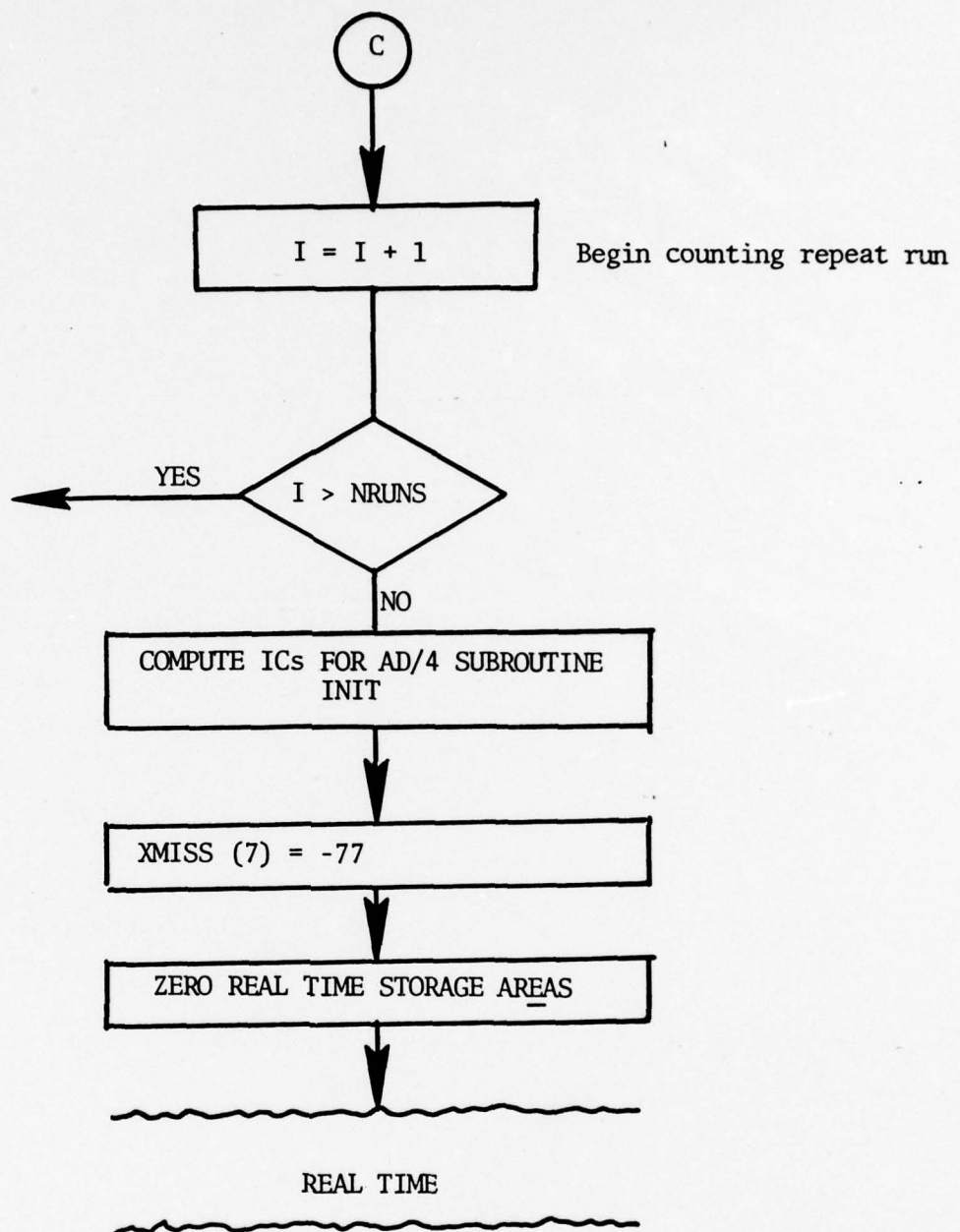


FIGURE 2.1 DATA CARD OR DDS DATA INPUT







TARGET ACCELERATION

$$\ddot{x}_{TE}(i) = \dot{x}_{TE}(i+1) - \dot{x}_{TE}(i), i = 1, 27$$

$$\ddot{y}_{TE}(i) = \dot{y}_{TE}(i+1) - \dot{y}_{TE}(i), i = 1, 27$$

$$\ddot{z}_{TE}(i) = \dot{z}_{TE}(i+1) - \dot{z}_{TE}(i), i = 1, 27$$

NOTE: ΔT , the time between samples in the target velocity tables, is assumed to be one second.

TEST FOR STATIONARY TARGETS

$$WVW = \sqrt{\dot{x}_{TE}^2(0) + \dot{y}_{TE}^2(0) + \dot{z}_{TE}^2(0)}$$

$WVW > 338 \text{ FT/SEC} \rightarrow \text{moving target}$

$WVW < 338 \text{ FT/SEC} \rightarrow \text{stationary target}$

TARGET ALTITUDE

$$h_{asL} = h + \Delta h$$

where Δh is altitude of launch point above sea level

ADJUSTMENT FOR TIME IN TARGET VELOCITY - TIME MANEUVER TABLES

Target velocity-time maneuver tables are shifted in time by the parameter TAU. Setting TAU to a positive real value causes the target trajectory time = TAU and real time = 0 to coincide. Therefore the portion of the target maneuver tables between time = 0 and time = TAU is disregarded. The end of the target maneuver tables is filled with a constant velocity maneuver, i.e., the portion of the trajectory between time = 27-TAU and time = 27 seconds. For TAU = 0 there is no shift in the target velocity - time maneuver tables.

EXAMPLE: TAU = 2.5

TM(I)	XDEM(J,ITT)	TMA(I)	XDM(I)	
0	XDEM(1,ITT)	-.5	XDEM(3,ITT)	+ t = 0
1	XDEM(2,ITT)	.5	XDEM(4,ITT)	
2	XDEM(3,ITT)	1.5	XDEM(5,ITT)	
.	.	.	.	
.	.	.	.	
23	XDEM(23,ITT)	22.5	XDEM(26,ITT)	
24	XDEM(24,ITT)	23.5	XDEM(26,ITT)	
25	XDEM(25,ITT)	25.0	XDEM(26,ITT)	
26	XDEM(26,ITT)	26.0	XDEM(26,ITT)	

LAUNCH AZIMUTH AND DIVE ANGLE

Calculation of launch angle and dive angle are based upon the following definitions and conventions:

- \bar{V} - Projection of target initial velocity vector on to the $X_E - Y_E$ plane
- \bar{W} - Projection of initial \bar{L}_{OS} vector in the $X_E - Y_E$ plane
- β - Angle from positive X_E axis to \bar{V} (positive clockwise)
- Σ_0 - Crossing angle = angle from \bar{V} to \bar{W} (positive clockwise)
- ψ_L - The angle from positive X_E axis to the vector from the origin to target (note this is just $-\bar{W}$)

From the above definitions $\Sigma_0 + \beta$ is the angle from positive X_E axis to vector \bar{W} . Then, since $-\bar{W}$ is in opposite direction from \bar{W} , the angle ψ_L differs from $\Sigma_0 + \beta$ by 180 degrees. Therefore

$$\psi_L = \Sigma_0 + \beta \pm 180^\circ$$

Here ψ_L is chosen base on whichever sign yields a positive value.

Based upon the value of $X_{TE}(0)$ and $Y_{TE}(0)$ the value of $\psi_L(0)$ is determined via four special computational rules. Note that the case $X_{TE}(0) \neq 0$ and $Y_{TE}(0) = 0$ is excluded from consideration and should not appear in candidate trajectories. The four computational rules as they are categorized in the computer code are:

CASE 1

$$\begin{array}{c|c} \dot{X}_{TE}(0) & \dot{Y}_{TE}(0) \\ \hline 0 & >0 \end{array}$$

$$\beta = \tan^{-1} (X_{TE}(0)/Y_{TE}(0))$$

$$\psi_L = \Sigma_0 + \beta - 180^\circ, \psi_L(0) \text{ is determined by whichever}$$

$$\Sigma_0 + \beta + 180^\circ \text{ quantity is positive}$$

SEO = (see computation in Subroutine INIT)

CASE 2

$\dot{x}_{TE}(0)$	$\dot{y}_{TE}(0)$
0	>0

$$\beta = 90^\circ$$

$$\psi_L(0) = \Sigma_0 + \beta - 180^\circ, \psi_L(0) \text{ is determined by whichever}$$
$$\Sigma_0 + \beta + 180^\circ \text{ quantity is positive}$$

SEO = (see computation in Subroutine INIT)

CASE 3

$\dot{x}_{TE}(0)$	$\dot{y}_{TE}(0)$
>0	>0
>0	<0
<0	>0
<0	<0

}Computer implementation does not take
care of this case

$$\beta = 270^\circ$$

$$\psi_L(0) = \Sigma_0 + \beta - 180^\circ \quad \psi_L(0) \text{ is determined by whichever}$$
$$\Sigma_0 + \beta + 180^\circ \text{ quantity is positive}$$

SEO = (see computation in Subroutine INIT)

CASE 4

$\dot{x}_{TE}(0)$	$\dot{y}_{TE}(0)$	and $z_{TE}(0) = 0$
0	0	
>0	0	}Computer implementation does not take care of these two cases
>0	0	

$$\psi_L(0) = 0$$

$$SEO = 0$$

For stationary target crossing angle
is not applicable, program sets KKK = 1

CASE 4b

$\dot{x}_{TE}(0)$	$\dot{y}_{TE}(0)$
0	0
>0	0} Computer implementation does not
<0	0} take care of these two cases

$$\psi_L(0) = 0$$

$$SEO = 90^\circ$$

For vertical target trajectory crossing
angle is not applicable, program sets KKK = 1

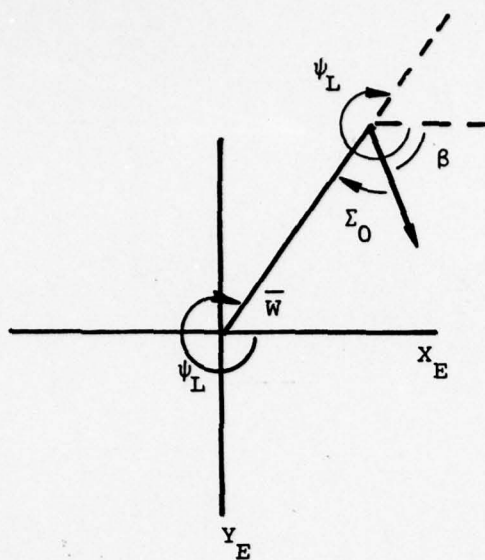
CASE 4c

$\dot{x}_{TE}(0)$	$\dot{y}_{TE}(0)$ and $z_{TE} < 0$
0	0
>0	0} Computer implementation does not
<0	0} take care of these two cases

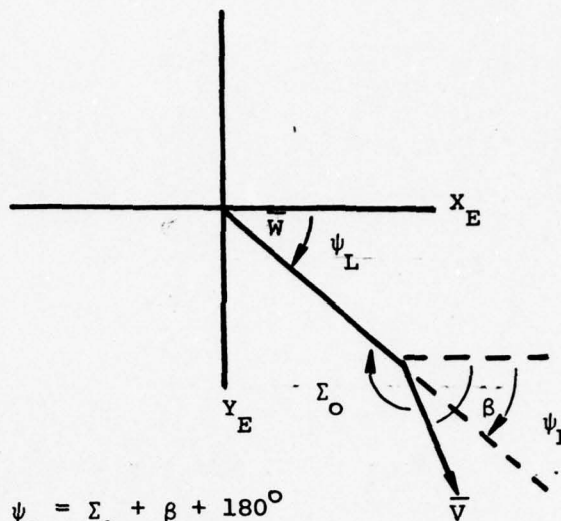
$$\psi_L(0) = 0$$

$$SEO = -90^\circ$$

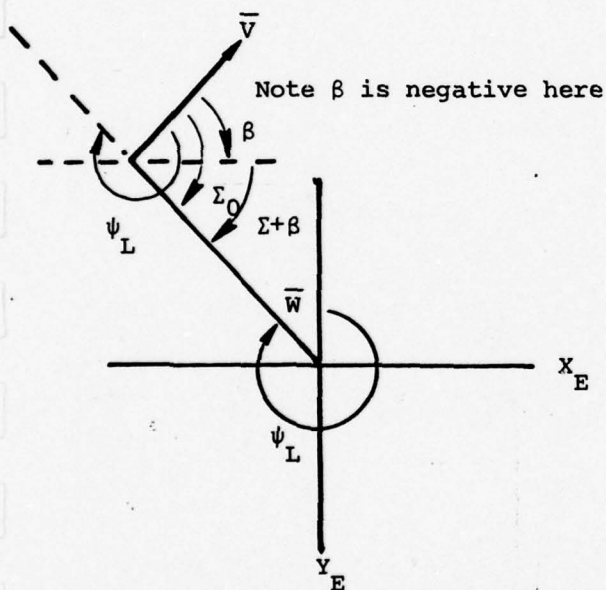
For vertical target trajectory
crossing angle is not applicable,
program sets KKK = 1



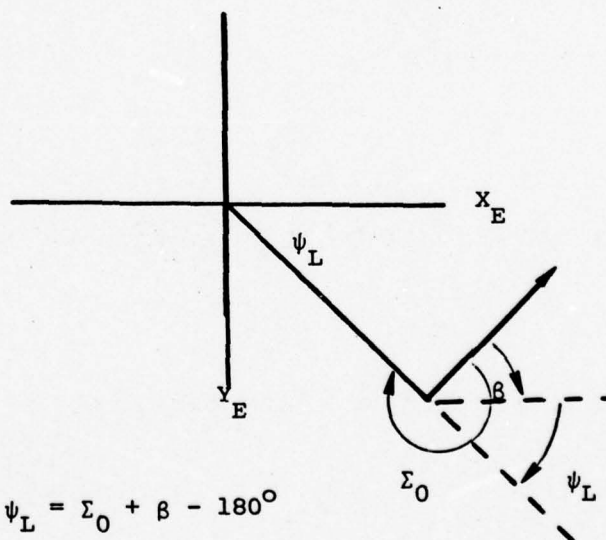
$$\psi_L = \Sigma_0 + \beta + 180^\circ$$



$$\psi_L = \Sigma_0 + \beta + 180^\circ$$



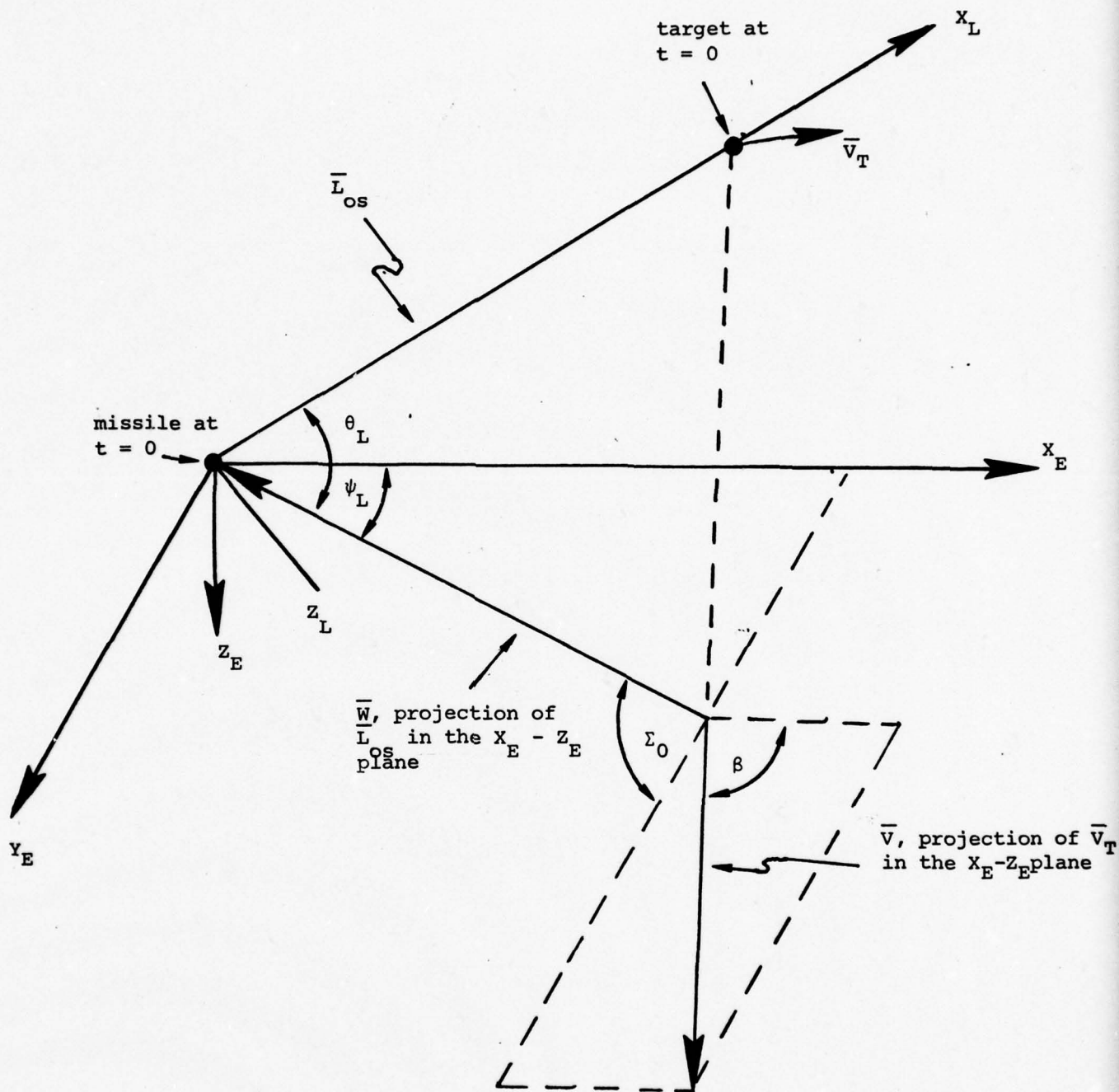
$$\psi_L = \Sigma_0 + \beta + 180^\circ$$



$$\psi_L = \Sigma_0 + \beta - 180^\circ$$

SOME POSSIBLE CONFIGURATIONS OF \bar{V} AND \bar{W}

FIGURE 2.2



RELATIONSHIP OF \bar{V} AND \bar{W} TO \bar{V}_T AND \bar{L}_{os}

FIGURE 2.3

TRANSFORMATION OF TARGET VELOCITY COMPONENTS FROM EARTH FIXED TO LAUNCH COORDINATES

$$\begin{bmatrix} x_{TL}(0) \\ y_{TL}(0) \\ z_{TL}(0) \end{bmatrix} \begin{bmatrix} \cos \theta_L \cos \psi_L & \cos \theta_L \sin \psi_L & -\sin \theta_L \\ -\sin \psi_L & \cos \psi_L & 0 \\ \sin \theta_L \cos \psi_L & \sin \theta_L \sin \psi_L & \cos \theta_L \end{bmatrix} \begin{bmatrix} x_{TE}(0) \\ y_{TE}(0) \\ z_{TE}(0) \end{bmatrix}$$

where $\theta_L = \theta_L(0)$

$\psi_L = \psi_L(0)$

This transformation is performed in Subroutine GUID

RANGE TABLE GENERATION

The range-table is generated for use as a data collection tool during real time simulation. The range table is a set of relative missile minus target positions along the X_L axis at which data collection should be performed. Generation of the range table follows from specification of

XTERM, the last data point to be collected

DX, the distance between data points

NPTS, number of data points desired

Provided analog scaling permits the collection of NPTS points, this is done. Otherwise, the program automatically reduces the value of NPTS until analog scaling requirements are satisfied. The new value of NPTS is stored for later usage as NADJ.

The rule for reducing NPTS to a final value of NADJ is given below

NADJ = NPTS, if DIF > 0
NPTS - truncated value of (DIF/DX)-1, if DIF \leq 0

Here DIF is defined as the difference between the data collection distance commanded and the largest data collection distance possible with the analog scaling given. DIF can be computed as follows

$$DIF = \{XTERM + (NPTS-1)DX\} - \left\{ \frac{(\text{Analog Scale Factor}) (\text{Largest Voltage})}{1 + \gamma} \right\}$$

TABLE 2.1 DESCRIPTION OF MAIN PROGRAM SYMBOLS (Pre-Real-Time)

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
IS1*	-----	Print flag, IS1 \neq 1 indicates print is desired.
NSAM*	-----	Quality control test case sample size $2 \leq \text{NSAM} \leq 11$
ICON*	-----	Automatic or manual launch set selection (ICON = 1 implies automatic, ICON = 2 implies manual)
INL*	-----	Number of first launch set desired in automatic mode, $1 \leq \text{INL} \leq 60$
CLMS(I)*	-----	{ Used in computation of quality control limits. For further information see SUBROUTINE QCLIM
CLS1(I)*	-----	
CLS2(I)*	-----	
Q1, Q2, ...Q6*	-----	
W1, W2, ...W6*	-----	
NRUNS*	-----	Number of runs ($\text{NRUNS} \leq 20$)
NPTS*	-----	Number of data points to be collected in real time
DX*	-----	Distance between real-time data collection points (FT)
XTERM*	-----	Distance between target and missile at last data collection point (FT)
NL*	-----	NL + 1 is number of launch sets to be read from data cards, if $\text{NL} \geq 61$
ZTEO(I)*	-----	Launch set target altitude in earth fixed coordinates (FT) (Note: printout shows - ZTEO(I))
ASC(I)*	Σ_0	Launch set target crossing angle table, measured positive clockwise from \bar{V} to \bar{W} (DEG)

*Data input from card reader

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
RR(I)*	R_i	Launch set target initial range table (FT) (distance measured along the line of sight)
III*	-----	Flag for automatic selection of target trajectory III = 1, for manual selection set III \neq 1.
IRSS*	-----	Flag, IRSS simulation requires IRSS = 1, for MICOM Hybrid set IRSS \neq 1.
KA*	-----	Index of target launch set. This is used in manual mode, i.e., III = 1
ITT*	-----	Trajectory number, ITT = 1 selects a stationary target. In general $1 \leq ITT \leq 45$
NOGO*	-----	
TAU*	τ	A parameter which selects a portion of the target velocity-time maneuver table for use in the simulation. This parameter shifts time forward TAU seconds and disregards all maneuver information between time = 0 and time = TAU. Note: $0 < TAU < 27$. With TAU = 0 the maneuver tables are unchanged. (SEC)
ZABOVE	Δh	Altitude of missile above sea level at $t = 0$
RTD	-----	Conversion factor for radians to degrees
DTR	-----	Conversion factor for degrees to radians
RLBK	L/B	L/B, actual plume ratio of length to breadth
NT	-----	Length of the trajectory time and velocity tables (currently NT = 27)
TMAS(K)	-----	Adjusted target time, see definition of τ

* Data input from card reader

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
I99	-----	Flag, if the current launch set number is a multiple of five or if this is the first launch set then I99 = 1. Otherwise I99 = 0
I88	-----	Flag, if this is last launch set in automatic selection sequence I88 = 1, otherwise I88 = 0
XE(I)	\ddot{x}_{TE}	Target acceleration tables, derived from target velocity tables.
YE(I)	\ddot{y}_{TE}	
ZE(I)	\ddot{z}_{TE}	
Z	$z_{TE}(0), h$	Specific launch altitude (from launch set table ZTEO)
ZZZ, ZALT	h_{asL}	Specific target altitude in earth fixed coordinates + altitude of missile launch site above sea level (FT)
AS	ϵ_0	Specific launch crossing angle (from launch set table ASC(I))
R	R_i	Specific launch initial range (from launch set table RR(I))
XD	$\dot{x}_{TE}(0)$	Initial target velocities in earth fixed coordinate system
YD	$\dot{y}_{TE}(0)$	
ZD	$\dot{z}_{TE}(0)$	
ASCO	ψ_L	Angle from positive X_E - axis to the vector from origin to target (note this is just $-W$)
SCO	ψ_L	ψ_L in DEG
SO	θ_L	Initial elevation angle of target (RAD)
ASO	θ_L	θ_L in DEG

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
X	$X_{TE}(0)$	X and Y components of \bar{L}_{os} in earth fixed coordinate system
Y	$Y_{TE}(0)$	
SINSO	$\sin(\theta_L)$	
COSSO	$\cos(\theta_L)$	
SINSCO	$\sin(\psi_L)$	
COSSCO	$\cos(\psi_L)$	
S2	$\cos(\theta_L)\cos(\psi_L)$	
S3	$\sin(\theta_L)\cos(\psi_L)$	
S4	$\cos(\theta_L)\sin(\psi_L)$	
S5	$\sin(\theta_L)\sin(\psi_L)$	
SPL	$\sin(\psi_L)$	
CTL	$\cos(\theta_L)$	
CPL	$\cos(\psi_L)$	
STL	-----	$\sin(\theta_L)$
KKK	-----	$KKK = 0$, if $\dot{Y}_{TE}(0) \neq 0$ 1 , if $\dot{Y}_{TE}(0) = 0$
VVV	$V_T(0)$	Initial velocity of target
XDTGO	$\dot{X}_{TL}(0)$	Components of target velocity in launch coordinates
YDTGO	$\dot{Y}_{TL}(0)$	
ZDTGO	$\dot{Z}_{TL}(0)$	
SEO	-----	Dive angle (Note: some cases are computed in SUBROUTINE INIT)

III. PROGRAM MAIN (POST-REAL-TIME)

III. PROGRAM MAIN (Post-Real-Time)

The post-real-time portion of the STINGER code provides an estimate of miss distance, lethality and simulation quality. In addition, the post-real-time code contains portions of the repeat run (rep-op) logic.

In general, the analysis in post-real-time data will contain the following events:

- If nonstationary target, calculate Euler angles for transformation from launch-to-target fixed coordinates
- Calculate the least square missile approach trajectory from collected A/D data and project miss distance information
- If the target is a high speed jet, perform a lethality test with the probability-of-kill model
- Repeat the simulated flight 20 times and obtain average PK, mean, and standard deviation of miss distance information
- Give control to pre-real time part for next simulation

More information concerning post-real-time data processing is contained in the Section titled SUBROUTINE MISCOM.

TIME CRITICAL DATA COLLECTION TEST

This test is performed to verify that each value of $X_{ML} - X_{TL}$ collected in real-time corresponds to a value in the range-to-go tables. The test is performed by testing each point collected as

$$XX_i \leq (X_{ML} - X_{TL})_i \leq XX_i + DX, i = 1, NADJ$$

where XX_i is the i'th entry in the pre-computed range-to-go table and $(X_{ML} - X_{TL})_i$ is the actual data point collected.

If time critical data collection failure is detected a diagnostic message is printed.

TABLE 3.1 DESCRIPTION OF MAIN PROGRAM SYMBOLS (Post-Real-Time)

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
NADJ	-----	The actual number of data collection points in real-time
XMISS(7)	-----	
PPX(I)	$X_{ML} - X_{TL}$	
PPY(I)	$Y_{ML} - Y_{TL}$	
PPZ(I)	$Z_{ML} - Z_{TL}$	
TIME(I)	t	Real time data collection points
VMX(I)	$\dot{X}_{ML} - \dot{X}_{TL}$	
VMY(I)	$\dot{Y}_{ML} - \dot{Y}_{TL}$	
VMZ(I)	$\dot{Z}_{ML} - \dot{Z}_{TL}$	
XX(I)	-----	Range-data collection table generated by SUBROUTINE INIT
LEVEL	-----	Status of maneuver, -7 implies not in real-time, 0 implies in real-time, +7 implies target trajectory table exceeded
ITT	-----	Target trajectory number, note: ITT = 1 is a stationary target
VVV	$V_T(0)$	Initial target velocity
IS1	-----	Print flag, IS1 \neq 1 indicates print is desired
XMAN(1,I)	t	Target maneuver velocity and time tables at range table data collection point (See MAN(J,I) in SUBROUTINE REALT)
XMAN(2,I)	\dot{X}_{TL}	
XMAN(3,I)	\dot{Y}_{TL}	
XMAN(4,I)	\dot{Z}_{TL}	

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
$XM(1), YM(1), ZM(1)$	-----	Missile trajectory peircing point in $Y_F' - Z_F'$ plane
$XM(2), YM(2), ZM(2)$	-----	Missile trajectory piercing point in $X_F' - Y_F'$ plane
$XM(3), YM(3), ZM(3)$	-----	Missile trajectory piercing point in $X_F' - Z_F'$ plane
$RM(1)$	-----	Nearest approach of missile trajectory to origin in the $Y_F' - Z_F'$ plane
$RM(2)$	-----	Nearest approach of missile trajectory to origin in the $X_F' - Y_F'$ plane
$RM(3)$	-----	Nearest approach of missile trajectory to origin in the $X_F' - Z_F'$ plane
$AXM(ICN)$	-----	Storage arrays for ICN'th repeat run, where ICN varies from 1 to NRUNS. The computer variables correspond to $XM(1), YM(1), ZM(1)$ and $RM(1)$ respectively
$AYM(ICN)$	-----	
$AZM(ICN)$	-----	
$ARM(ICN)$	-----	
$AXB(ICN)$	-----	Storage arrays for ICN'th repeat run, where ICN varies from 1 to NRUNS. The computer variables correspond to $XM(2), YM(2), ZM(2)$ and $RM(2)$ respectively
$AYB(ICN)$	-----	
$AZB(ICN)$	-----	
$ARB(ICN)$	-----	
$AXC(ICN)$	-----	Storage arrays for ICN'th repeat run, where ICN varies from 1 to NRUNS. The computer variables correspond to $XM(3), YM(3), ZM(3)$ and $RM(3)$ respectively
$AYC(ICN)$	-----	
$AZC(ICN)$	-----	
$ARC(ICN)$	-----	

PROGRAM SYMBOL	VARIABLE	DESCRIPTION
YA	a_1	See equations in SUBROUTINE MISCOM
ZA	a_2	See equations in SUBROUTINE MISCOM

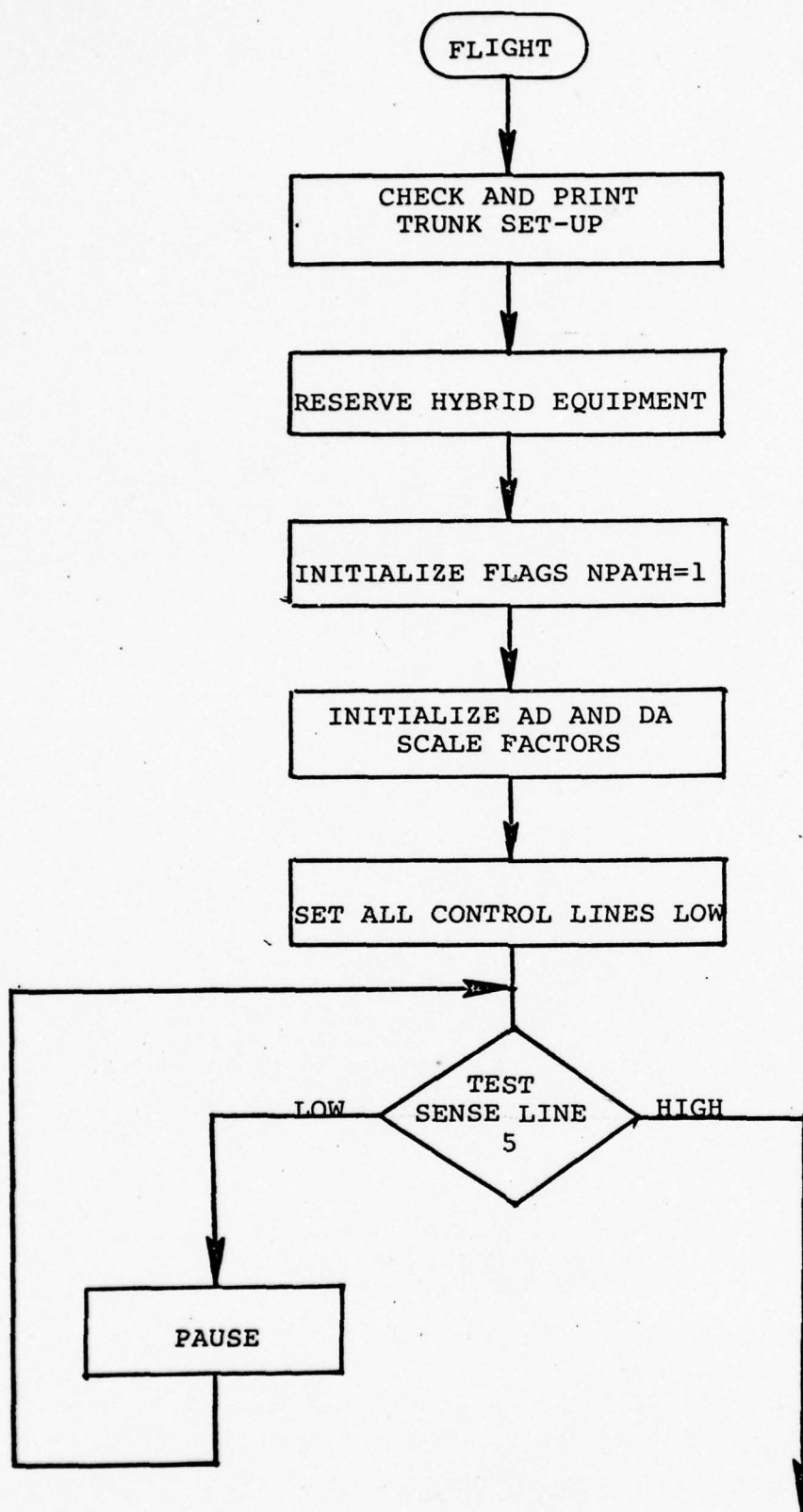
IV. SUBROUTINE FLIGHT AND REALT

IV. SUBROUTINE FLIGHT AND REALT (Real-Time)

This section contains a description of Subroutines required during real-time operation of the MICOM Hybrid STINGER simulation. The documentation is provided in three parts:

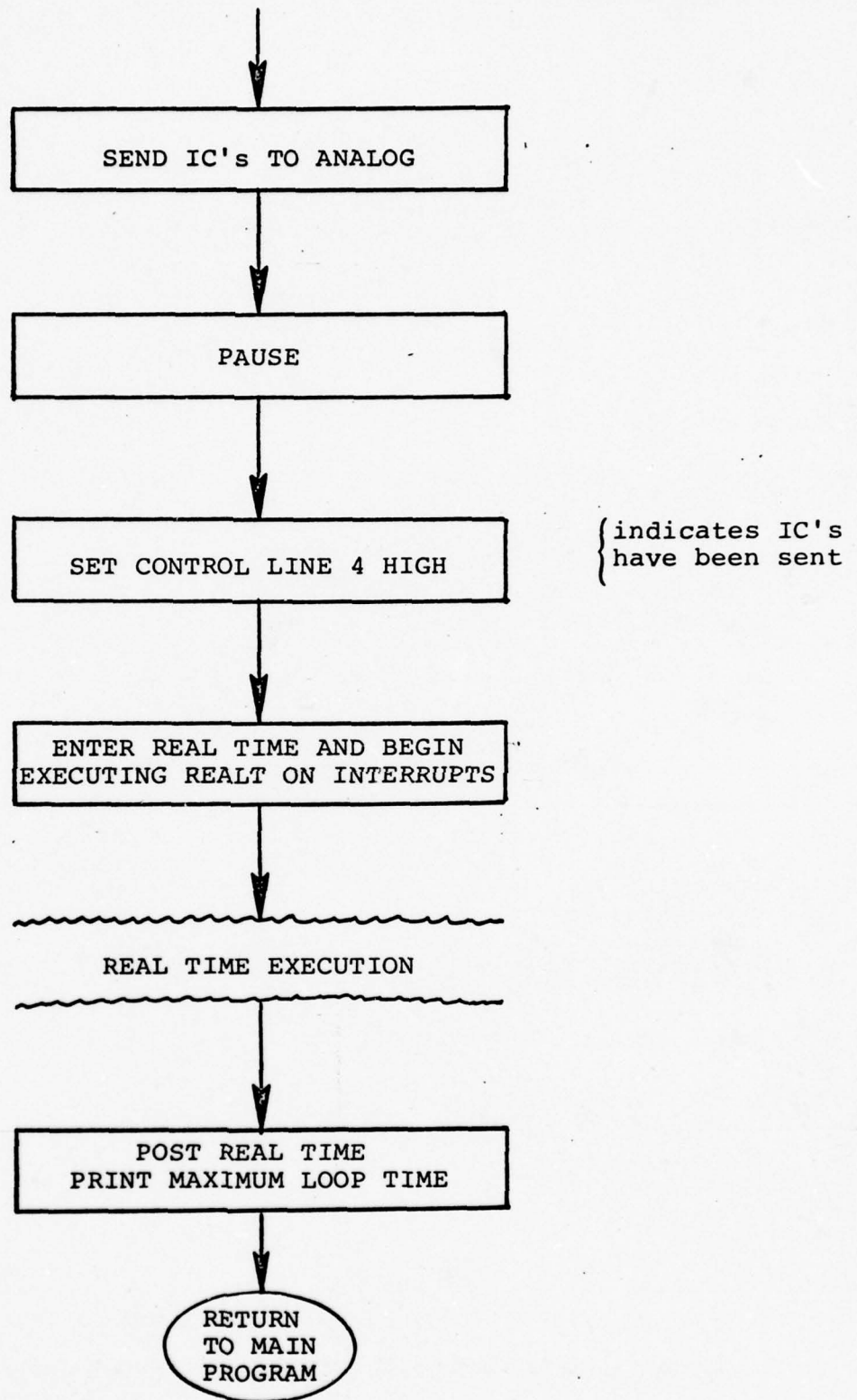
- Flow charts
- Equations
- Description of Symbols

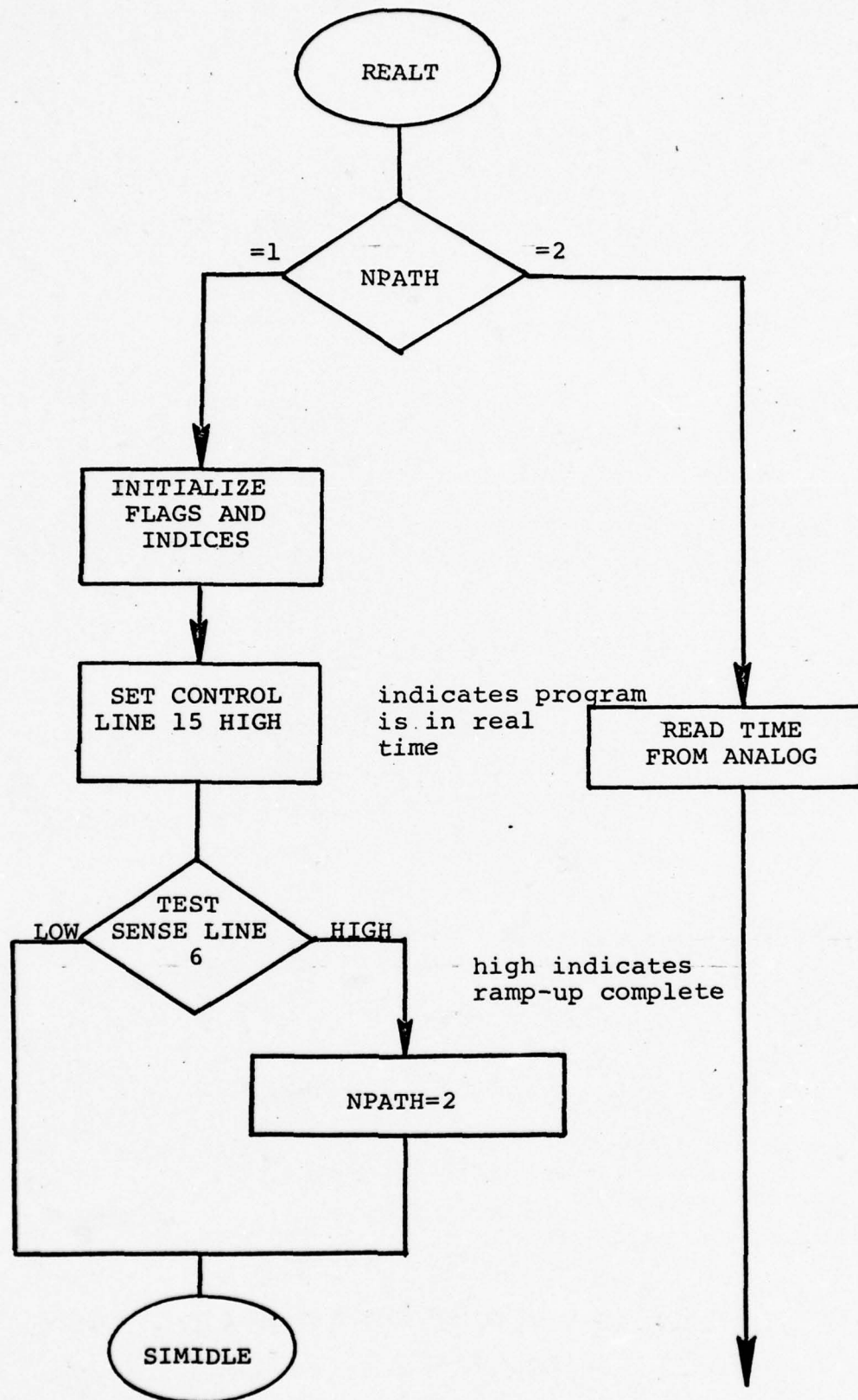
The flow chart given in Figure 4.1 only to the digital program. However, the equations and description of symbols are given for both analog and digital implementations.



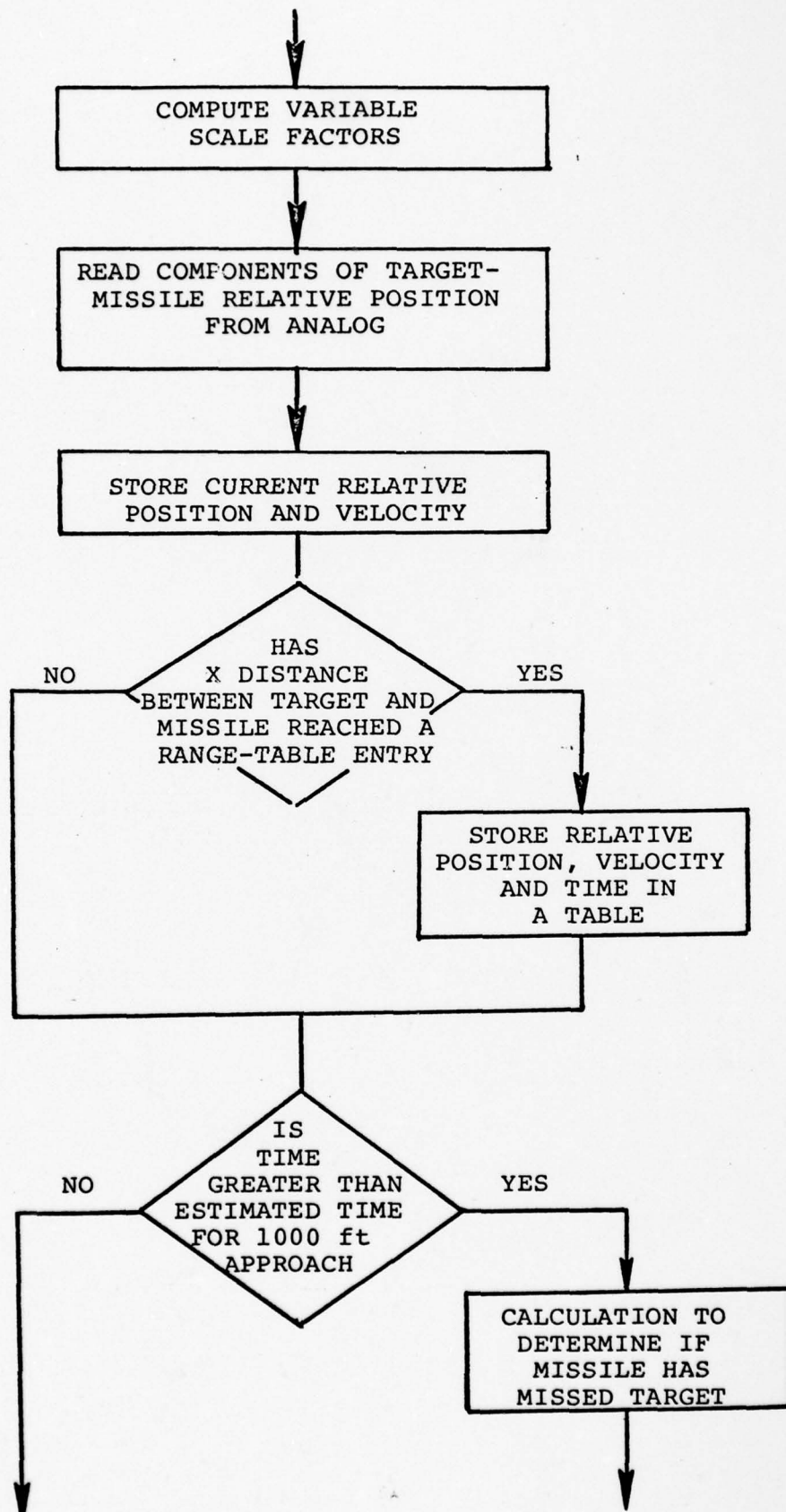
sense line 5 high
indicates static
test complete on
analog

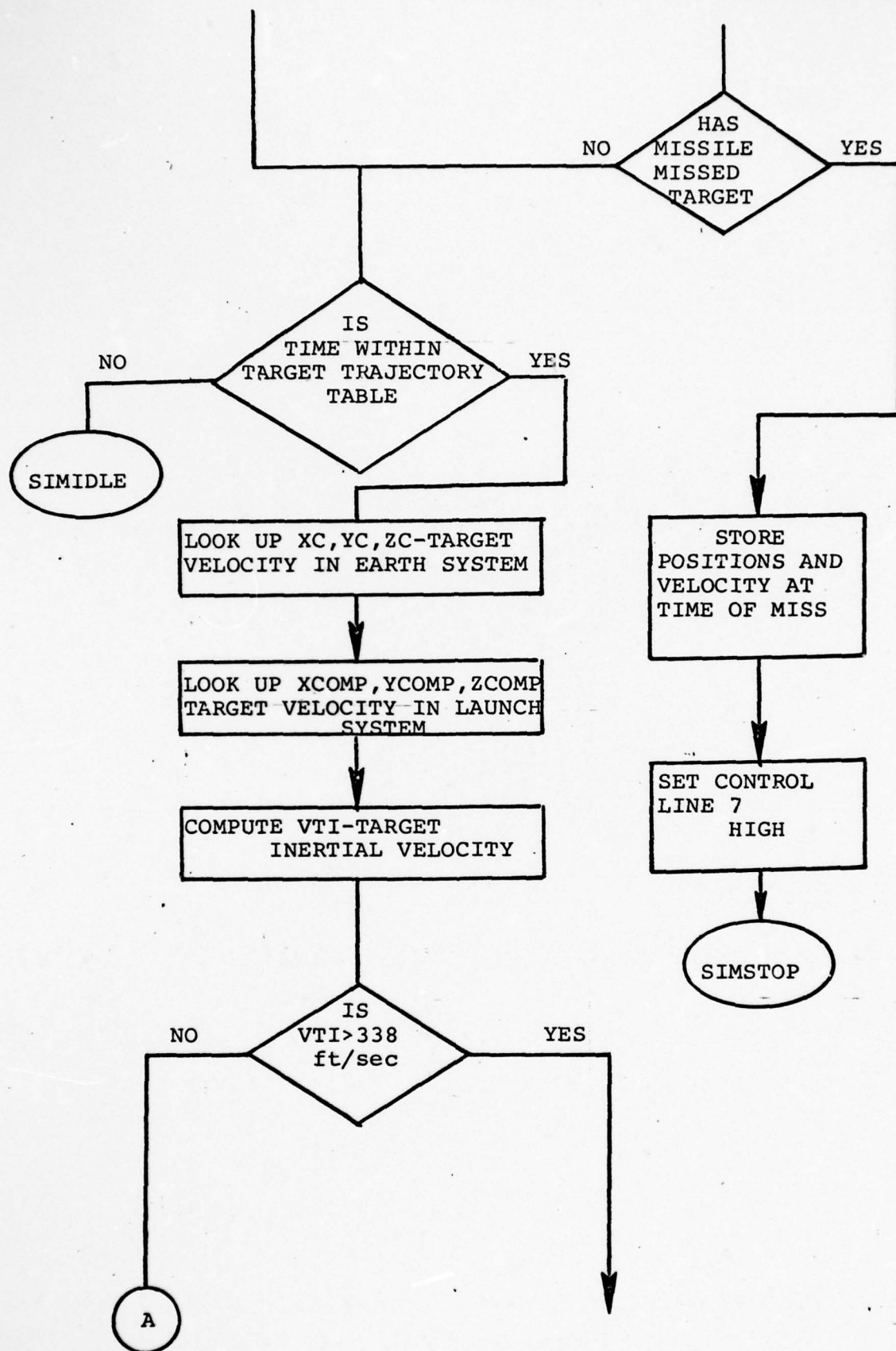
FLOW CHART FOR SUBROUTINE FLIGHT
FIGURE 4.1

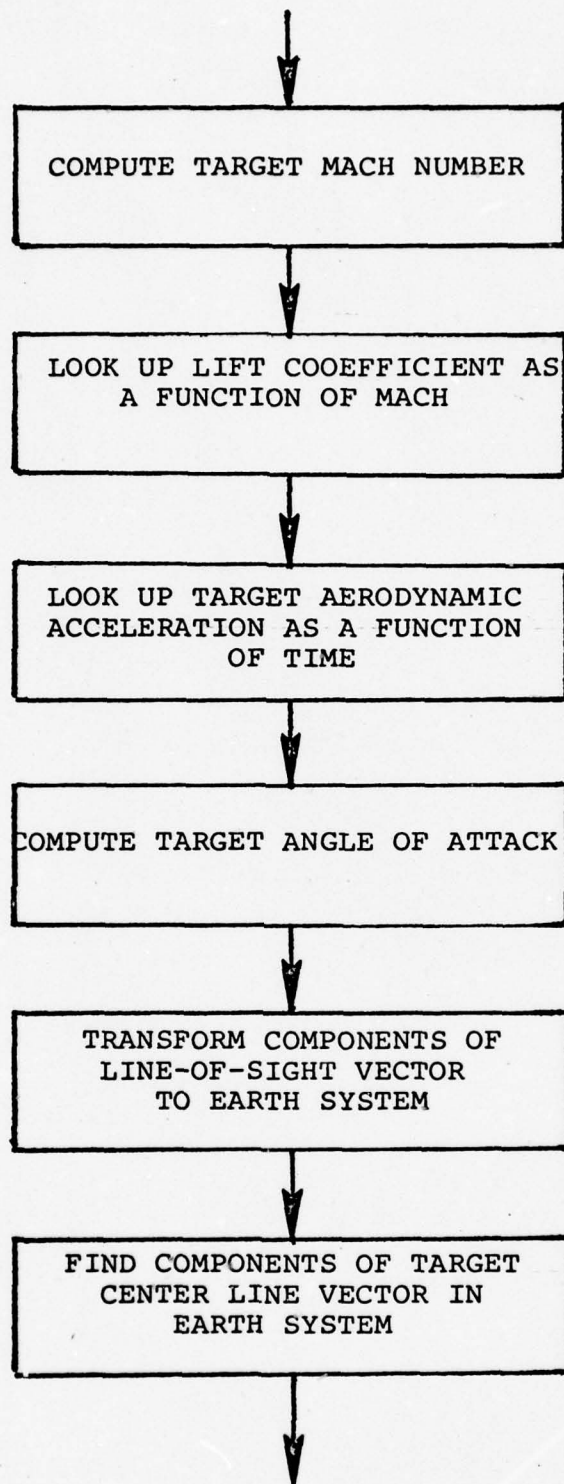


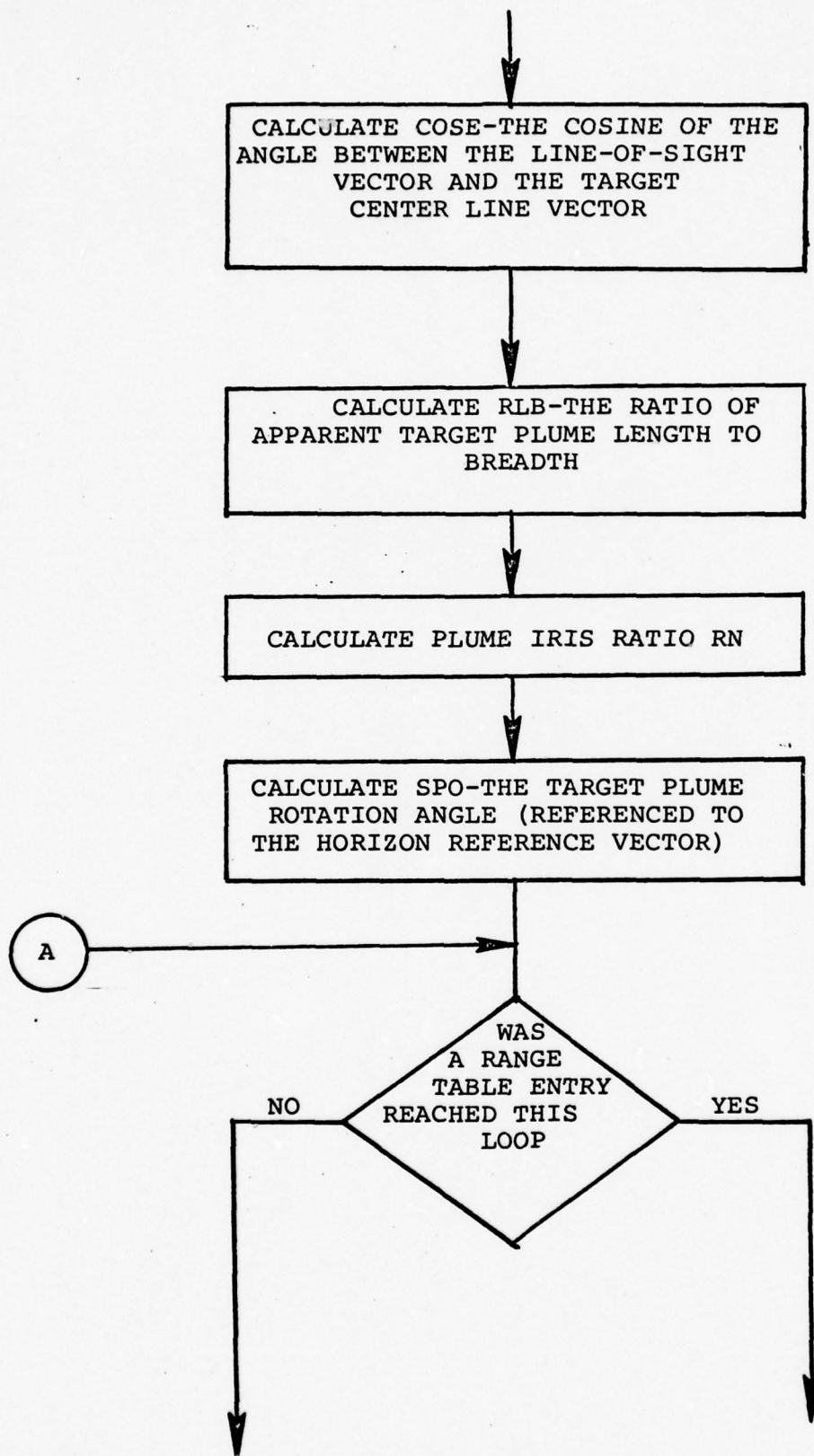


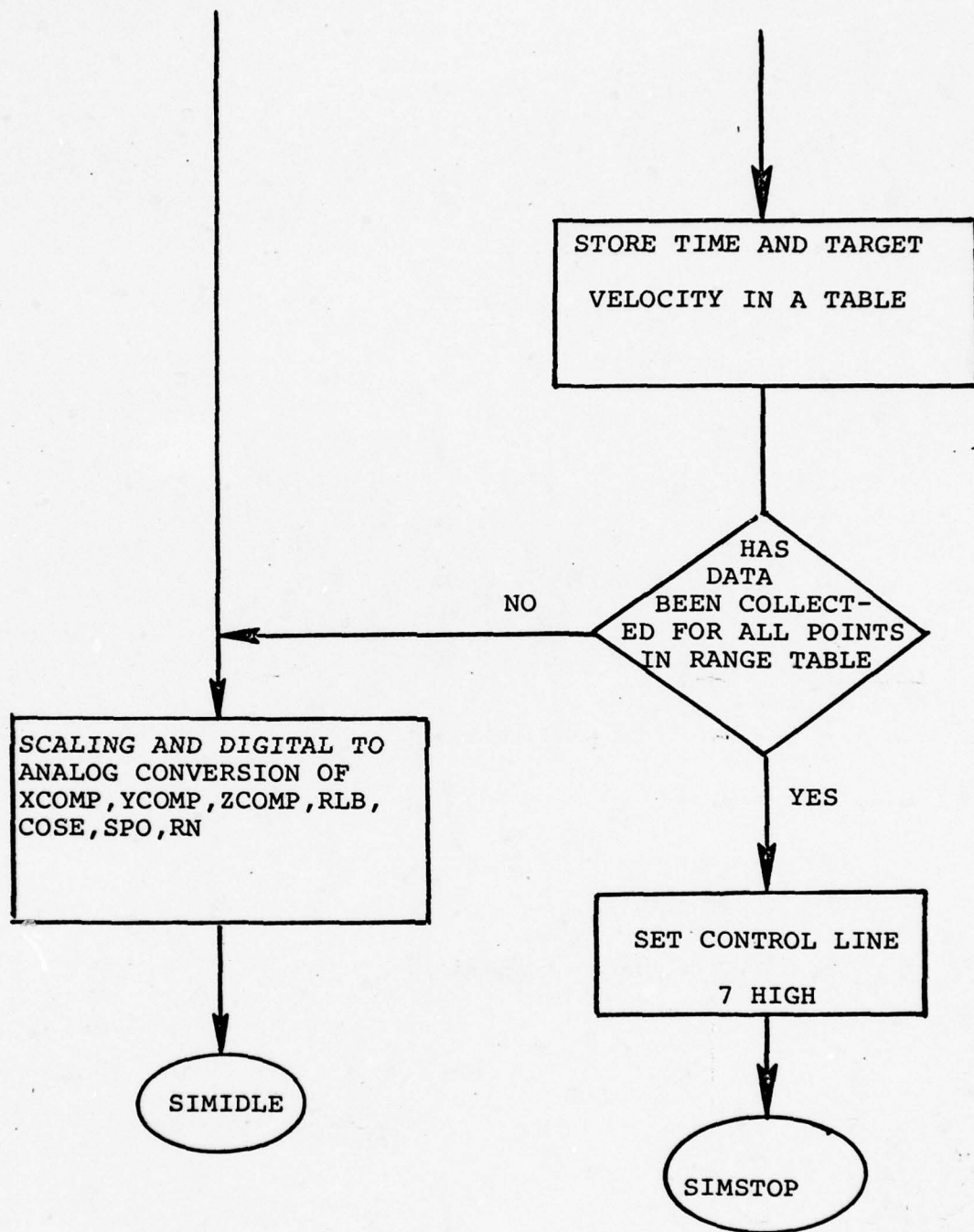
FLOW CHART FOR SUBROUTINE REALT
FIGURE 4.2











PLUME SHAPE

$$|\bar{L}_{os}| = \sqrt{(x_{ML} - x_{TL})^2 + (y_{ML} - y_{TL})^2 + (z_{ML} - z_{TL})^2}$$

$$P_1 = 2 \tan^{-1} \left(\frac{B/2}{l} \right) \quad (\text{DEG})$$

$$P_2 \text{ INCH}^\dagger = \frac{(f)(l)}{|\bar{L}_{os}|} \quad (\text{IN})$$

$$P_2 \text{ RAD}^\dagger = \tan^{-1} (l/|\bar{L}_{os}|) \quad (\text{RAD})$$

$$P_2 \text{ RAD}^\dagger = l/|\bar{L}_{os}| \quad (\text{RAD})$$

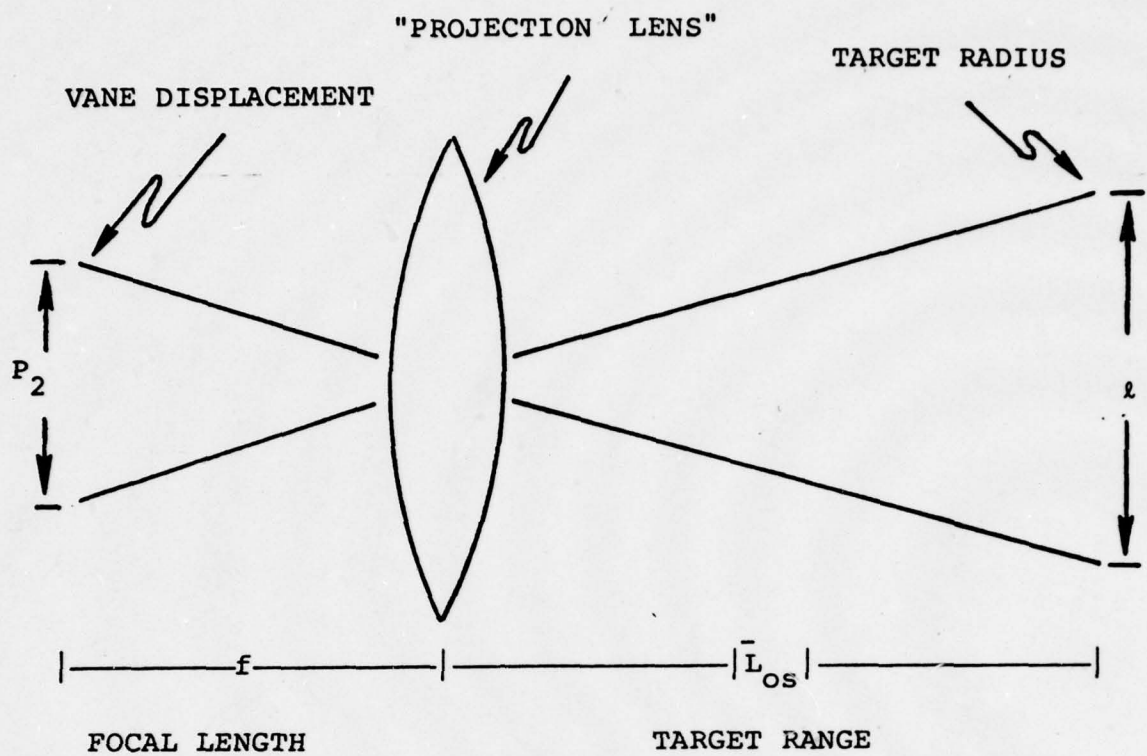


FIGURE 4.3
PLUME TRANSPARENCY

PLUME AZIMUTH AND ELEVATION

$$\psi_7 = \psi_4 - P_2 \cos (T_{RP}) \quad (\text{DEG})$$

$$\dot{\psi}_7 = \dot{\psi}_4 \quad (\text{DEG/SEC})$$

$$\theta_7 = \theta_4 - P_2 \sin (T_{RP}) \quad (\text{DEG})$$

$$\dot{\theta}_7 = \dot{\theta}_4 \quad (\text{DEG/SEC})$$

PLUME LENGTH TO BREADTH RATIO AND ASPECT ANGLE

$$l \approx L \sin (\epsilon) \quad \text{if } B < L, B=3.0$$

$$l = L \sqrt{1 - \cos^2 (\epsilon)}$$

$$l/B = \frac{L}{B} \sqrt{1 - \cos^2 (\epsilon)}$$

$$\cos (\epsilon) = \frac{\bar{L}_{os} \cdot \bar{C}_L}{|\bar{L}_{os}| |\bar{C}_L|}$$

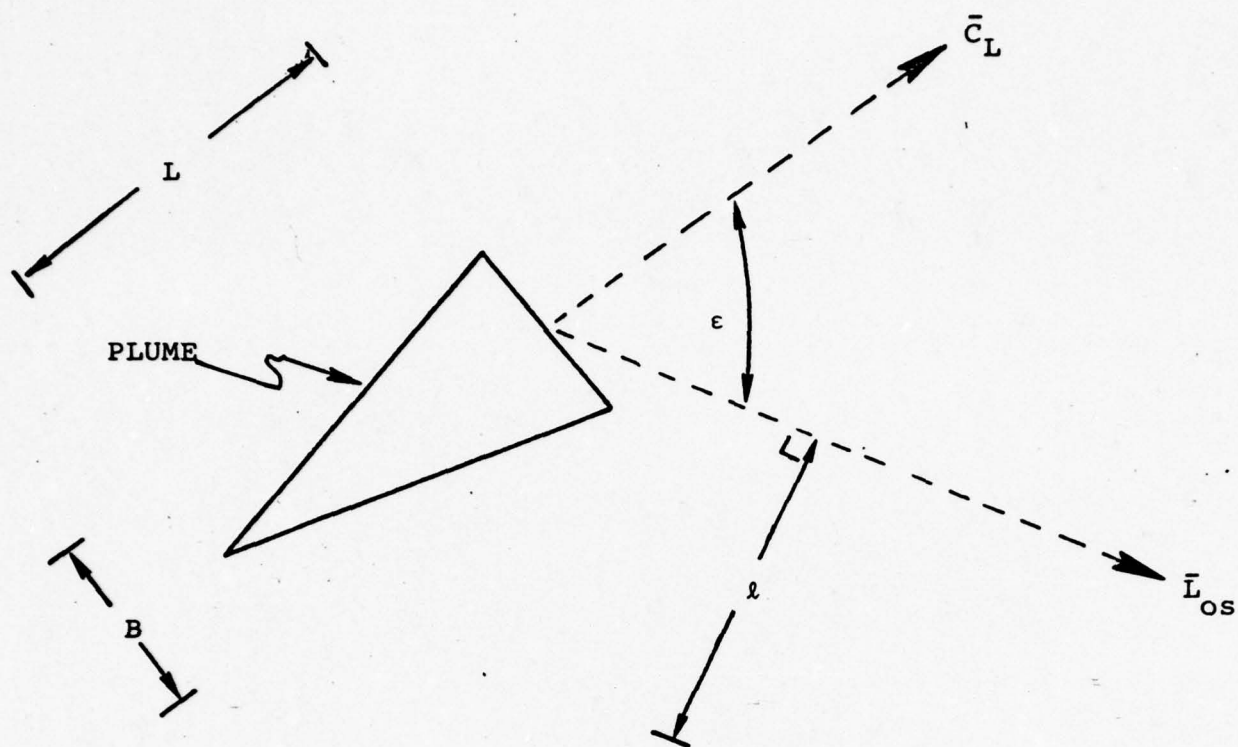


FIGURE 4.4
PLUME APPARENT LENGTH AND ASPECT ANGLE

PLUME IRIS RATIO

$$H_{c7} = \left(\frac{R}{7000} \right)^{-2.341} \left(H \middle|_{\epsilon}^{R=7000} \right) \quad (W/CM^2)$$

$$A_{t7} = \frac{P_2^2 \text{INCH} \sin(P_1)}{2 \cos^2(P_1/2)} \quad (IN^2)$$

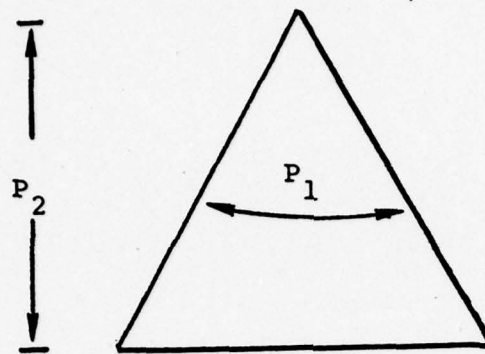
$$J_{tu7} = K_2 A_{t7}^{K_3}, \quad K_2 = .1, \quad K_3 = 1.003258 \quad (W/STER)$$

From IRSS Calibration
curve fit

$$I_{r7} = \frac{\frac{H_{c7} f^2}{T_{f, \text{plume}}}}{J_{tu}}$$

$$i_7 = i_7 (I_{r7})$$

From IRSS Calibration limits



$$\text{AREA} = P_2^2 \tan (P_1/2)$$

OR

$$\text{AREA} = \frac{P_2^2 \sin P_1}{2 \cos^2 (P_1/2)}$$

FIGURE 4.5
AREA OF PLUME TRANSPARENCY

PLUME ROTATION ANGLE

$$\beta = \cos^{-1} \left(\frac{L_X}{\sqrt{L_X^2 + L_Y^2}} \right)$$

$$C_X = -\cos \beta$$

$$C_Y = \begin{cases} +\sin \beta & \text{if } L_X > 0 \\ -\sin \beta & \text{if } L_X < 0 \end{cases}$$

$$D_X = L_Y \cdot C_{LZ} - L_Z \cdot C_{LY}$$

$$D_Y = L_Z \cdot C_{LY} - L_X \cdot C_{LZ}$$

$$D_Z = L_X \cdot C_{LY} - L_Y \cdot C_{LX}$$

$$\cos \theta = \frac{(\bar{L}_{os} \times \bar{C}_L) \cdot \bar{C}}{|\bar{L}_{os} \times \bar{C}_L| \cdot |\bar{C}|}, \text{ or } \theta = \cos^{-1} \left(\frac{(D_X \cdot C_X + D_Y \cdot C_Y)}{\sqrt{D_X^2 + D_Y^2 + D_Z^2}} \right)$$

$$T_{RP} = \begin{cases} \pi/2 - \theta & \text{if } D_Z < 0 \\ \pi/2 + \theta & \text{if } D_Z > 0 \text{ and } \theta < \pi/2 \\ \theta - 3\pi/2 & \text{if } D_Z > 0 \text{ and } \theta > \pi/2 \end{cases}$$

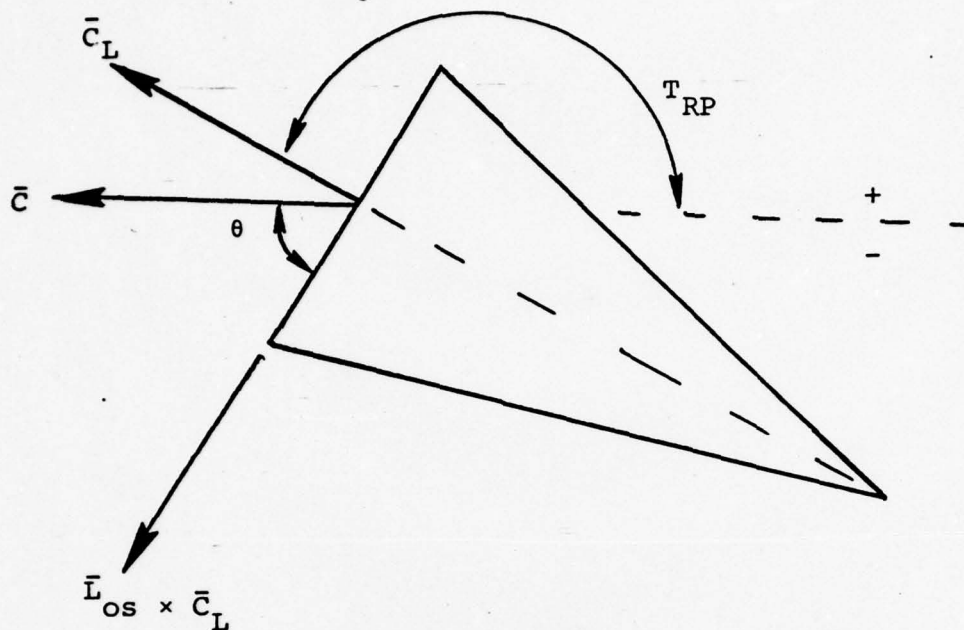


FIGURE 4.6

APPARENT TARGET PLUME AS SEEN FROM THE MISSILE SEEKER
 (THE PLANE OF THE PAPER IS PERPENDICULAR TO THE \bar{L}_{os} VECTOR)

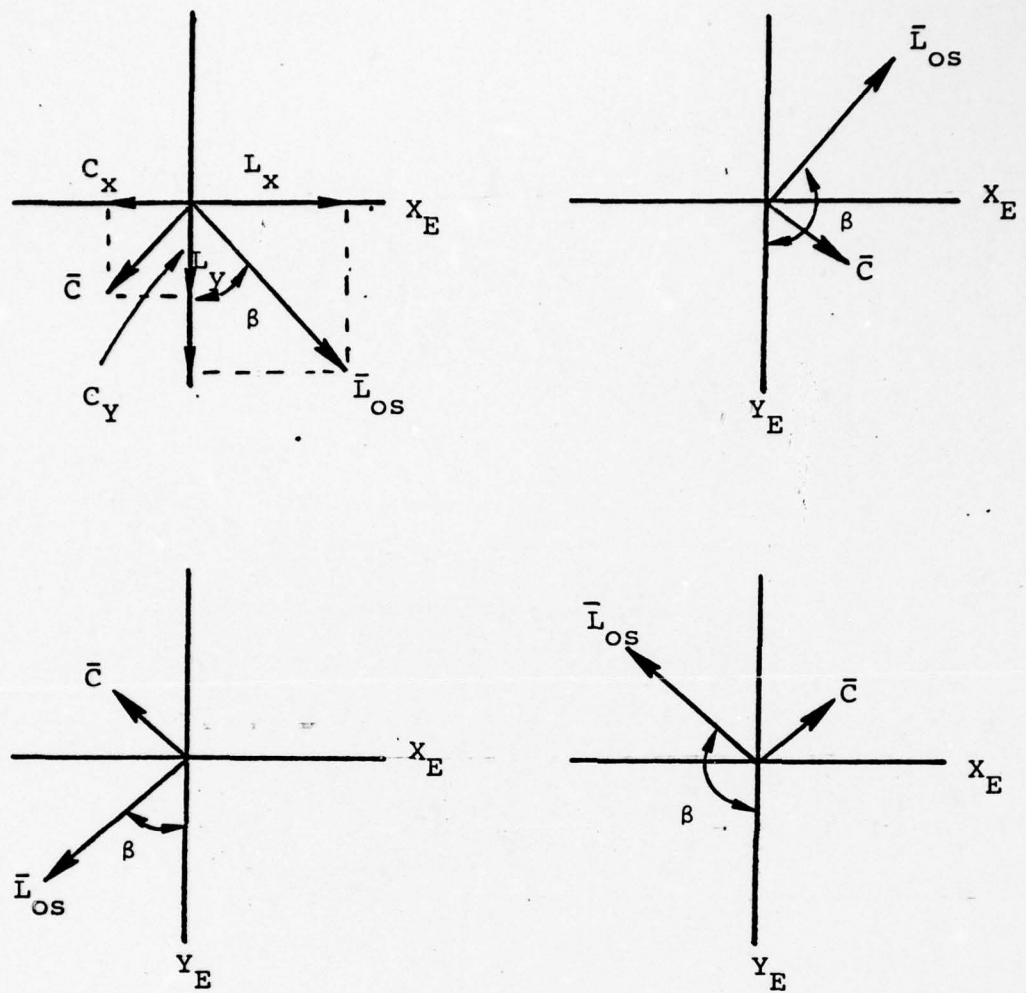


FIGURE 4.7
EXHAUSTION OF GENERAL CONFIGURATIONS FOR \bar{L}_{os} AND \bar{C}

TARGET ANGLE OF ATTACK AND MACH NUMBER

$$\rho = .00237692 e^{-.00003 h_{aSL}} \quad (\text{SLUGS/FT}^3)$$

$$V_T = \sqrt{\dot{X}_{TE}^2 + \dot{Y}_{TE}^2 + \dot{Z}_{TE}^2} \quad (\text{FT/SEC})$$

$$C_{L_{\alpha_T}} = CLAA \Big|_{Q_M}$$

$$a_s = 1116.89 - .003894 h_{aSL} \quad (\text{FT/SEC})$$

$$Q_M = V_T / a_s$$

$$h_{aSL} = \sqrt{X_{ML}^2 + Z_{ML}^2} \sin \left[\tan^{-1} \left(\frac{-Z_{ML}}{X_{ML}} \right) + \theta_L \right] + \Delta h^* \quad (\text{FT})$$

ΔL = Altitude of launch site above sea level (FT)

$$\alpha = \frac{2W_T}{\rho V_T^2 C_{L_{\alpha_T}} S_T g} \left(\sqrt{X_{TE}^2 + Y_{TE}^2 + Z_{TE}^2} \right) \quad (\text{RAD})$$

*THIS MODEL IS NOT CURRENTLY INCORPORATED IN THE MICOM REAL TIME SIMULATIONS.

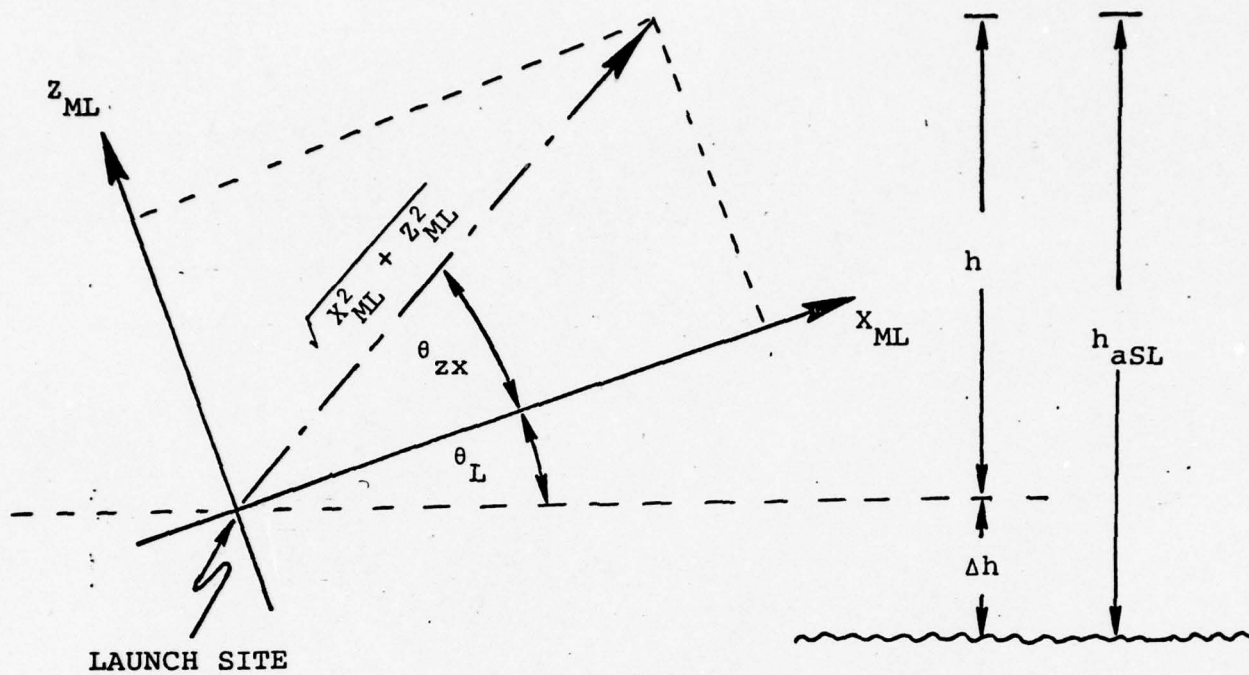


FIGURE 4.8 —
ALTITUDE OF TARGET ABOVE SEA LEVEL

FLARE TRANSPARENCY RADIUS AND IRIS RATIO

$$J_{tu2} = J_{tu2}(t_{FD}) \quad (W/STER), \text{ DFG}$$

$$R_F = \sqrt{(X_{ML} - X_{2L})^2 + (Y_{ML} - Y_{2L})^2 + (Z_{ML} - Z_{2L})^2}$$

$$H_{c2} = J_{tu2} / R_F^2 \quad (W/CM^2), \text{ DFG}$$

$$t_2 = t_2(H_{c2}) \quad (RAD), \text{ DFG}$$

$$i_2 = i_2(H_{c2}) \quad (RAD), \text{ DFG based on IRSS calibration limits.}$$

FLARE AZIMUTH AND ELEVATION

$$\sigma_{Y2} = \frac{Y_{ML} - Y_{2L}}{X_{ML} - X_{2L}} \quad (\text{RAD})$$

$$\psi_{24REL} = \begin{cases} 57.3 (\sigma_{Y4} - \sigma_{Y2}), & t \geq t_{EJECT} \\ 0, & t < t_{EJECT} \end{cases} \quad (\text{DEG.})$$

$$\dot{\psi}_{24REL} = 57.3 \left\{ \left[\frac{(\dot{Y}_{ML} - \dot{Y}_{4L}) - \sigma_{Y4} (\dot{X}_{ML} - \dot{X}_{4L})}{X_{ML} - X_{4L}} \right] - \left[\frac{(\dot{Y}_{ML} - \dot{Y}_{2L}) - \sigma_{Y2} (\dot{X}_{ML} - \dot{X}_{2L})}{X_{ML} - X_{2L}} \right] \right\} \quad (\text{DEG/SEC})$$

$$\psi_2 = \psi_4 - \psi_{24REL} \quad (\text{DEG})$$

$$\dot{\psi}_2 = \dot{\psi}_4 - \dot{\psi}_{24REL} \quad (\text{DEG/SEC})$$

$$\theta_{24REL} = \begin{cases} -57.3 (\sigma_{Z4} - \sigma_{Z2}), & t > t_{EJECT} \\ 0, & t < t_{EJECT} \end{cases} \quad (\text{DEG})$$

$$\dot{\theta}_{24REL} = -57.3 \left\{ \left[\frac{(\dot{Z}_{ML} - \dot{Z}_{4L}) - \sigma_{Z4} (\dot{X}_{ML} - \dot{X}_{4L})}{(X_{ML} - X_{4L})} \right] - \left[\frac{(\dot{Z}_{ML} - \dot{Z}_{2L}) - \sigma_{Z2} (\dot{X}_{ML} - \dot{X}_{2L})}{(X_{ML} - X_{2L})} \right] \right\} \quad (\text{DEG/SEC})$$

FLARE DYNAMICS

$$\ddot{x}_{2L} = \frac{-\rho C_{D2} S_2 V_2}{2M_2} x_{2L} - g \sin \theta_L, \quad t > t_{EJECT}$$

$$\ddot{y}_{2L} = \frac{-\rho C_{D2} S_2 V_2}{2M_2} y_{2L}, \quad t > t_{EJECT}$$

$$\ddot{z}_{2L} = \frac{-\rho C_{D2} S_2 V_2}{2M_2} z_{2L} + g \cos \theta_L, \quad t > t_{EJECT} \quad (FT/SEC^2)$$

$$x_{2L} = x_{4L}$$

$$y_{2L} = y_{4L}$$

$$z_{2L} = z_{4L}$$

$$\dot{x}_{2L} = \dot{x}_{4L}$$

$$\dot{y}_{2L} = \dot{y}_{4L}$$

$$\dot{z}_{2L} = \dot{z}_{4L}$$

$t < t_{EJECT}$

(FT)

TAILPIPE AZIMUTH AND ELEVATION

$$\sigma_{Y4} = \frac{Y_{ML} - Y_{4L}}{X_{ML} - X_{4L}} \quad (\text{RAD})$$

$$\psi_4 = 57.3 \sigma_{Y4} \quad (\text{DEG})$$

$$\dot{\psi}_4 = 57.3 \left[\frac{(\dot{Y}_{ML} - \dot{Y}_{4L}) - \sigma_{Y4} (\dot{X}_{ML} - \dot{X}_{4L})}{(X_{ML} - X_{4L})} \right] \quad (\text{DEG/SEC})$$

$$\sigma_{Z4} = \frac{Z_{ML} - Z_{4L}}{X_{ML} - X_{4L}} \quad (\text{RAD})$$

$$\theta_4 = -57.3 \sigma_{Z4} \quad (\text{DEG})$$

$$\dot{\theta}_4 = -57.3 \left[\frac{(\dot{Z}_{ML} - \dot{Z}_{4L}) - \sigma_{Z4} (\dot{X}_{ML} - \dot{X}_{4L})}{(X_{ML} - X_{4L})} \right] \quad (\text{DEG/SEC})$$

PITCH, YAW AND ROLL POSITIONS

$$P = 57.29 \int q' dt \quad (\text{DEG})$$

$$Y = 57.29 \int r' dt \quad (\text{DEG})$$

$$R = R(p') \quad (\text{DEG})$$

TRANSFORMATION OF \bar{C}_L AND \bar{L}_{OS} FROM LAUNCH TO EARTH COORDINATES

$$\bar{C}_L = \bar{i}_E \left\{ \frac{X_{TE}}{V_T} \cos(\alpha) + \frac{X_{TE} Z_{TE} \sin(\alpha)}{V_T \sqrt{X_{TE}^2 + Y_{TE}^2}} \right\}$$

$$+ \bar{j}_E \left\{ \frac{Y_{TE}}{V_T} \cos(\alpha) + \frac{Y_{TE} Z_{TE} \sin(\alpha)}{V_T \sqrt{X_{TE}^2 + Y_{TE}^2}} \right\}$$

$$+ \bar{k}_E \left\{ \frac{Z_{TE} \cos(\alpha)}{V_T} - \frac{\sqrt{X_{TE}^2 + Y_{TE}^2} \sin(\alpha)}{V_T} \right\}$$

$$\bar{L}_{OS} = \bar{i}_E (X_G \cos \theta_L \cos \psi_L - Y_G \sin \psi_L + Z_G \sin \theta_L \cos \psi_L)$$

$$+ \bar{j}_E (X_G \cos \theta_L \sin \psi_L + Y_G \cos \psi_L + Z_G \sin \theta_L \sin \psi_L)$$

$$+ \bar{k}_E (-X_G \sin \theta_L + Z_G \cos \theta_L)$$

$$X_G = X_{ML} - X_{TL}$$

$$Y_G = Y_{ML} - Y_{TL}$$

$$Z_G = Z_{ML} - Z_{TL}$$

VARIABLE SCALE FACTOR

$$K = \begin{cases} 1 + \frac{\gamma t}{t'}, & t < t' \\ 1 + \gamma & t > t' \end{cases}$$

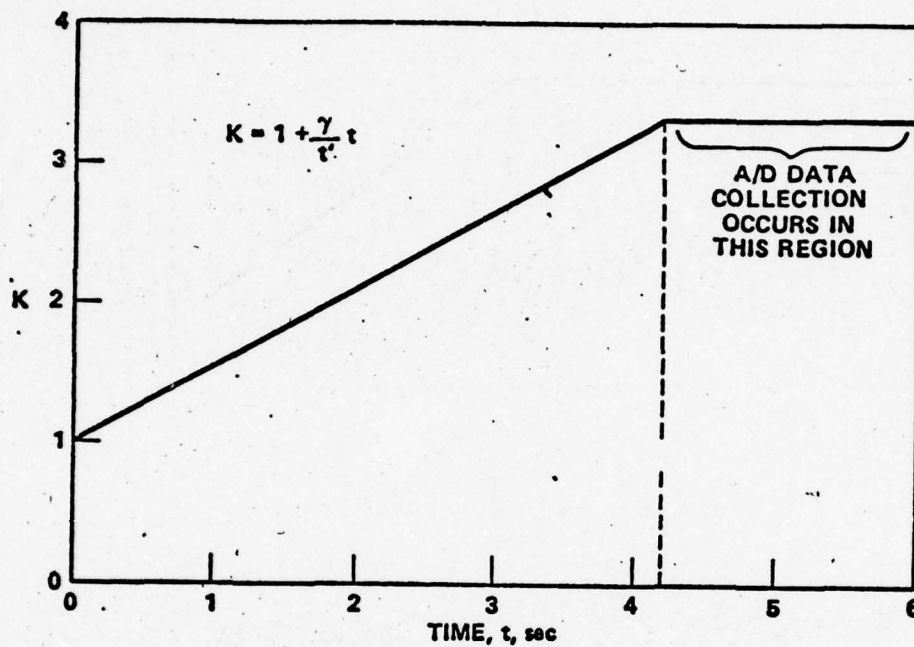


FIGURE 4.9
VARIABLE ANALOG SCALE FACTOR

TABLE 4.1

DESCRIPTION OF PROGRAM SYMBOLS
FOR SUBROUTINE FLIGHT AND REALT

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
_____	SPO	Scaled plume rotation angle
T_{RP}	TRP	Plume rotation angle (RAD.)
θ_L	THETAL	Elevation angle of target (DEG.)
_____	_____	_____
t	DT	Real time (SEC.)
g	_____	Gravitational constant
x_E	XE	{ Target aerodynamic acceleration table in earth fixed coordinates (Note ZE includes an added factor of 32.174 FT/SEC/SEC
y_E	YE	
z_E	ZE	
α	Al	Target angle of attack (RAD.)
t'	G,GAM	Time at approximately 1000 feet to go
$C_{L_{\alpha_T}}$	CLA	Aerodynamic lift coefficient of target due to angle of attack
\bar{V}_{TI}	VTI	Target inertial velocity
l/B	RLB	Apparent plume length to breadth ratio
E	_____	Subscript which denotes earth fixed coordinates
ψ_L	_____	Azimuth angle of target (DEG.)

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
F	_____	Subscript which denotes target fixed coordinates
L	_____	Subscript which denotes launch coordinates
R _i	RI	Initial range (FT.)
R _{FT}	RFEET	Range (FT)
_____	EDOT	Scaled γ/t'
ρ	PHO	Air density (SLUGS/FT ³)
γ_{min}	GGG	Minima of the overload function
K	SKK	Variable scale factor, $K = \begin{cases} 1 + \frac{\gamma t}{t'} & , \quad t \leq t' \\ 1 + \gamma & , \quad t > t' \end{cases}$
_____	XX	Range table for data collection
_____	XXS	Scaled range table (XX)

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
I_{r7}	RN	For MICOM Hybrid, a uniform random number, $RN \in (-1,1)$ For IRSS, iris ratio number 7
$\cos(\epsilon)$	COSE	Cosine of angle between LOS and center line of target
$x_{ML} - x_{TL}$	DX	Scaled XXX, YYY, ZZZ (NOTE: these variables may overload on the AD/4 until time = t')
$y_{ML} - y_{TL}$	DY	
$z_{ML} - z_{TL}$	DZ	
t	DT	Real time
$x_{ML} - x_{TL}$	XXX	x-Missile minus x-target position (FT.)
$y_{ML} - y_{TL}$	YYY	y-Missile minus y-target position (FT.)
$z_{ML} - z_{TL}$	ZZZ	z-Missile minus z-target position (FT.)
$\dot{x}_{ML} - \dot{x}_{TL}$	XDOT	x-Missile minus x-target velocity (FT./SEC.)
$\dot{y}_{ML} - \dot{y}_{TL}$	YDOT	y-Missile minus y-target velocity (FT./SEC.)
$\dot{z}_{ML} - \dot{z}_{TL}$	ZDOT	z-Missile minus z-target velocity (FT./SEC.)

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
\dot{x}_{TL}	XDTGMS	Tables of target velocity components in launch system
\dot{y}_{TL}	YDTGMS	
\dot{z}_{TL}	ZDTGMS	
β	_____	$\cos^{-1} (L_y / \sqrt{L_x^2 + L_y^2})$
h	ZALT	Altitude of missile above sea level (FT.)
_____	XCOMP	Interpolated value of XDTGMS
_____	YCOMP	Interpolated value of YDTGMS
_____	ZCOMP	Interpolated value of ZDTGMS
\dot{x}_{TE}	XC	Interpolated value of XDM
\dot{y}_{TE}	YC	Interpolated value of YDM
\dot{z}_{TE}	ZC	Interpolated value of ZDM

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
—	XDM	Tables of target velocity components in earth system
—	YDM	
—	ZDM	
—	TIME	Storage for missile position, velocity and time in the region of pre-specified range table entries
—	PPX	
—	PPY	
—	PPZ	
—	VMX	
—	VMY	
—	VMZ	
—	IPTS	Number of points in range table
—	MISSED	An array of values representing miss conditions
—	Tlll	Angle between ($\overline{LOS} \times \overline{C}_L$) and horizon reference vector

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
x_G	—	x-Missile minus x-target (in launch coordinates)
y_G	—	y-Missile minus y-target (in launch coordinates)
z_G	—	z-Missile minus z-target (in launch coordinates)
VT	VTI	Target inertial velocity
—	XTA	{ Interpolated target accelerations in earth fixed coordinate system
—	YTA	
—	ZTA	
\bar{C}_L	—	Longitudinal center line of target
C_{Lx}	G1	{ Components of \bar{C}_L in earth fixed coordinates
C_{Ly}	G2	
C_{Lz}	G3	
\bar{L}_{os}	—	Line of sight vector

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
L_x	F1	{ Components of \bar{L}_{os} in earth fixed coordinates
L_y	F2	
L_z	F3	
x_{ML}	_____	x-Missile position in launch coordinates
y_{ML}	_____	y-Missile position in launch coordinates
z_{ML}	_____	z-Missile position in launch coordinates
x_{TL}	_____	x-target position in launch coordinates
y_{TL}	_____	y-target position in launch coordinates
z_{TL}	_____	z-target position in launch coordinates
x_{TE}	_____	x-position of target in inertial coordinates
y_{TE}	_____	y-position of target in inertial coordinates
z_{TE}	_____	z-position of target in inertial coordinates

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
_____	XDTGO	Initial values of XDTGMS, YDTGMS, ZDTGMS
_____	YDTGO	
_____	ZDTGO	
H_{c7}	_____	Commanded irradiance for plume
f	19.5	Focal length of projection lens (CM)
$H \left \begin{array}{l} R=7000 \\ \epsilon \end{array} \right.$	HR7E	Irradiance at 7000 meters (W/CM ²)
P_1	PLIRSS	Vertex angle of plume transparency (DEG)
P_2	P2IRSS	Length of plume transparency (IN.)
A_{t7}	AT7	Area of plume transparency (IN ²)
J_{tu7}	PJTU1	Available radiant intensity of target as function of plume transparency area taken from calibration in IRSS (W/STER)
$T_{f,plume}$	0.3	Neutral density transmission factor for plume

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
W_T	WT	Weight of target
S_T	ST	Reference surface area of target
\bar{C}	_____	Horizon reference vector
Q_M	QM	Mach number of target
a_s	AAA	Speed of sound
V_2	_____	Speed of flare
R_F	_____	Range to go between missile and flare
H_{i2}, H_{c2}	_____	Irradiance of flare W/CM ² (Note, letter c denotes calibration)
\dot{x}_{FL}	_____	Velocity of flare in launch coordinates (FT/SEC)
\dot{y}_{FL}	_____	
\dot{z}_{FL}	_____	
σ_{Y4}	_____	Approximate ψ_4 (RAD)
σ_{Z4}	_____	Approximate θ_4 (RAD)
σ_{Y2}	σ_{YT}	Approximate ψ_2 (RAD)

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
σ_{Z2}	σ_{ZT}	Approximate θ_2 (RAD)
_____	J_{tu2}	Available radiant intensity of flare
_____	T_{FD}	Time of flare drop (SEG)
$ L_{os} $	R	Norm of line of sight (FT)
t_{FD}	t_{FD}, t_{fd}	Time associated with flare drop
δ	_____	Missile wing deflection
ψ_2	ψ_{F2}	Flare azimuth (DEG)
ψ_4	ψ_{T4}	Tail pipe azimuth (DEG)
ψ_7	ψ_{T7}	Plume azimuth (DEG)
ψ_{24}	ψ_{T2REL}	
θ_2	θ_{T2}	Flare elevation (DEG)
θ_4		Tail pipe elevation (DEG)
θ_7	θ_{T7}	Plume elevation (DEG)
θ_{24}		
$\dot{\psi}_2$	$\dot{\psi}_{F2}$	Flare azimuth rate (DEG/SEC)
$\dot{\psi}_4$	$\dot{\psi}_{T4}$	Tail pipe azimuth rate (DEG/SEC)

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
$\dot{\psi}_7$	$\dot{\psi}_{T7}$	Plume azimuth rate (DEG/SEC)
$\dot{\psi}_{24}$	$\dot{\psi}_{T2REL}$	
$\dot{\theta}_2$	$\dot{\theta}_{T2}$	Flare elevation rate (DEG/SEC)
$\dot{\theta}_4$	$\dot{\theta}_{T4}$	Tail pipe elevation rate (DEG/SEC)
$\dot{\theta}_7$	$\dot{\theta}_{T7}$	Plume elevation rate (DEG/SEC)
$\dot{\theta}_{24}$	$\dot{\theta}_{T2REL}$	
t_2	_____	Transparency radius for flare
t_4	_____	Transparency radius for tailpipe
		} used to command true size
P	θ	GUM pitch angle (DEG)
Y	ψ	GUM yaw angle (DEG)
R	ϕ	GUM roll angle (DEG)
r'	_____	GUM Yaw rate (DEG/SEC)
q'	_____	GUM pitch rate (DEG/SEC)
p'	_____	GUM roll rate (DEG/SEC)

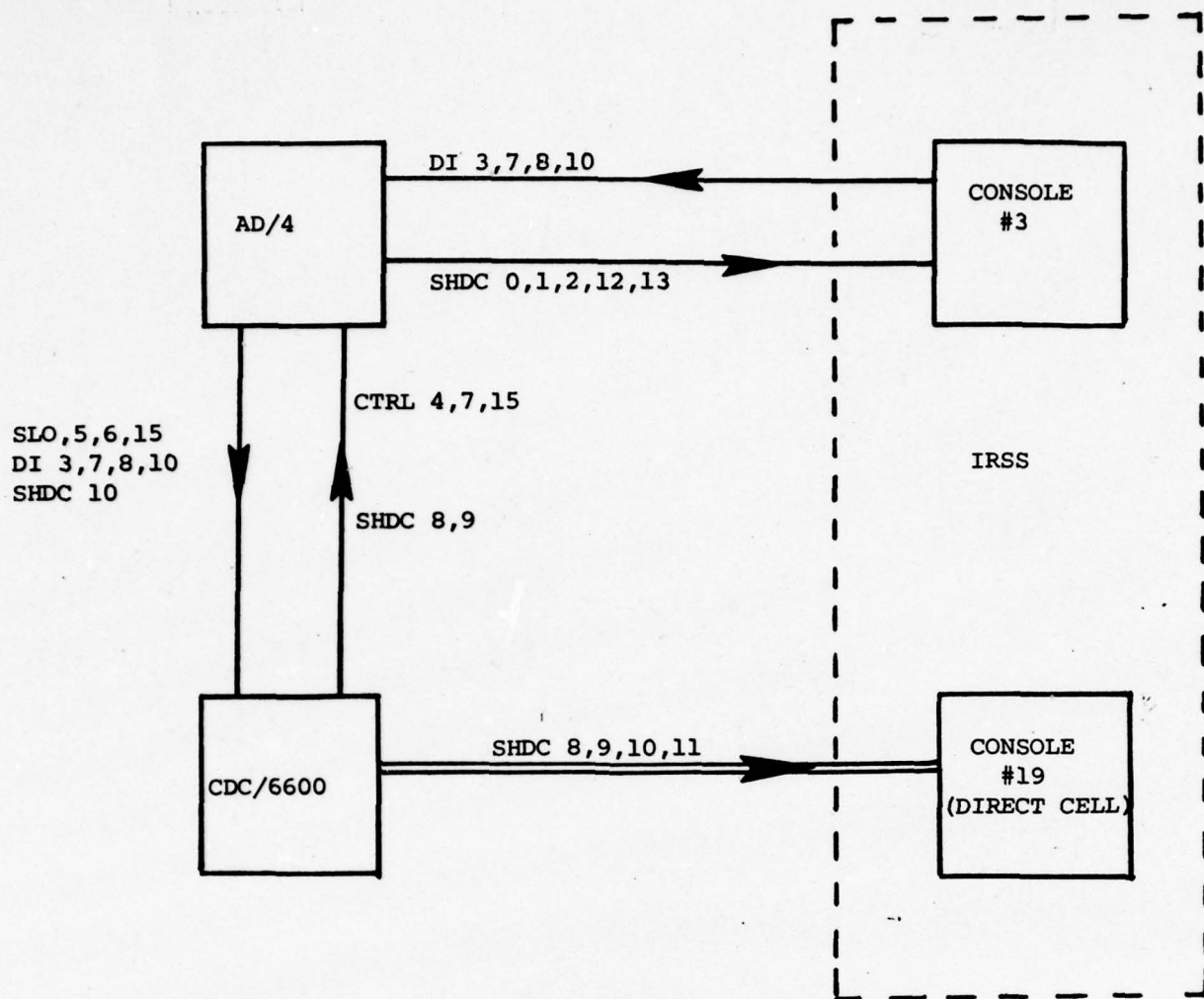
VARIABLE	PROGRAM SYMBOL	DESCRIPTION
_____	NPATH	Flag to control entrance into computation loop of real-time code.
_____	LOOP1	Loop counter for real-time interrupts prior to sense line 6 coming high
_____	LOOP2	Loop counter for real-time interrupts after sense line 6 comes high
_____	INFLRT	Flag to signal entrance into real time, INFLRT = -1 indicates batch and INFLRT = +1 indicates entrance into real-time
_____	LTF	Clock time at beginning of real-time loop. This value is used later to compute specific loop time for each loop
_____	NSEG	Segment number of real-time code which is to be entered.
_____	IT1	
_____	INDEX	Index for storing real-time data for post real-time analysis
_____	LEVEL	Status of maneuver -7 → not in real-time 0 → in real-time +7 → target trajectory table exceeded
_____	IT1, IT2	Index used in interpolation of target trajectory time
_____	NT	Length for target trajectory tables

VARIABLE	PROGRAM SYMBOL	DESCRIPTION
_____	DXG	Dummy storage location for current value of DX, DY, DZ, XDOT, YDOT and ZDOT respectively. These variables are returned to the main program for diagnostic purposes
_____	DYG	
_____	DZG	
_____	XDO	
_____	YDO	
_____	ZDO	
L	PL	Actual plume length (FT)
B	PB	Actual plume breadth at base (FT)
ℓ	PLA	Apparent plume length
_____	t	MAN(1,I)
_____	\dot{x}_{TL}	MAN(2,I)
_____	\dot{y}_{TL}	MAN(3,I)
_____	\dot{z}_{TL}	MAN(4,I) Target time and velocity at each range table data collection point

V. REAL-TIME I/O

V. REAL-TIME I/O

This Section contains a description of real-time input output requirements of the MICOM Hybrid STINGER Simulation. The tables and figures included in this section describe the flow of analog and discrete information between an AD/4 analog computer, a CDC/6600 digital computer and the IRSS.



NOTE: The CTRL and SL word are also used to transmit SHDCS and DIs, the specific usage is:

- | | |
|---------------------|-----------------|
| o SHDC 8 = CTRL 8 | o DI 3 = SL 3 |
| o SHDC 9 = CTRL 9 | o DI 7 = SL 7 |
| o SHDC 10 = SL 11 | o DI 8 = SL 8 |
| o SHDC 11 = CTRL 11 | o DI 10 = SL 10 |

FIGURE 5.1
DISCRETE CIRCULATION

V60	V61	V60	V61	V62	V63	V62	V63
00	10	20	30	40	50	60	70
01	11	21	31	41	51	61	71
02	12	22	32	42	52	62	72
03	13	23	33	43	53	63	73
04	14	24	34	44	54	64	74
05	15	25	35	45	55	65	75
06	16	26	36	46	56	66	76
07	17	27	37	47	57	67	77

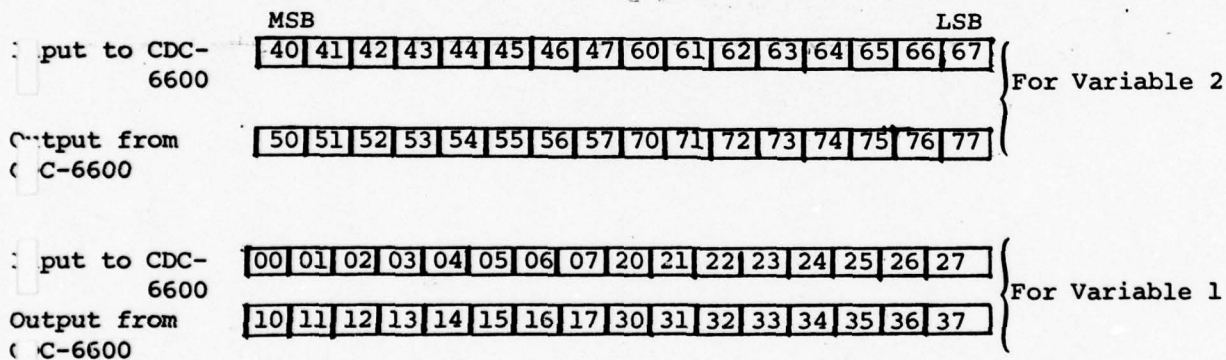


FIGURE 5.2

AD/4 DISCRETE TRUNK LINE CONNECTIONS

TABLE 5.1
DISCRETE SIGNALS FROM AD/4 TO CDC/6600

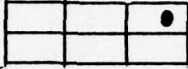
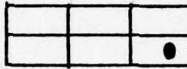
AD/4 PATCH	CDC/6600 BIT	DESCRIPTION	ORIGIN	ULTIMATE DESTINA- TION
TR4	SL11	NORMAL TERMINATION (SHDC10), SIGNALS RAMP DOWN COMPLETE	AD/4	IRSS/19
TR27	SL0	LOOP TO BATCH, RETRANSMITTS ICs WHEN SET LOW	AD/4	6600
TR22	SL5	STATIC TEST OK, SIGNALS AD/4 READY TO RECEIVE IC 	AD/4	6600
TR21	SL6	RAMP UP READY, SET HIGH BY OPERATE SWITCH IN MICOM HYBRID,  THIS STARTS REAL TIME LOOPING	AD/4	6600
TR00	SL15	6600 ABNORMAL ABORT, USED TO EXIT REAL TIME LOOPING	AD/4	6600
TR24	SL3	IRSS READY (DI3)	IRSS	6600
TR20	SL7	END OF PROBLEM (DI7)	IRSS	AD/4 6600
TR7	SL8	EMERGENCY SHUTDOWN (DI8)	IRSS	AD/4 6600
TR5	SL10	INITIAL FIELD REQUEST (DI10)	IRSS	6600

TABLE 5.2 DISCRETE SIGNALS FROM AD/4 TO IRSS


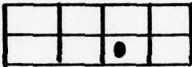
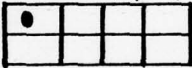
AD/4 PATCH	IRSS BIT	DESCRIPTION	ORIGIN	ULTIMATE DESTINA- TION
T46	SHDC0	<u>SHUTTER #2 COMMAND</u>	AD/4	IRSS/3
T61	SHDC1	<u>SHUTTER #4 COMMAND</u>	AD/4	IRSS/3
T63	SHDC2	<u>SHUTTER #7 COMMAND</u>	AD/4	IRSS/3
-----	SHDC8	<u>SIMULATION RUNNING</u> , (THIS PATH NOT USED SEE CTRL8)	-----	-----
-----	SHDC9	<u>FIELD TRANSMITTED</u> , (THIS PATH NOT USED SEE CTRL9)	-----	-----
-----	SHDC10	<u>NORMAL TERMINATION</u> , (THIS PATH NOT USED SEE SL11)	-----	-----
T43	SHDC12	<u>TARGET AQUIRED</u>	AD/4	IRSS/3
T40	SHDC13	<u>DISCRETE #5</u> , SWITCH SEEKER FROM EXTERNAL TO INTERNAL POWER	AD/4	IRSS/3

NOTE: IRSS/3 IS IRSS CONSOLE 3 AND IRSS/19 IS IRSS CONSOLE 19, THE DIRECT
CELL DATA LINK

TABLE 5.3 DISCRETE SIGNALS FROM IRSS TO AD/4

AD/4 PATCH	IRSS BIT	DESCRIPTION	ORIGIN	ULTIMATE DESTINA- TION
T72	DI3	IRSS READY, NOT SENT UNTIL TARGET ACQUIRED SIGNAL IS RECEIVED	IRSS	6600
T56	DI7	END OF PROBLEM, SIGNALS EQUIPMENT SHUT DOWN IN IRSS	IRSS	AD/4 6600
T55	DI8	EMERGENCY SHUT DOWN, SIGNALS EXCESSIVE ACCELERATION IN GUM	IRSS	AD/4 6600
T53	DI10	INITIAL FIELD REQUEST	IRSS	6600

TABLE 5.4 DISCRETE SIGNALS FROM CDC/6600 TO AD/4 OR IRSS

AD/4 PATCH	CDC/6600 BIT	DESCRIPTION	ORIGIN	ULTIMATE DESTINA- TION
TR33	CTRL4	<u>ICs SENT</u> , 	6600	AD/4
TR30	CTRL7	<u>INTECEPT DETECTED</u> , SET HIGH BY INTERCEPT OR MISS CONDITION 	6600	AD/4
TR10	CTRL15	<u>REAL TIME LOOPING</u> , SIGNALS CDC/6600 WAIT- ING FOR SL6 HIGH 	6600	AD/4
TR16	CTRL9	<u>FIELD TRANSMITTED</u> (SHDC9) SIGNAL TO GEPAC THAT FIRST FRAME OF DATA IS AVAILABLE. THIS OCCURS AFTER THE 6600 HAS RECEIVED INITIAL FIELD REQUEST, DI10	6600	IRSS/19 AD/4
TR17	CTRL8	<u>SIMULATION RUNNING</u> (SHDC8) TURNS ON INDI- CATOR LIGHTS ONLY. SENT WITH SHDC11	6600	IRSS/19 AD/4
-----	CTRL11	START SIMULATION (SHDC11) IN CLOSED-LOOP GEPAC RESPONDS BY SENDING FIRST CLOCK PULSE. SENT WITH SHDC8	6600	IRSS/19

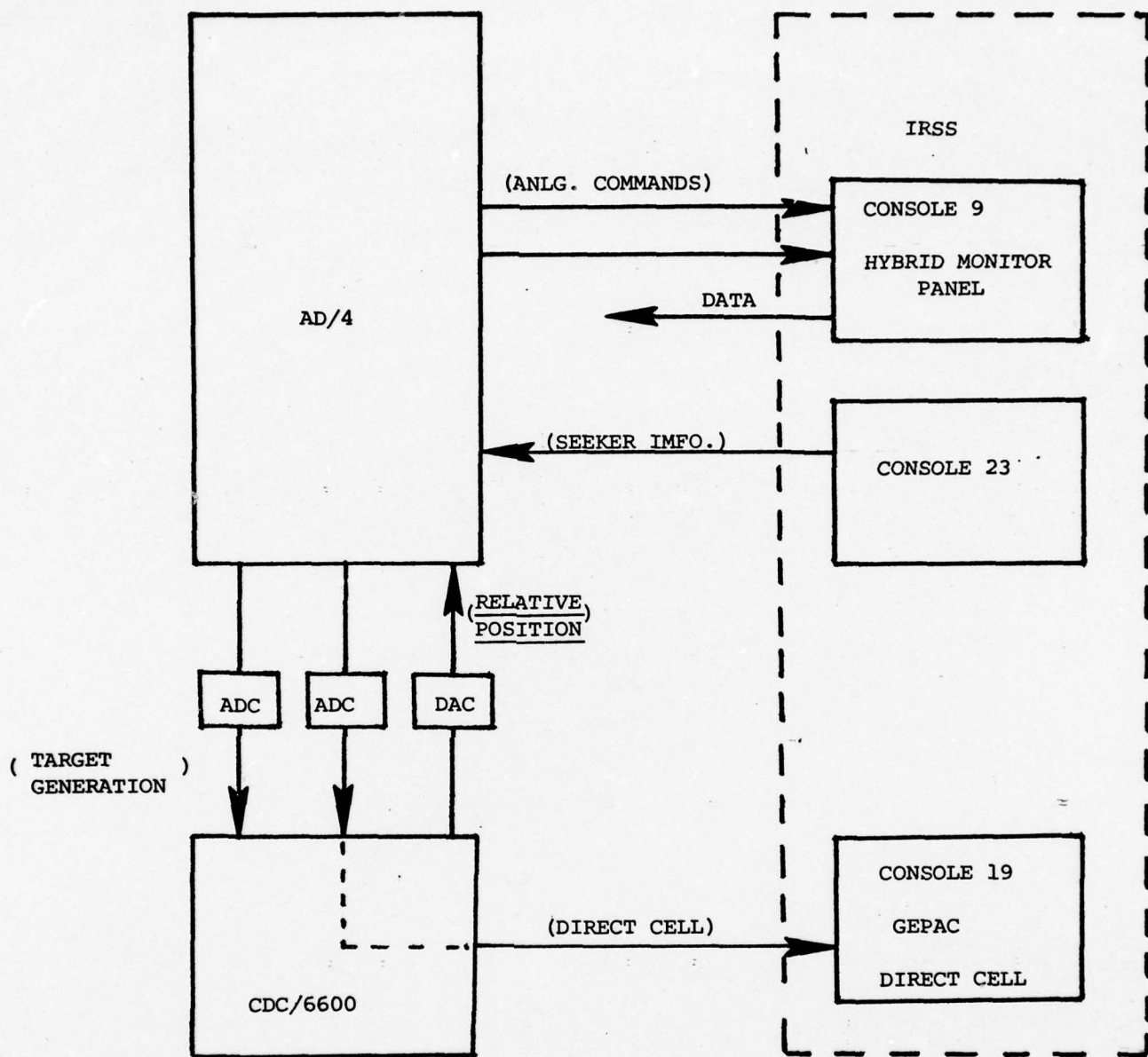


FIGURE 5.3 ANALOG SIGNAL CIRCULATION

SEEKER DATA TO AD/4

NO. 231 R

10	30	TAB	50	70	
11	31	SYNC FILT	51	71	
12	32	ACQ.	52	72	
13	33		53	73	
14	34		54	74	
15	35	δ_{WL}	55	75	
16	36	GUID COMD.	56	76	
17	37	TAG	57	77	

AD/4 COMMANDS TO IRSS/9

DACS TO 6600

10	30	θ_2	50	70	$\dot{x}_{ML} - \dot{x}_{TL}$
11	31	ψ_2	51	71	$\dot{y}_{ML} - \dot{y}_{TL}$
12	32	θ_4	52	72	$\dot{z}_{ML} - \dot{z}_{TL}$
13	33	ψ_4	53	73	$\dot{x}_{ML} - \dot{x}_{TL}$
14	34		54	74	$\dot{y}_{ML} - \dot{y}_{TL}$
15	35	θ_7	55	75	$\dot{z}_{ML} - \dot{z}_{TL}$
16	36		56	76	$\dot{x}_{ML} - \dot{x}_{TL}$
17	37	ψ_7	57	77	$\dot{y}_{ML} - \dot{y}_{TL}$

0	1
2	3

ADCS TO GEPAC

ADCS TO 6600

10	30	t_2	50	\dot{x}_{TL}	70	y/t_2
11	31	t_4	51	\dot{y}_{TL}	71	θ_L
12	32	P_2	52	\dot{z}_{TL}	72	i_7
13	33	R	53	λ/B	73	
14	34	P_1	54	$\cos(\epsilon)$	74	
15	35	t_2	55	T_{RP}	75	
16	36	t_4	56	R_1	76	
17	37	t_7	57	t_2	77	

TO 231 R

AD/4 COMMANDS TO IRSS/9

10	30		50	70	
11	31		51	71	
12	32		52	72	
13	33		53	73	
14	34		54	74	
15	35		55	75	
16	36		56	76	
17	37		57	77	

FIGURE 1.4 AD/4 TRACKER VARIANTS

TABLE 5.5 AD/4 - CDC/6600 ADC ASSIGNMENT (V13 →)

ANALOG VARIABLE NAME	AD/4 ANLG. VOLTAGE -100<V<+100	DIGITAL FRACTION -1<N<+1	RELATIVE ADC ASSIGN.	AD/4 TRUNK LINE ASSIGNMENT
DX	$\frac{K(X_{ML} - X_{TL})}{20}$	$\frac{K(X_{ML} - X_{TL})}{(20)(100)}$	2	151
DY	$\frac{K(Y_{ML} - Y_{TL})}{20}$	$\frac{K(Y_{ML} - Y_{TL})}{(20)(100)}$	3	152
DZ	$\frac{K(Z_{ML} - Z_{TL})}{20}$	$\frac{K(Z_{ML} - Z_{TL})}{(20)(100)}$	4	153
DT	10t	$\frac{10t}{(100)}$	5	154
XDOT	$\frac{\dot{X}_{ML} - \dot{X}_{TL}}{200}$	$\frac{\dot{X}_{ML} - \dot{X}_{TL}}{(200)(100)}$	6	155
YDOT	$\frac{\dot{Y}_{ML} - \dot{Y}_{TL}}{200}$	$\frac{\dot{Y}_{ML} - \dot{Y}_{TL}}{(200)(100)}$	7	156
ZDOT	$\frac{\dot{Z}_{ML} - \dot{Z}_{TL}}{200}$	$\frac{\dot{Z}_{ML} - \dot{Z}_{TL}}{(200)(100)}$	8	157

(ADC ASSIGNMENT CONTINUED)

ANALOG VARIABLE NAME	AD/4 ANLG. VOLTAGE -100<V<+100	DIGITAL FRACTION -1<N<+1	RELATIVE ADC ASSIGNMENT	AD/4 TRUNK LINE ASSIGNMENT
XXX	$\frac{K(X_{ML} - X_{TL})}{200}$	$\frac{K(X_{ML} - X_{TL})}{(200)(100)}$	9	170
YYY	$\frac{K(Y_{ML} - Y_{TL})}{200}$	$\frac{K(Y_{ML} - Y_{TL})}{(200)(100)}$	10	171
ZZZ	$\frac{K(Z_{ML} - Z_{TL})}{200}$	$\frac{K(Z_{ML} - Z_{TL})}{(200)(100)}$	12	173

TABLE 5.6 AD/4 - CDC/6600 DAC ASSIGNMENT (V15 →)

DIGITAL VARIABLE NAME	DIGITAL FRACTION -1 < N < +1	AD/4 ANLG. VOLTAGE -10 < V < +10	RELATIVE DAC ASSIGNMENT	AD/4 TRUNK LINE ASSIGNMENT
XDTGO, XCOMP	$\frac{\dot{x}_{TL}}{(200)(10)}$	$\frac{\dot{x}_{TL}}{200}$	1	250
YDTGO, YCOMP	$\frac{\dot{y}_{TL}}{(200)(10)}$	$\frac{\dot{y}_{TL}}{200}$	2	251
ZDTGO, ZCOMP	$\frac{\dot{z}_{TL}}{(200)(10)}$	$\frac{\dot{z}_{TL}}{200}$	3	252
RLB	$\frac{(\ell/B)}{(10)}$	ℓ/B	4	253
COSE	$\frac{10 \cos(\epsilon)}{10}$	$10 \cos(\epsilon)$	5	254
SPO	$\frac{T_{RP}}{10}$	T_{RP}	6	255
RI	$\frac{R_i}{(2000)(10)}$	$\frac{R_i}{2000}$	7	256

(DAC ASSIGNMENT CONTINUED)

DIGITAL VARIABLE NAME	DIGITAL FRACTION -1 N +1	AD/4 ANLG. VOLTAGE -10 V +10	DAC ASSIGNMENT	AD/4 TRUNK LINE ASSIGNMENT
GAM	$\frac{t'}{10}$	t'	8	257
EDOT	$\frac{(y/t')}{(.6)(10)}$	$\frac{5(y/t')}{3}$	9	270
THETAL	$\frac{\theta_L}{(10)(10)}$	$\frac{\theta_L}{10}$	10	271
RN	$\frac{10.741 i_7}{10}$	$10.741 i_7$	12	273
RN*	$\frac{R_n}{10}$	R_n	12	273

* FOR MICOM HYBRID APPLICATIONS

TABLE 5.7 COMMANDS TO IRSS/9
U01+W9X28A

ANALOG VARIABLE NAME	AD/4 ANALOG VOLTAGE	RELATIVE TRUNK ASSIGNMENTS	AD/4 TRUNK LINE ASSIGNMENTS
θ_7	$-.875 \theta_7$	14	235
ψ_7	$-.875 \psi_7$	7	216
θ_2	$-.875 \theta_2$	9	230
ψ_4	$+.875 \psi_4$	4	213
θ_4	$-.875 \theta_4$	11	232
ψ_2	$-.875 \psi_2$	2	211

TABLE 5.8 COMMANDS TO IRSS/9

V17 - U02+W9X28A

ANALOG VARIABLE NAME	AD/4 ANALOG VOLTAGE	RELATIVE TRUNK ASSIGNMENTS	AD/4 TRUNK LINE ASSIGNMENTS
r' (YAW RATE)	1.0 r'	5	354
q' (PITCH RATE)	1.0 q'	6	355
p' (ROLL RATE)	$13.8 \times 10^{-3} p'$	7	356
T_{RP}	.5555 T_{RP}	2	351

TABLE 5.9 IRSS/23 TO AD/4 (seeker outputs)
V14-400-W23X28C

ANALOG VARIABLE NAME	AD/4 ANALOG VOLTAGE	RELATIVE TRUNK ASSIGNMENT	AD/4 TRUNK LINE ASSIGNMENT
δ_{wi}	.5435 δ_{wi}	6	015
Guid. Comd.	-----	7	016
TAG	-----	8	017
TAB	-----	9	030
Sync Filt	-----	10	031
Acquisition	-----	11	032

TABLE 5.10 AD/4 TO CDC/6600
(sent to IRSS via direct cell)

V12+

ANALOG VARIABLE NAME	AD/4 ANALOG VOLTAGE	RELATIVE ADC ASSIGNMENT	AD/4 TRUNK LINE ASSIGNMENT
t_2	$9.53 \times 10^3 t_2$	1	110
t_4	$9.534 \times 10^3 t_4$	2	111
P_2	$9.896 \times 10^2 P_2$	3	112
R	.5555 R	4	113
P_1	1.7255 P_1	5	114
i_2	10.742 i_2	6	115
i_4	10.742 i_4	7	116
i_7	10.741 i_7	8	117
ψ_2	1.1111 ψ_2	9	130
θ_2	3.333 θ_2	10	131
ψ_4	1.111 ψ_4	11	132
θ_4	3.333 θ_4	12	133
ψ_7	1.111 ψ_7	13	134
θ_7	3.333 θ_7	14	135
P	1.25 P	15	136
Y	1.111 Y	16	137

VI. SUBROUTINE KSCALE

VI. SUBROUTINE KSCALE

This subroutine estimates t' , the time at 1000 feet-to-go for target missile intercept and computes the overload function for real-time variable scale factors. The estimates are based on a simplified model involving a constant bearing course and a nominal missile/target trajectory.

In addition, the program computes γ_{\min} - the minimal of the overload function, $t_{\gamma \min}$ - the time at which γ_{\min} occurs and the smallest bit ADC resolution for relative missile positions.

EQUATIONS:

$$\bullet \quad \theta_2 = \tan^{-1} \left(\frac{t' y_{TL}(0)^2 + z_{TL}(0)^2}{R_i - 1000 + t' x_{TL}(0)} \right)$$

$$\bullet \quad R_i - \Delta R \cos(\theta_2) - 1000 + t' x_{TL}(0) = 0$$

(Note, the iterative solution of this equation yields t')

$$\bullet \quad K_p = -x_{L1m}/R_i = +20,000/R_i \rightarrow K_p R_i = 20,000$$

$$\bullet \quad K_p R_i = \left(1 + \frac{\gamma_{\min} t_{\gamma \min}}{t'} \right) \left(R_i + x_{TL}(0) t_{\gamma \min} - \Delta R_{\min} \cos \theta_2 \right)$$

or

$$\gamma_{\min} = \frac{1}{t_{\gamma \min}} \left(\frac{20,000 t'}{(R_i + x_{TL}(0) t_{\gamma \min} - \Delta R_{\min} \cos \theta_2)} - t' \right)$$

$$\bullet \quad \frac{d\gamma_{\min}}{dt_{\gamma \min}} = At_{\gamma \min}^2 + Bt_{\gamma \min} + C = 0$$

(Note, the iterative solution of this equation yields $t_{\gamma \min}$)

$$\bullet \quad A = \dot{x}_{TL}^2(0)$$

$$\bullet \quad B = 2 \dot{x}_{TL}(0) (20,000 - R + \Delta R_{\min} \cos \theta_2) - 20,000 V_m \cos(\theta_2)$$

$$\bullet \quad C = (R - \Delta R_{\min} \cos \theta_2) (20,000 - R + \Delta R_{\min} \cos \theta_2)$$

- $\gamma_{\min} = - \left(\frac{20,000}{R_i + \bar{X}_{TL}(0) t \gamma_{\min} - \Delta R \cos \theta_2} + 1 \right) \left(\frac{t'}{t \gamma_{\min}} \right)$
- $A2 = \frac{(\Delta \text{Voltage}) (\text{Analog Scale Factor for DX})}{1 + \gamma_{\min}}$

Here Δ Voltage is the analog voltage change resulting from a smallest bit change in the associated DAC.

$\Delta V = .024$	} Typical Values
Analog Scale Factor = 20	

AD-A052 676

B-K DYNAMICS INC ROCKVILLE MD
SUMMARY REPORT OF STINGER CONVERSION ACTIVITIES.(U)
JUL 76

F/G 9/2

DAAH01-75-C-0194

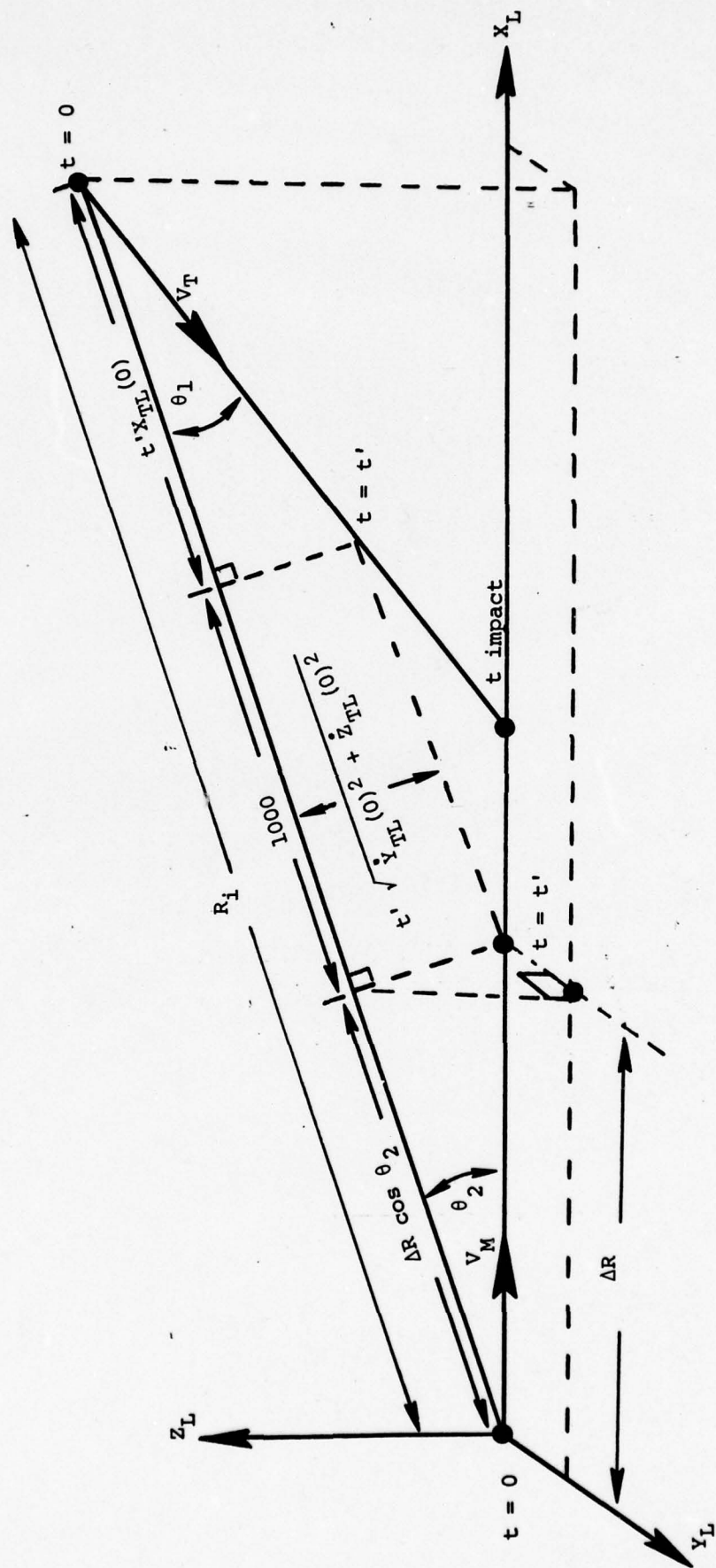
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SIMPLIFIED GEOMETRY FOR ESTIMATING TARGET-MISSILE Intercept

FIGURE 6.1

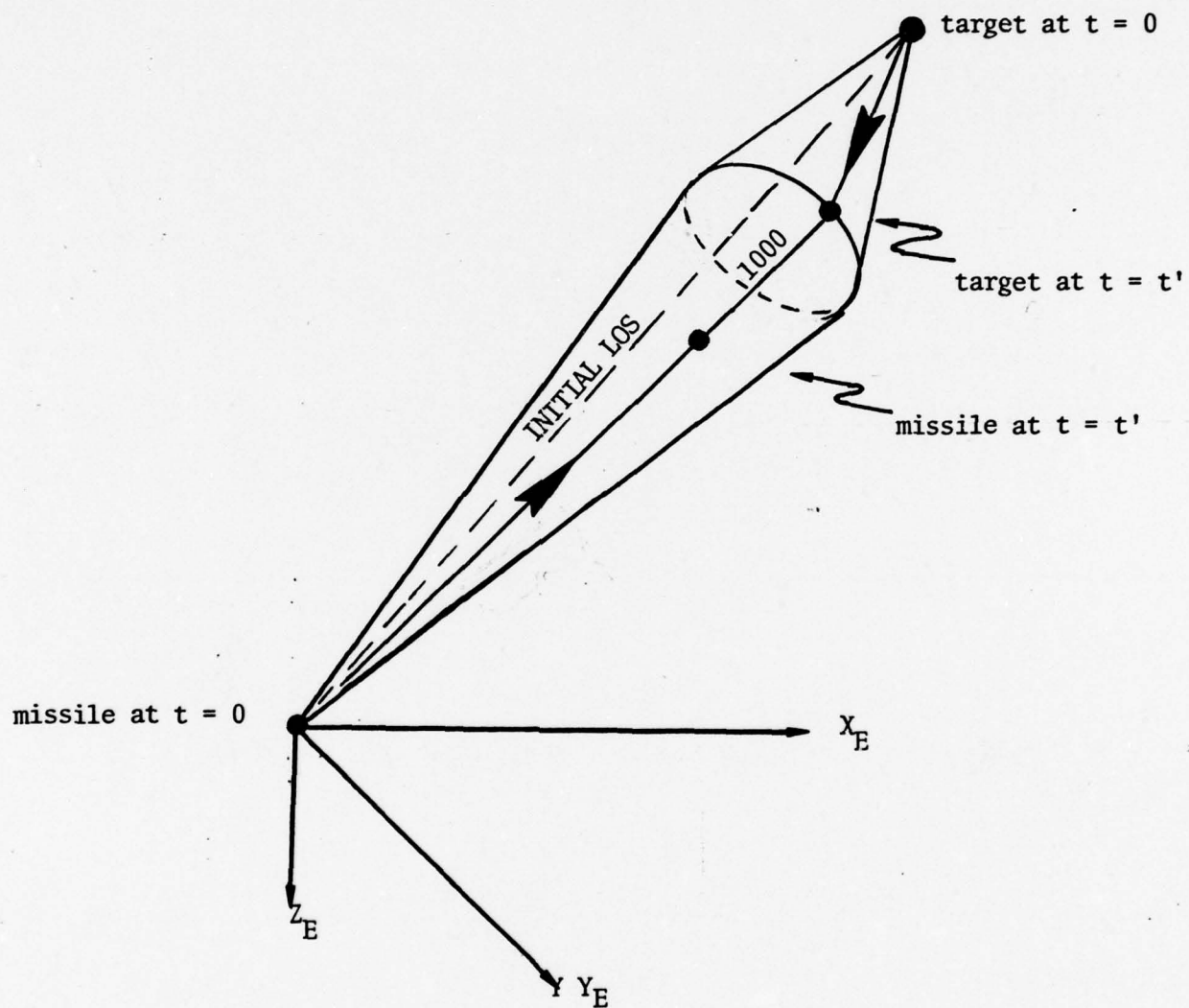


FIGURE 6.2 TYPICAL TARGET/MISSILE POSITION AT TIME $t = t_0$ and $t = t'$

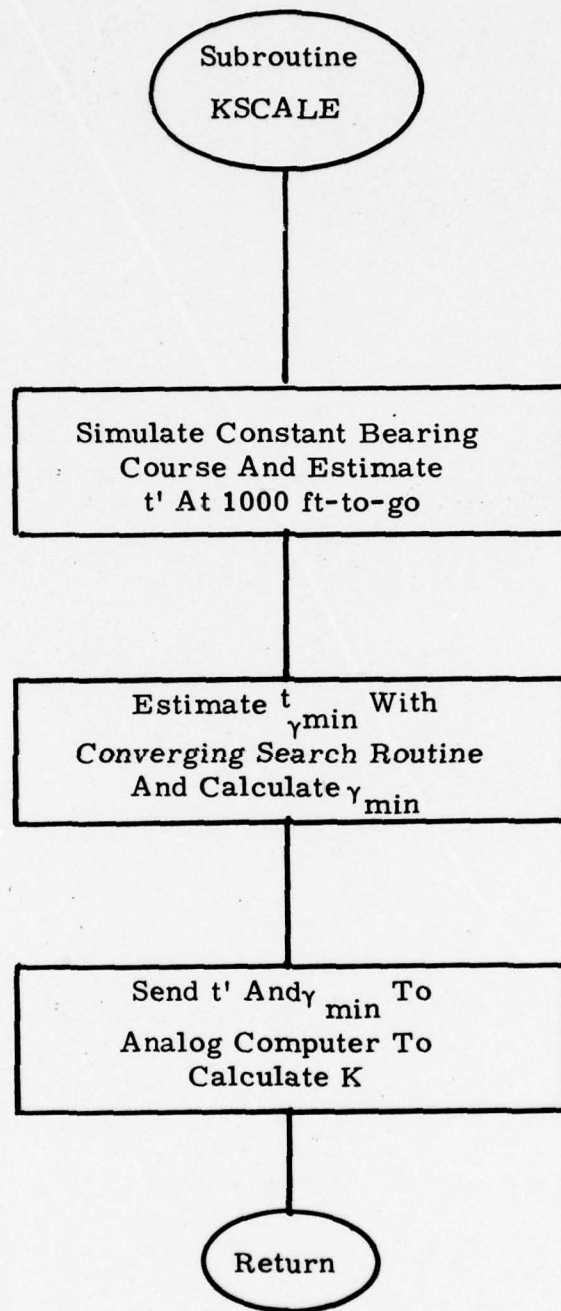


FIGURE 6.3
OVERVIEW OF SUBROUTINE KSCALE

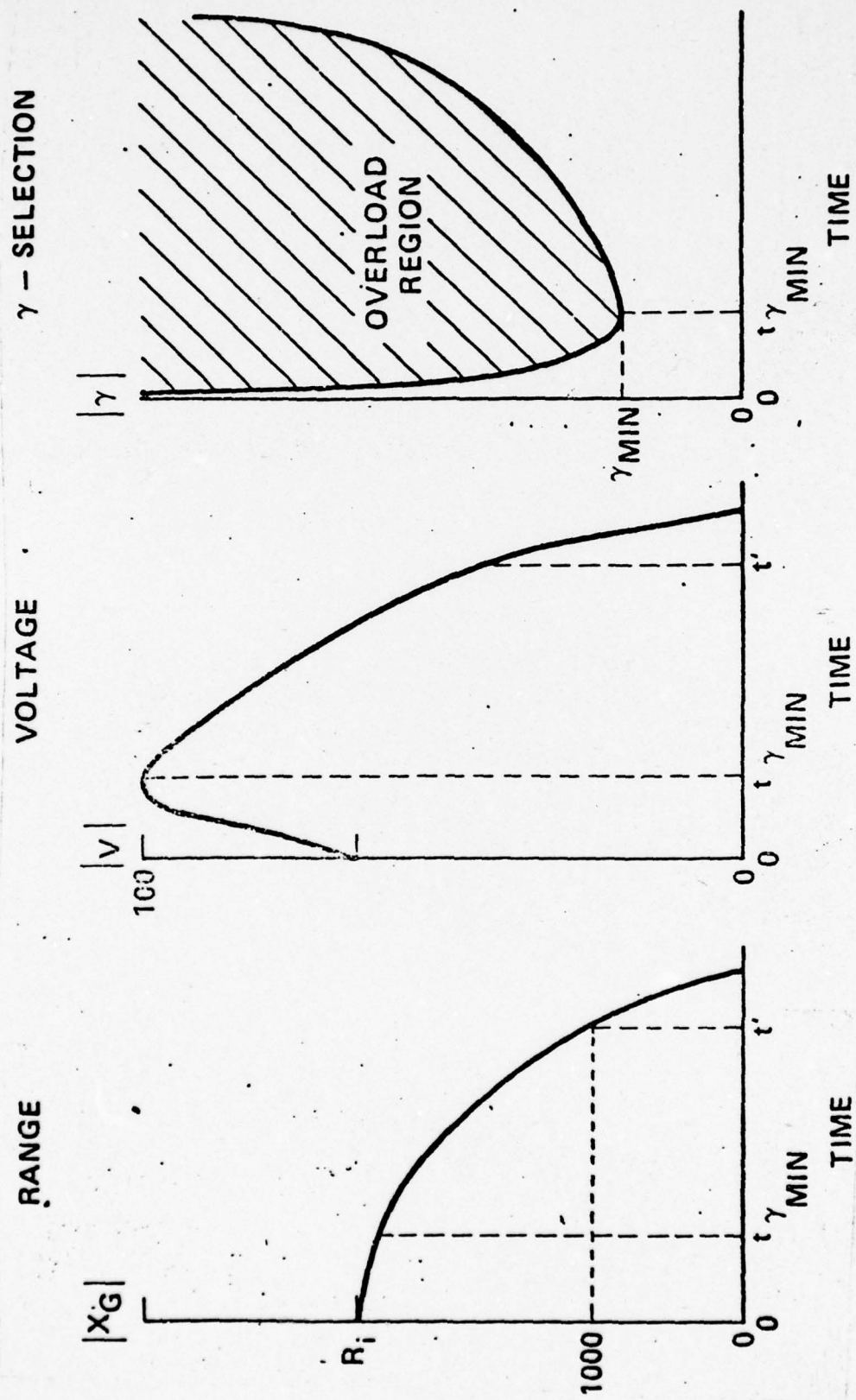
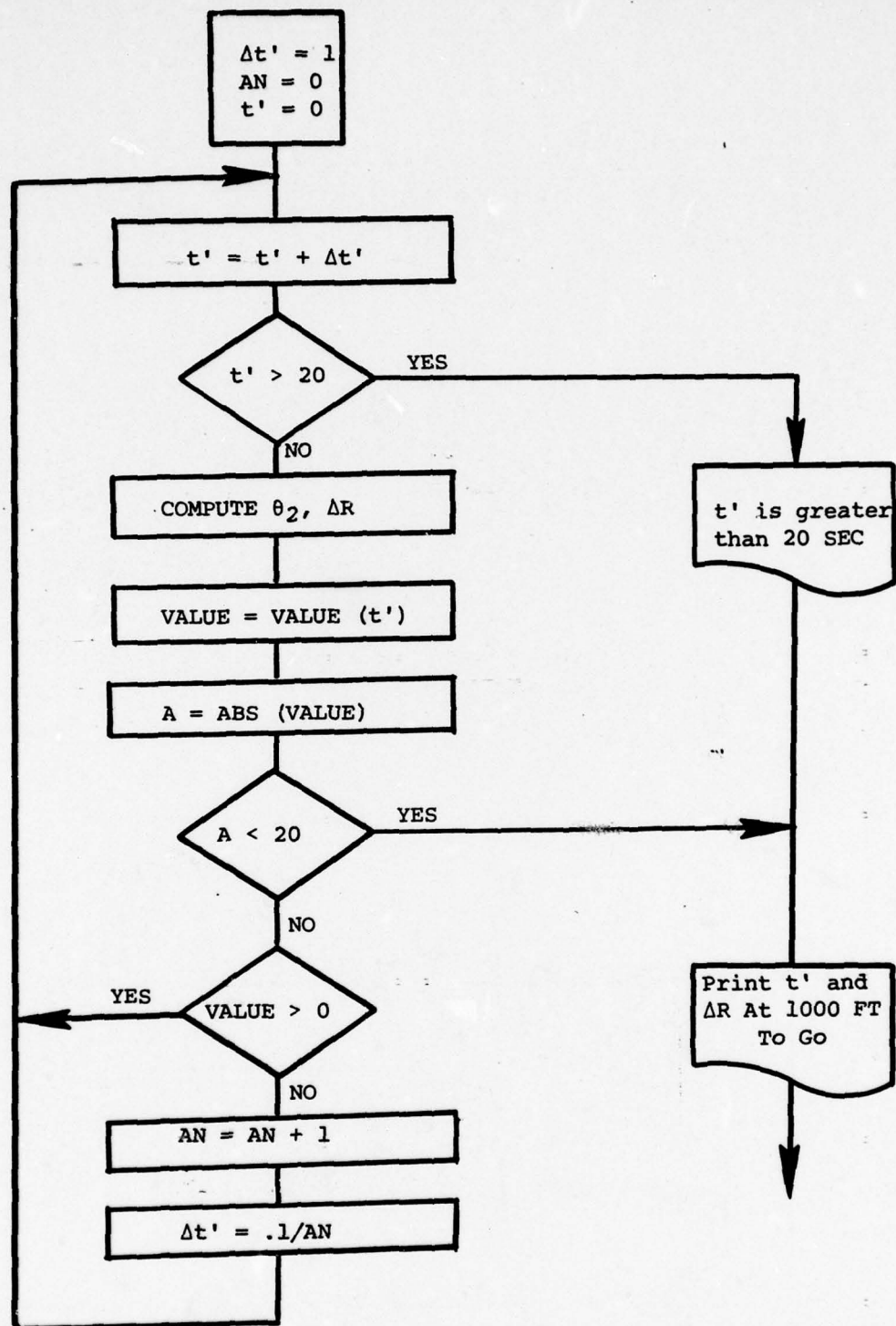


FIGURE 6.4
SELECTION CRITERIA



CONVERGING SEARCH FOR t' AT 1000 FT TO GO

FIGURE 6.5

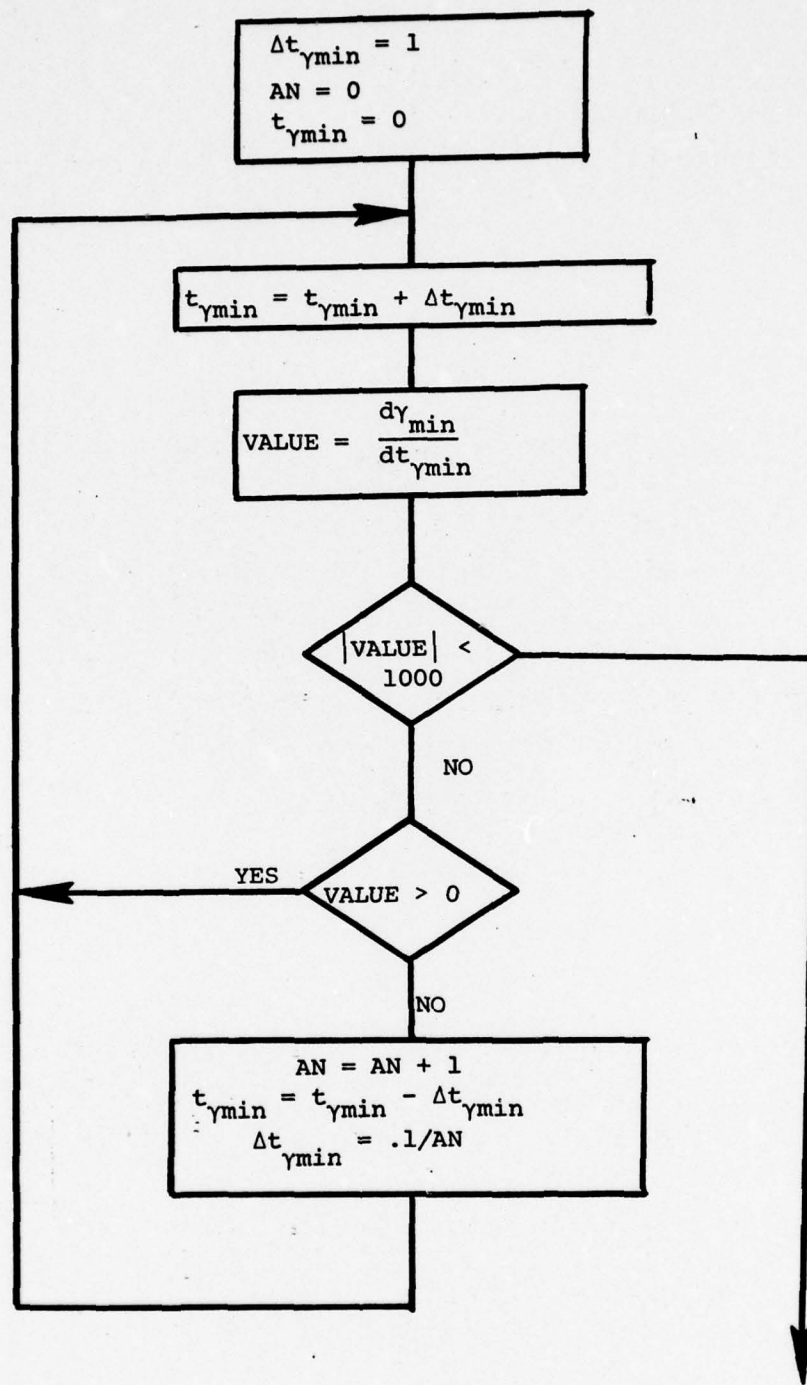
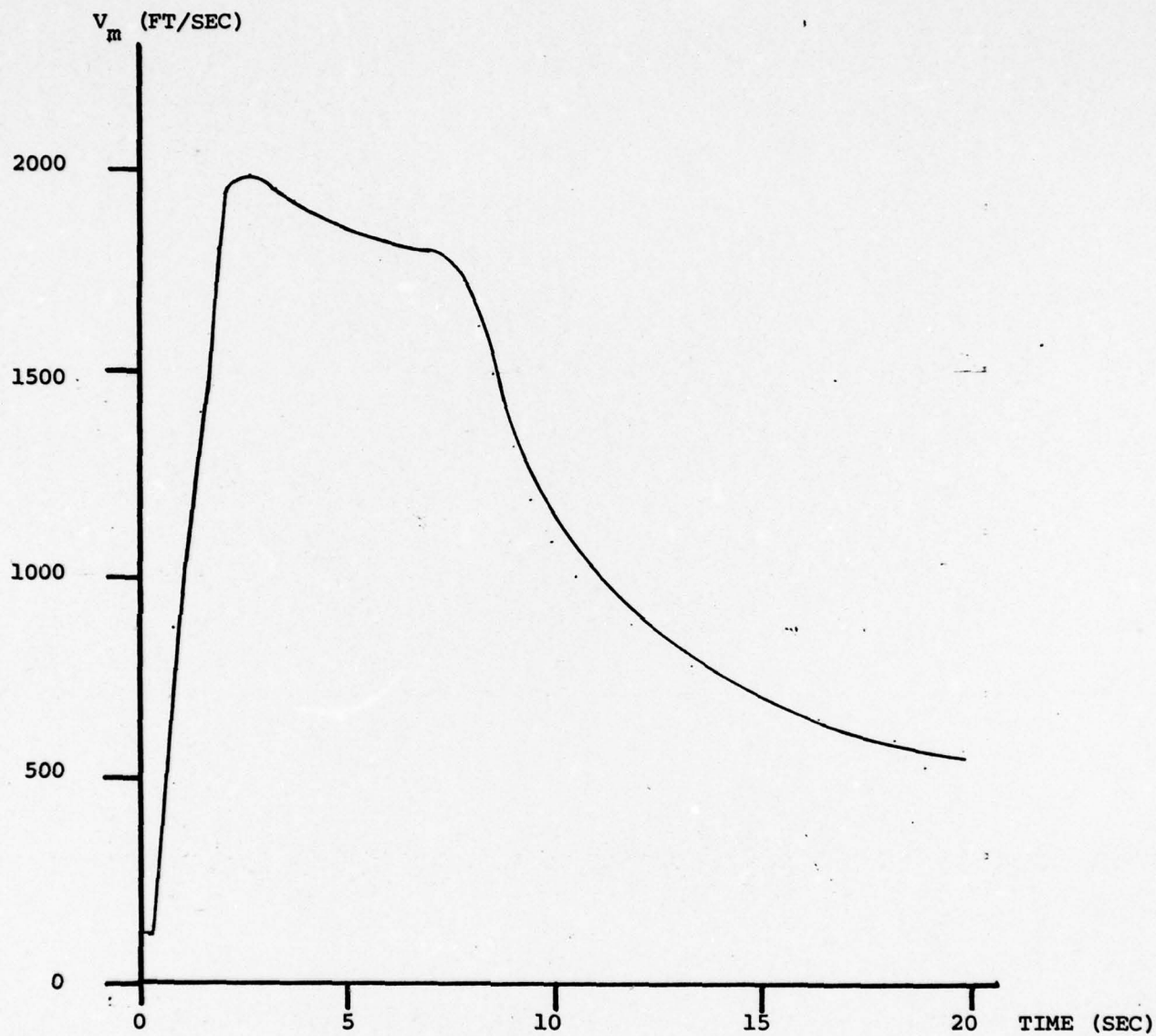


FIGURE 6.6
CONVERGING SEARCH FOR γ_{\min}



VELOCITY VS TIME FOR
NOMINAL STINGER TRAJECTORY

FIGURE 6.7

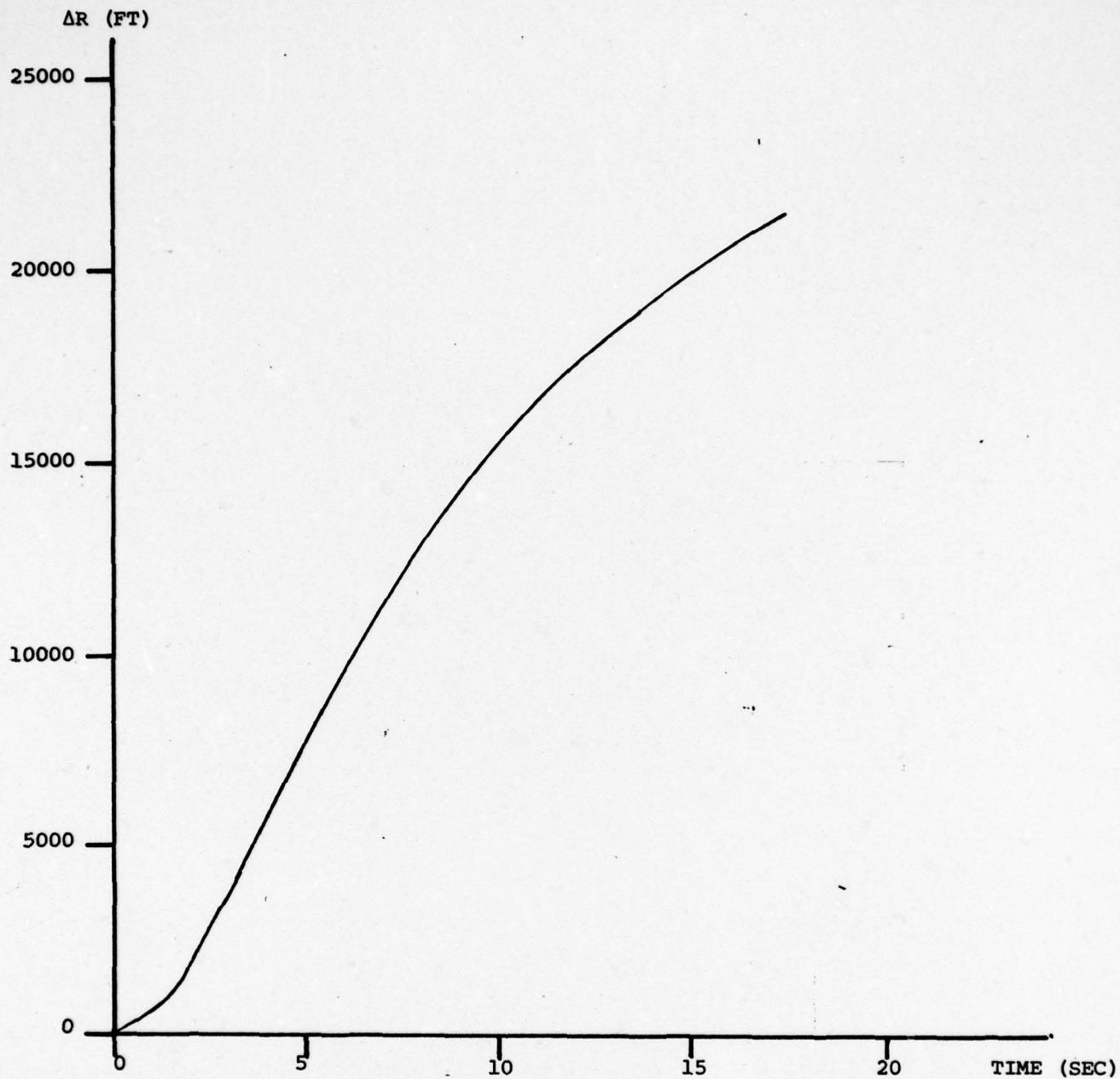


FIGURE 6.8
DISTANCE VS TIME FOR
NOMINAL STINGER TRAJECTORY

TABLE 6.1 DESCRIPTION OF SYMBOLS FOR SUBROUTINE KSCALE

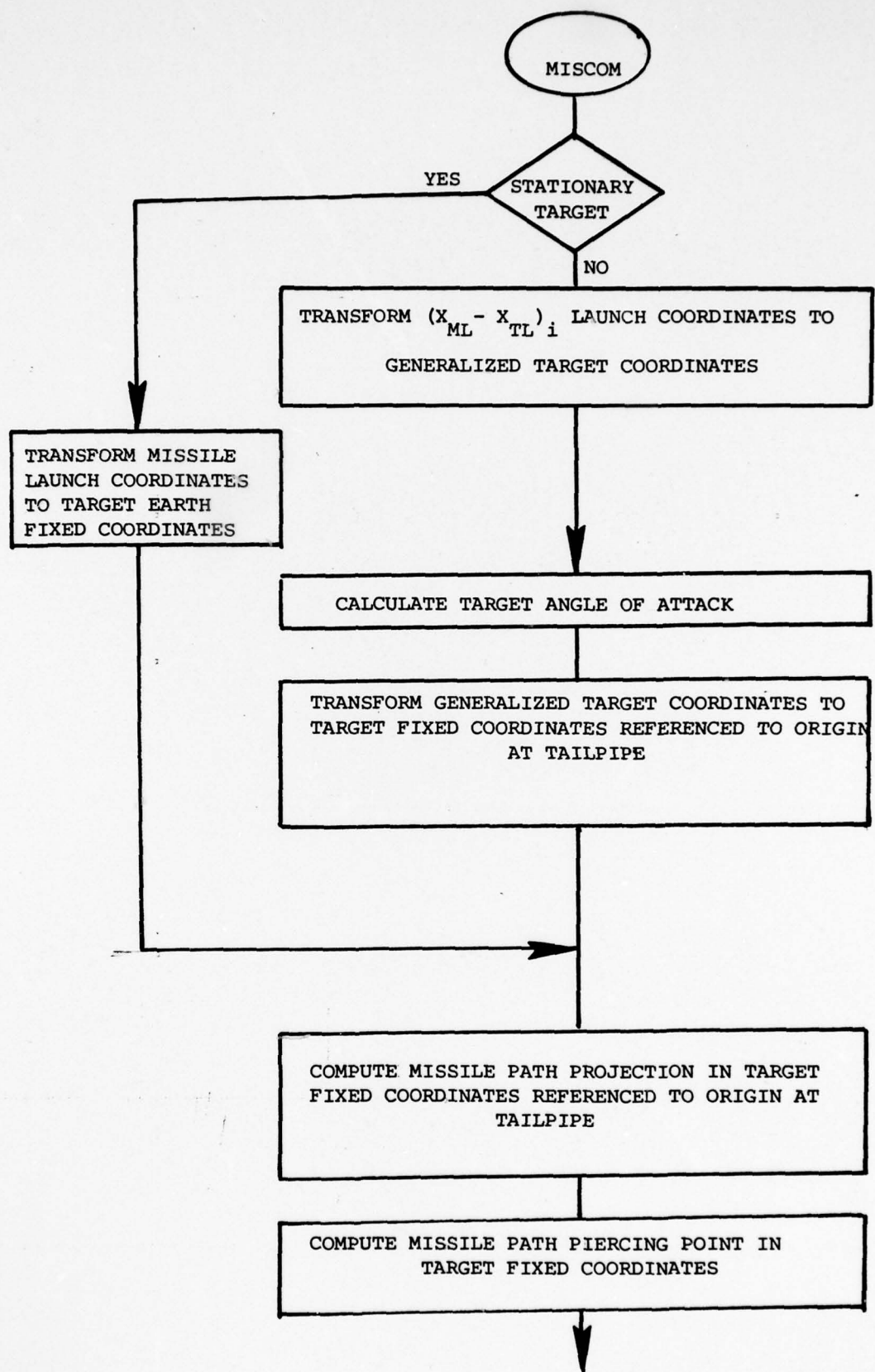
PROGRAM VARIABLE	SYMBOL	DESCRIPTION
EDOT	γ/t'	γ/t'
RI	R_i	Initial range (FT)
G	t'	Time at approximately 1000 feet to go
GG	$t_{\gamma min}$	
GGG	γ_{min}	Minima of the overload function, obtained by iterative solution
IS1		Print flag, IS1 \neq 1 indicates print is desired
THETA1	θ_1	See Figure titled Simplified Geometry for Estimating Target-Missile intercept.
THETA2	θ_2	
XDTGO	$\dot{x}_{TL}(0)$	Initial components of target velocity in launch coordinates
YDTGO	$\dot{y}_{TL}(0)$	
ZDTGO	$\dot{z}_{TL}(0)$	
DG	$\Delta t', \Delta t_{\gamma min}$	Time increment in t' search
AN	-----	Scale factor for decrementing Δt as the search is refined
DELTAR(I)	$\Delta R(t_m)$	Distance missile has flown along nominal trajectory
VM(I)	$V_m(t_m)$	Velocity of missile for a nominal trajectory
TAMA(I)	t_m	Time table for the above nominal trajectories
	k_p	Maximum analog voltage = 100v
NB	-----	Length of nominal trajectory tables TAMA, VM and DELTAR
-----	X_{L1m}	Maximum value expected for X_{ML} (used to estimate scale factors, $X_{L1M} = 20,000$ FT)

PROGRAM VARIABLE	SYMBOL	DESCRIPTION
----- A2	k_p -----	Maximum analog voltage ($k_p = 100v$) Smallest bit ADC resolution in feet

VII. SUBROUTINE MISCOM

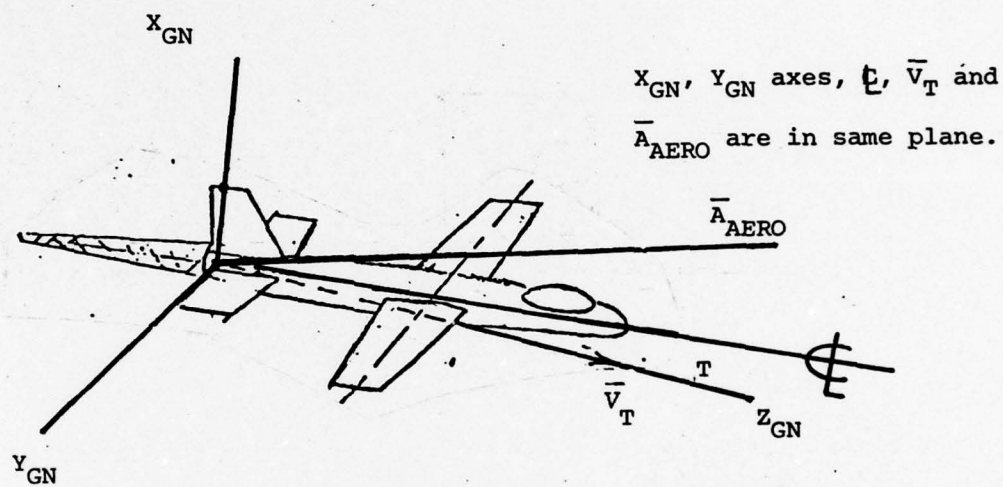
VII. SUBROUTINE MISCOM

Subroutine MISCOM transforms the relative missile minus target location in launch coordinates to target fixed coordinates referenced to the target tailpipe. The missile path projection is then computed by a least square straight line approximation of real time data. Nearest approach miss distance is computed in each plane of the target fixed coordinate system (referenced to tailpipe origin).



OVERVIEW OF SUBROUTINE MISCOM

FIGURE 7.1



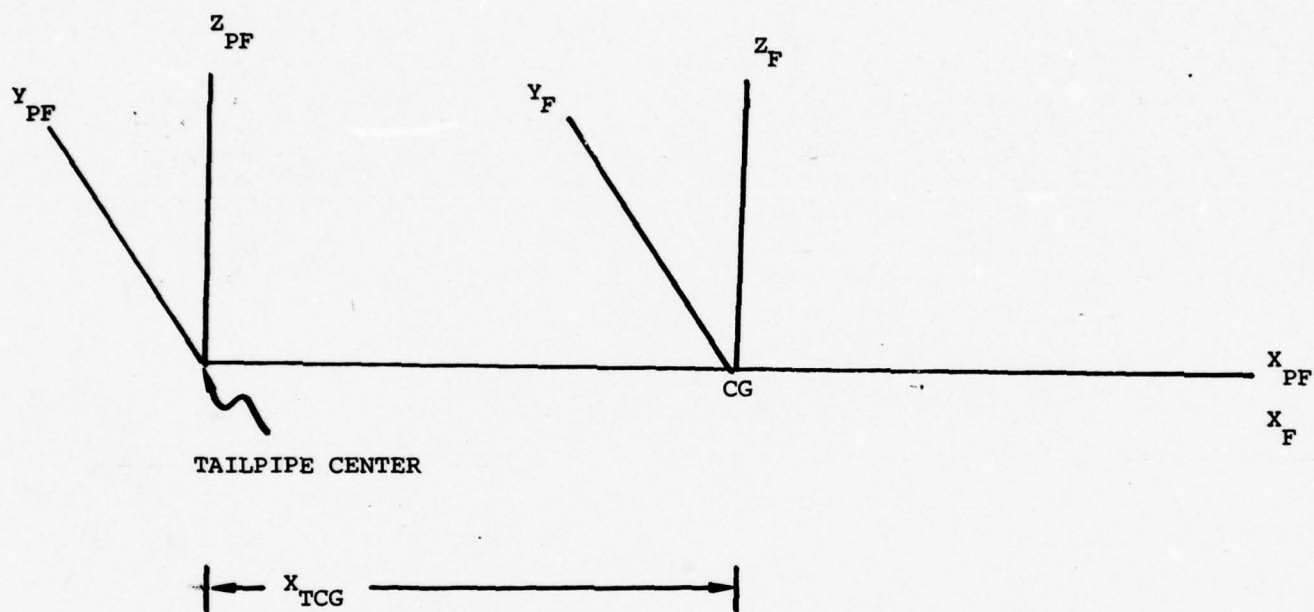
GENERALIZED TARGET COORDINATE SYSTEM
FIGURE 7.2

Transformation of Generalized Target Coordinates to Tailpipe Fixed Coordinates

$$\begin{bmatrix} X_{PF} \\ Y_{PF} \\ Z_{PF} \end{bmatrix} = \begin{bmatrix} \sin \alpha_T & 0 & \cos \alpha_T \\ 0 & -1 & 0 \\ \cos \alpha_T & 0 & -\sin \alpha_T \end{bmatrix} \begin{bmatrix} X_{GN} \\ Y_{GN} \\ Z_{GN} \end{bmatrix}$$

Transformation of Tailpipe Fixed Coordinates to Origin at Target CG

$$\begin{bmatrix} X_F \\ Y_F \\ Z_F \end{bmatrix} = \begin{bmatrix} \frac{1 - X_{TCG}}{X_{PF}} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} X_{PF} \\ Y_{PF} \\ Z_{PF} \end{bmatrix}$$



TAILPIPE TARGET FIXED AND TARGET FIXED COORDINATE SYSTEM RELATIONSHIP

FIGURE 7.3

MISSILE PATH PROJECTION

The missile path projection is computed in target fixed coordinates referenced to the target tailpipe. This projection is based upon a linear curve fit of real time relative-position-data.

For a least squares approximate linear curve fit, the projection equations are

$$Y_F = a_1 X_F + b_1$$

$$Z_F = a_2 X_F + b_2$$

The least square approximate fit for a_1 and b_1 is obtained from the simultaneous solution of the following equations.

$$a_1 \sum_{i=1}^n X_{Fi}^2 + b_1 \sum_{i=1}^n X_{Fi} = \sum_{i=1}^n X_{Fi} Y_{Fi}$$

$$a_1 \sum_{i=1}^n X_{Fi} + b_1 n = \sum_{i=1}^n Y_{Fi}$$

Then, a_2 and b_2 can be solved similarly

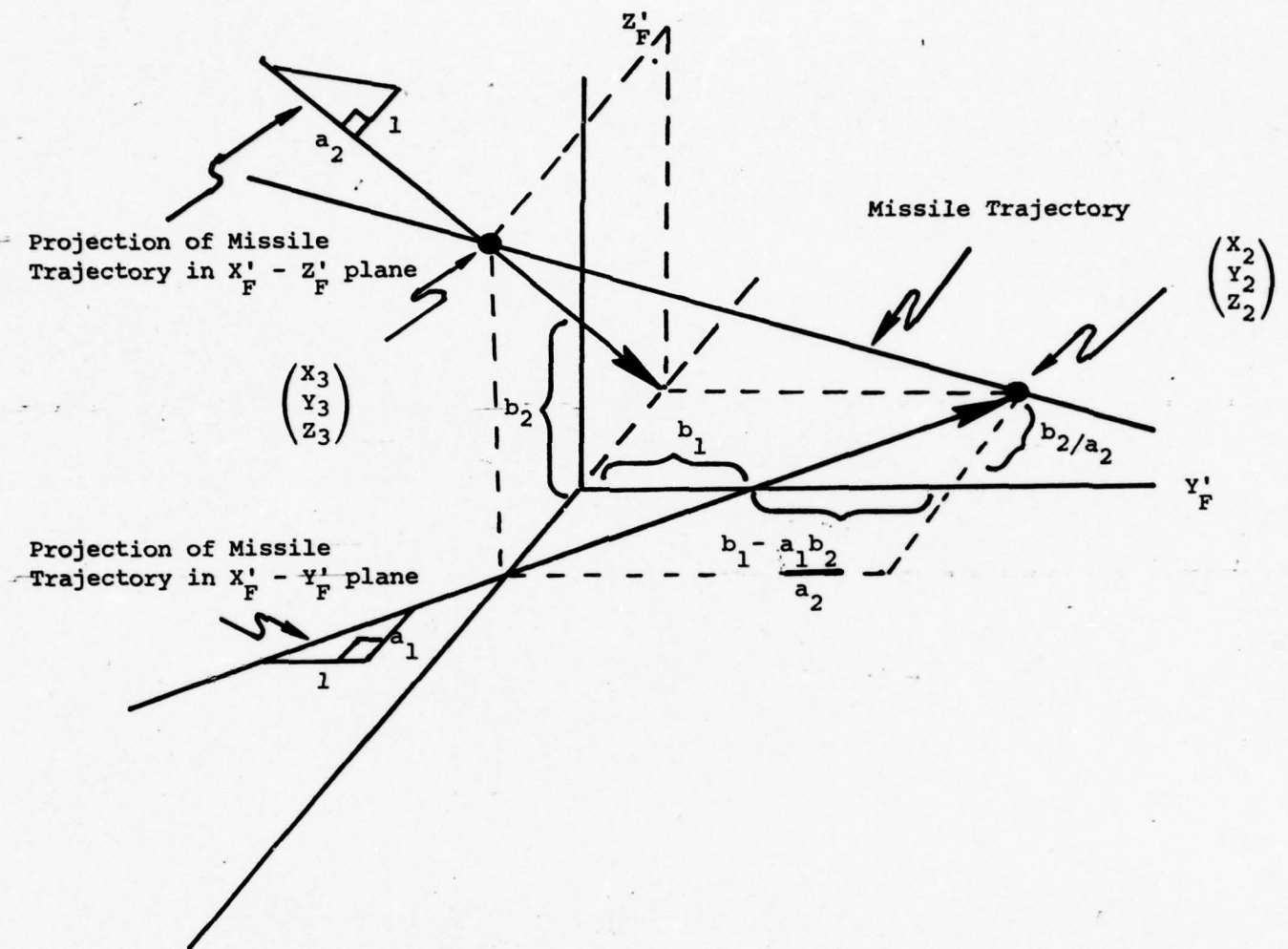
$$a_2 \sum_{i=1}^n X_{Fi}^2 + b_2 \sum_{i=1}^n X_{Fi} = \sum_{i=1}^n X_{Fi} Z_{Fi}$$

$$a_2 \sum_{i=1}^n X_{Fi} + b_2 n = \sum_{i=1}^n Z_{Fi}$$

where n is the number of real time data collection points.

Then, the piercing points of the missile trajectory into the $X'_F - Y'_F$ plane, $X'_F - Z'_F$ plane and the $Y'_F - Z'_F$ plane is computed. These values are printed as:

XM(1), YM(1), ZM(1) - the piercing point in the $Y'_F - Z'_F$ plane



Projections of Missile Trajectory onto $X'_F - Y'_F$ plane
and $X'_F - Z'_F$ plane

FIGURE 7.4

$XM(2), YM(2), ZM(2)$ - the piercing point in the $X'_F - Y'_F$ plane, and

$XM(3), YM(3), ZM(3)$ - the piercing point in the $X'_F - Z'_F$ plane

The above piercing point are deduced from geometry as

$$\begin{bmatrix} X'_{F1} \\ Y'_{F1} \\ Z'_{F1} \end{bmatrix} = \begin{bmatrix} 0 \\ b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} XM(1) \\ YM(1) \\ ZM(1) \end{bmatrix}$$

$$\begin{bmatrix} X'_{F2} \\ Y'_{F2} \\ Z'_{F2} \end{bmatrix} = \begin{bmatrix} -b_2/a_2 \\ b_1 - \frac{a_1 b_2}{a_2} \\ 0 \end{bmatrix} = \begin{bmatrix} XM(2) \\ YM(2) \\ ZM(2) \end{bmatrix}$$

$$\begin{bmatrix} X'_{F3} \\ Y'_{F3} \\ Z'_{F3} \end{bmatrix} = \begin{bmatrix} -b/a \\ 0 \\ b_2 - \frac{a_2 b_1}{a_1} \end{bmatrix} = \begin{bmatrix} XM(3) \\ YM(3) \\ ZM(3) \end{bmatrix}$$

Then, the nearest approach of the missile trajectory to origin is computed in the $Y'_F - Z'_F$ plane, $X'_F - Y'_F$ plane and the $X'_F - Z'_F$ plane respectively as:

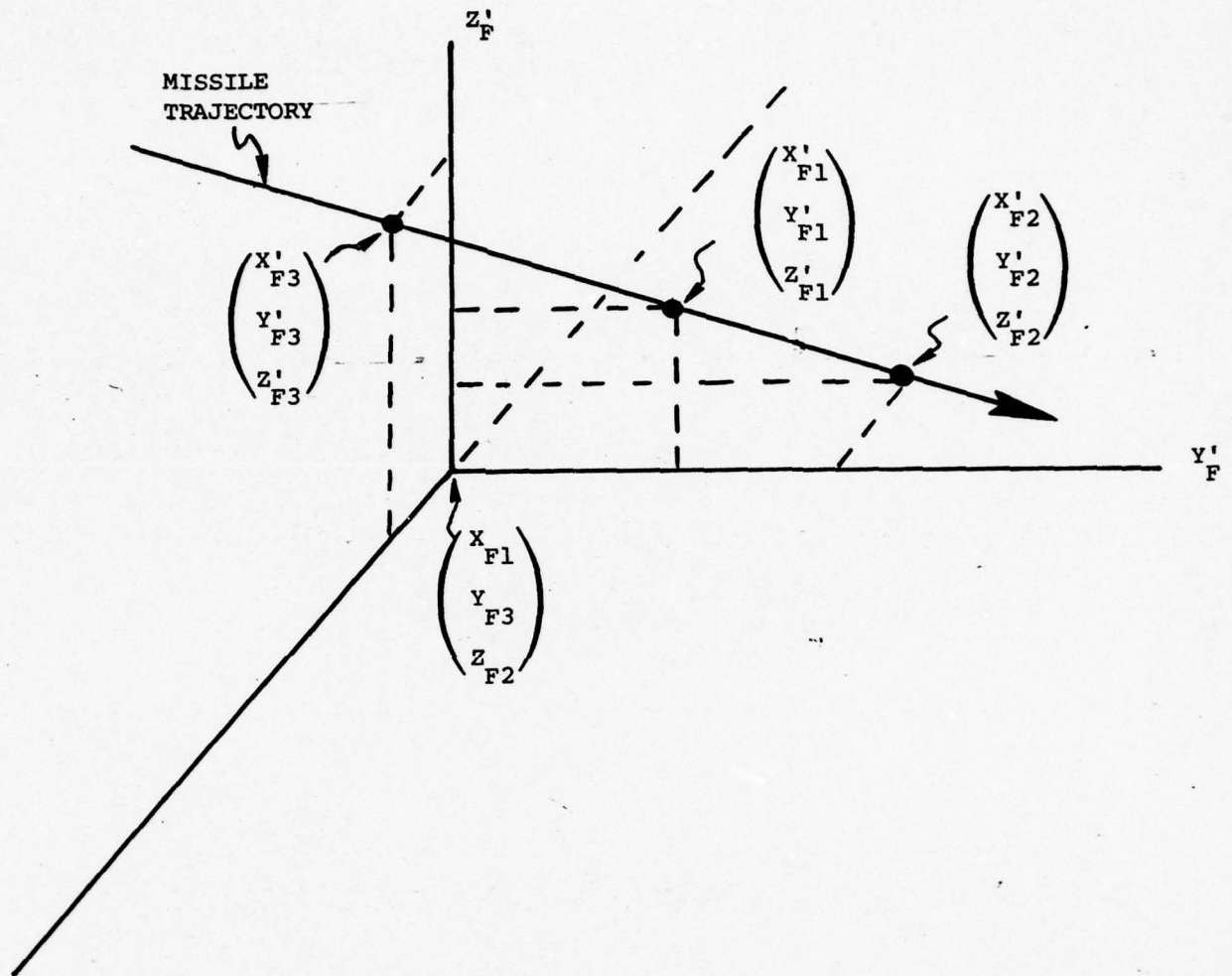
$$RM(1) = \sqrt{X'^2_{F1} + Y'^2_{F1} + Z'^2_{F1}}$$

$$RM(2) = \sqrt{X'^2_{F2} + Y'^2_{F2} + Z'^2_{F2}}$$

$$RM(3) = \sqrt{X'^2_{F3} + Y'^2_{F3} + Z'^2_{F3}}$$

Here the origin of the $X'_F - Y'_F - Z'_F$ system is

$$\begin{bmatrix} X'_{F1} \\ Y'_{F3} \\ Z'_{F2} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$



ISOMETRIC PROJECTION OF MISSILE TRAJECTORY PIERCING POINTS IN TARGET FIXED COORDINATES

FIGURE 7.5,

TABLE 7.1 DESCRIPTION OF VARIABLES IN SUBROUTINE MISCOM

COMPUTER VARIABLE	PHYSICAL VARIABLE	DESCRIPTION
FXA FYA FZA		Elements of the matrix transformation from launch coordinates to generalized target coordinates
FXB FYB FZB		
FXC FYC FZC		
DX DY DZ	$X_{ML} - X_{TL}$ $Y_{ML} - Y_{TL}$ $Z_{ML} - Z_{TL}$	Data collected during real time range table search (see PPX(I) PPY(I) and PPZ(I) in Subroutine REALT)
XT YT ZT	$X_{MGN} - X_{TGN}$ $Y_{MGN} - Y_{TGN}$ $Z_{MGN} - Z_{TGN}$	
AAA	a_s	Speed of sound in air
ZZZ	h_{asl}	Target altitude in earth fixed coordinate + altitude of launch site above sea level
VT	V_T	Velocity of target
XDEF YDEF ZDEF	X_{TE} Y_{TE} Z_{TE}	Target maneuver velocity at time of first real time data collection point
QM	Q_m	Mach number of target
CLA	$C_{L\alpha_T}$	Aerodynamic lift coefficient of target due to angle of attack
WT	W_T	Weight of target
ST	S_T	Reference surface area of target
AT	α_T	Angle of attack of target
XS YS ZS	$X_{MGN} - X_{TGN}$ $Y_{MGN} - Y_{TGN}$ $Z_{MGN} - Z_{TGN}$	The last real time data point collected, expressed in generalized launch coordinates
	X_{TCG}	Distance from tailpipe center to CG measured along target centerline
	X_{PF}	

COMPUTER VARIABLE	PHYSICAL VARIABLE	DESCRIPTION
S2	$\cos(\theta_L)\cos(\psi_L)$	Elements of coordinate transformation launch coordinates to earth fixed coordinates
SPL		
S3	$\sin(\theta_L)\cos(\psi_L)$	
S4	$\cos(\theta_L)\sin(\psi_L)$	
CPL	$\cos(\psi_L)$	
S5	$\sin(\theta_L)\sin(\psi_L)$	
STL	$\sin(\theta_L)$	
CTL	$\cos(\theta_L)$	
N	-----	The number of data points collected during real time data collection
VVVV	$V_T(0)$	Speed of target at time = 0
XM(1),YM(1), ZM(1)	$X'_{F1}, Y'_{F1}, Z'_{F1}$	Missile trajectory piercing point in $Y'_F - Z'_F$ plane
XM(2),YM(2), ZM(2)	$X'_{F2}, Y'_{F2}, Z'_{F2}$	Missile trajectory piercing point in $X'_F - Y'_F$ plane
XM(3),YM(3), ZM(3)	$X'_{F3}, Y'_{F3}, Z'_{F3}$	Missile trajectory piercing point in $X'_F - Z'_F$ plane
RM(1),RM(2), RM(3)	-----	Distance of each piercing point from origin of $X'_F - Y'_F - Z'_F$ system
YA	a_1	See equations
ZA	a_2	See equations

VIII. SUBROUTINE GUID

VIII. SUBROUTINE GUID

(Coordinate transformation from earth fixed to launch coordinates)

$$\begin{bmatrix} X_L \\ Y_L \\ Z_L \end{bmatrix} = \begin{bmatrix} \cos\theta_L \cos\psi_L & \cos\theta_L \sin\psi_L & -\sin\theta_L \\ -\sin\psi_L & \cos\psi_L & 0 \\ \sin\theta_L \cos\psi_L & \sin\theta_L \sin\psi_L & \cos\theta_L \end{bmatrix} \begin{bmatrix} X_E \\ Y_E \\ Z_E \end{bmatrix}$$

TABLE 8.1 DESCRIPTION OF SYMBOLS FOR SUBROUTINE GUID

PROGRAM VARIABLE	SYMBOL	DESCRIPTION
XD	-----	Components in earth fixed coordinate system
YD	-----	
ZD	-----	
XDTG	-----	Components in launch coordinate system
YDTG	-----	
ZDTG	-----	
COSSO	-----	+ $\cos\theta_L$
COSSCO	-----	+ $\cos\psi_L$
SINSCO	-----	+ $\sin\psi_L$
SINSO	-----	+ $\sin\theta_L$

IX. SUBROUTINE INIT

BOK
DYNAMICS, INC.

IX. SUBROUTINE INIT

This subroutine computes the range table for real-time data collection and the initial conditions for the analog computer. More detail concerning the equations, given here, can be obtained in the section dealing with real-time digital computation.

Initial Velocity of Target in Launch-Coordinate System

$$\begin{bmatrix} \dot{x}_{TL}(0) \\ \dot{y}_{TL}(0) \\ \dot{z}_{TL}(0) \end{bmatrix} = \begin{bmatrix} \cos\theta_L \cos\psi_L & \cos\theta_L \sin\psi_L & -\sin\theta_L \\ -\sin\psi_L & \cos\psi_L & 0 \\ \sin\theta_L \cos\psi_L & \sin\theta_L \sin\psi_L & \cos\theta_L \end{bmatrix} \begin{bmatrix} \dot{x}_{TE}(0) \\ \dot{y}_{TE}(0) \\ \dot{z}_{TE}(0) \end{bmatrix}$$

$$\text{where } \theta_L = \theta_L(0)$$

$$\psi_L = \psi_L(0)$$

This transformation is performed in SUBROUTINE GUID

NOTE: The transformation is orthonormal therefore $A^{-1} = A^T$

Dive Angle

$$SEO = \tan^{-1} \frac{\dot{z}_{TE}(0)}{\sqrt{\dot{x}_{TE}^2(0) + \dot{y}_{TE}^2(0)}} \quad , \text{ if } \dot{y}_{TE}(0) \neq 0$$

NOTE: For all other cases see computations performed in program MAIN

Initial Angle of Attack

$$a = 1116.89 + .003894 h_{asL} \quad (\text{SLUGS/FT}^3)$$

$$\rho = .00237692 e^{.00003hasL} \quad (\text{FT/SEC})$$

$$Q_m = V_T/a_s$$

$$C_{L_{\alpha_T}} = CLAA|_{Q_m}$$

$$\alpha = \frac{2W_T}{\rho V_T^2 C_{L_{\alpha_T}} S_T} \sqrt{\ddot{x}_{TE}(0) + \ddot{y}_{TE}(0) + \ddot{z}_{TE}(0)}$$

Initial cos(ε)

$$\begin{aligned} \cos(\epsilon) = & \{(\sin\theta_L)(\dot{z}_{TE}(0) \cos\alpha - \sqrt{\dot{x}_{TE}^2(0) + \dot{y}_{TE}^2(0)} \sin\alpha) \\ & - (\cos\alpha + \dot{z}_{TE}(0) \sin\alpha / \sqrt{\dot{x}_{TE}^2(0) + \dot{y}_{TE}^2(0)}) \\ & (\dot{x}_{TE}(0) \cos\theta_L \cos\psi_L + \dot{y}_{TE}(0) \cos\theta_L \sin\psi_L)\} / V_T \end{aligned}$$

Initial Apparent Plume Length to Breadth Ratio

$$l/B = (L/B) \sqrt{1 - \cos^2(\epsilon)}$$

Initial \bar{L}_{os}

$$L_x = -R_i \cos\theta_L \cos\psi_L$$

$$L_y = -R_i \cos\theta_L \sin\psi_L$$

$$L_z = R \sin\theta_L$$

Initial Horizon Reference Vector

$$\beta = \cos^{-1} \frac{L_y}{\sqrt{L_x^2 + L_y^2}}$$

$$C_x = -\cos(\beta)$$

$$C_y = \begin{cases} -\sin(\beta), & \text{if } X_{\text{Los}} < 0 \\ +\sin(\beta), & \text{if } X_{\text{Los}} \geq 0 \end{cases}$$

Initial Target Centerline Vector

$$C_{L_x} = \frac{\dot{X}_{\text{TE}}(0) (\cos\alpha + \dot{Z}_{\text{TE}}(0) \sin\alpha)}{\sqrt{\dot{X}_{\text{TE}}^2(0) + \dot{Y}_{\text{TE}}^2(0)}}$$

$$C_{L_y} = \frac{\dot{Y}_{\text{TE}}(0) (\cos\alpha + \dot{Z}_{\text{TE}}(0) \sin\alpha)}{\sqrt{\dot{X}_{\text{TE}}^2(0) + \dot{Y}_{\text{TE}}^2(0)}}$$

$$C_{L_z} = \frac{\dot{Z}_{\text{TE}}(0) \cos\alpha - \sqrt{\dot{X}_{\text{TE}}^2(0) + \dot{Y}_{\text{TE}}^2(0)} \sin\alpha}{V_T}$$

Initial Plume Rotation Angle

$$\theta = \cos^{-1} \frac{C_x (L_y C_{Lz} - L_z C_y) + C_y (L_z C_x - L_x C_z)}{\sqrt{(L_y C_{Lz} - L_z C_y)^2 + (L_z C_x - L_x C_z)^2 + (L_x C_{Ly} - L_y C_{Lx})^2}}$$

$$D_z = L_x C_{Ly} - L_y C_{Lx}$$

$$T_{rp} = \pi/2 - \theta, \text{ if } D_z < 0$$

$$\pi/2 + \theta, \text{ if } D_z > 0 \text{ and } \theta < \pi/2$$

$$\theta - 3\pi/2, \text{ if } D_z > 0 \text{ and } \theta > \pi/2$$

Initial Plume Iris Ratio

$$H_{c7} = 1209.675 H \Big|_{R=7000}^{\epsilon} e^{-2.341(\ln(R_i/22965.831))} \quad (w/cm^2)$$

$$P_1 = 2 \tan^{-1} \left(\frac{B/2}{\ell} \right) \quad (DEG)$$

$$P = \frac{(f)(\ell)}{|L_{os}|} \quad (IN)$$

$$A_{t7} = \frac{P_2^2 \sin(P_1)}{2 \cos^2(P_1/2)} \quad (IN)^2$$

$$J_{tu7} = e^{1.003258(\ln A_{t7}/10)} \quad (W/STER)$$

$$I_{r7} = \frac{H_{c7}}{\frac{T_{fplume}}{J_{tu}}}$$

$$i_7 = i_7(I_{r7}) \quad (\text{table look up})$$

TABLE 9.1 DESCRIPTION OF SYMBOLS FOR SUBROUTINE INIT

PROGRAM VARIABLE	SYMBOL	DESCRIPTION
NPTS	-----	Number of real-time data collection points
XTERM	-----	Distance between target and missile at last data collection point
DX	-----	Distance between real-time data collection points
GGG	γ_{\min}	Minima of the overload function (see SUBROUTINE KSCALE)
DIF	-----	The difference between the data collection distance commanded and the largest data collection distance possible with the analog scaling given.
NADJ	-----	New value for NPTS if NPTS is too large
XD,XDX	$\dot{X}_{TE}(0)$	Target initial velocity in earth coordinates
YD,YDY	$\dot{Y}_{TE}(0)$	
ZD,ZDZ	$\dot{Z}_{TE}(0)$	
XDTG	$\dot{X}_{TL}(0)$	Target initial velocity in launch coordinates
YDTG	$\dot{Y}_{TL}(0)$	
ZDTG	$\dot{Z}_{TL}(0)$	
KKK	-----	$\text{KKK} = 0 \text{ if } \dot{Y}_{TE}(0) \neq 0$ $1 \text{ if } \dot{Y}_{TE}(0) = 0$
SEO	-----	Dive angle (Note, some cases are computed in MAIN)

PROGRAM VARIABLE	SYMBOL	DESCRIPTION
XDTGM(I)	\dot{x}_{TL}	Target velocity tables in launch coordinates
YDTGM(I)	\dot{y}_{TL}	
ZDTGM(I)	\dot{z}_{TL}	
IS1	-----	Print flag, IS1 \neq 1 indicates print desired
AAA	a_s	Speed of sound
ZZZ	h_{aSL}	Specific target altitude in earth fixed coordinates + altitude of missile launch site above sea level (FT)
PHO	ρ	Air density (SLUGS/FT ³)
QM	Q_m	Mach number of target
VVV	V_T	Velocity of target (Computed in MAIN)
CLA	$C_{L_{\alpha_T}}$	Aerodynamic lift coefficient of target due to angle of attack
CLAA	-----	Table containing CLA as a function of mach number
WT	W_T	Weight of target
ST	S_T	Reference surface area of target
XEU	$\ddot{x}_{TE}(0)$	Initial acceleration of target in earth fixed coordinates
YEU	$\ddot{y}_{TE}(0)$	
ZEU	$\ddot{z}_{TE}(0)$	
AT	α	Initial target angle of attack
STL	-----	$\sin(\theta_L)$

PROGRAM VARIABLE	SYMBOL	DESCRIPTION
C1	-----	$\cos (\alpha)$
S9	-----	$\sqrt{X_{TE}^2(0) + Y_{TE}^2(0)}$
S1	-----	$\sin (\alpha)$
S2	-----	$\cos (\theta_L) \cos (\psi_L)$
S4	-----	$\cos (\theta_L) \sin (\psi_L)$
RLB	ℓ/B	Apparent ratio of plume length to breadth
RLBK	L/B	Actual ratio of plume length to breadth
XLOS	L_x	Initial components of \vec{L}_{os} in earth fixed coordinates
YLOS	L_y	
ZLOS	L_z	
R	R_i	Initial range of target (FT)
BET	β	$\cos^{-1} (L_y / \sqrt{L_x^2 + L_y^2})$
L_x	L_x	Components of Horizon Reference vector in earth fixed coordinates
L_y	L_y	
CLX	C_{L_x}	Components of target center line vector in earth fixed coordinates
CLY	C_{L_y}	
CLZ	C_{L_z}	
TRP	T_{rp}	Initial plume rotation angle

PROGRAM VARIABLE	SYMBOL	DESCRIPTION
THE	θ	-----
HC7FT	H_{c7}	Commanded irradiance for plume
P1IRSS	P_1	Vertex angle of plume transparency (DEG)
P2IRSS	P_2	Length of plume transparency (IN)
AT7	A_{t7}	Area of plume transparency
RN	i_7	Iris ratio number 7
-----	f	Focal length of projection lens
-----	ℓ	Apparent length of plume

APPENDIX A. STINGER CODE

APPENDIX A

This Appendix contains a proposed, structured version of the MICOM Hybrid STINGER program. Usage would require the following changes:

1. Under "Manual Selection of Launch Conditions" where the variables KA, ITT, TAU, IRSS are read from a card - the program should be altered to read these variables from the terminal.
2. In order to integrate the new FLIGHT and REALT programs into the structured STINGER package, a few changes in the common blocks and variables in FLIGHT and REALT will be necessary.
3. In the structured version of STINGER only the programs MAIN and INIT have been essentially altered. Some cleaning up and alteration may be necessary in the subroutines which perform the post real-time calculations.
4. There are now two interpolation routines - INTERP and LINTRP. LINTRP is much faster and INTERP should probably be removed unless higher order interpolation than linear is desired.

X

INPUTS TO STRUCTURED STINGER PROGRAM

IS1 PRINT FLAG
 IS1 = 0 for limited printout
 IS1 = 1 for full printout
 format I5

NRUNS DESIRED NUMBER OF RUNS PER FLIGHT CONDITION
 1 NRUNS 20
 format I5

NPTS, DX, XTERM
 NPTS = NUMBER OF DATA POINTS TO BE COLLECTED
 1 NPTS 50

 DX = DELTA RANGE BETWEEN COLLECTED DATA POINTS

 XTERM = X SEPARATION AT WHICH REAL TIME IS TERMINATED
 format I10, 2F10.0

NL NUMBER OF SETS OF LAUNCH CONDITIONS
 1 NL 61
 format I5

(ZTEO(I), ASC(I), RR(I), I = 1, NL)

THESE ARE THE NL SETS OF LAUNCH CONDITIONS

ZTEO(I) IS THE I-TH INITIAL ALTITUDE

ASC(I) IS THE I-TH CROSSING ANGLE

RR(I) IS THE I-TH INITIAL RANGE
format 3F10.2

III LAUNCH SELECTION FLAG
 III = 0 for manual selection
 III = 1 for automatic selection
 format I5

NOTE: FROM THIS POINT ON, THE INPUTS TO BE SUPPLIED DEPEND
 ON THE VALUE OF III CHOSEN ABOVE.

THE FOLLOWING INPUTS ARE READ ONLY IF III = 0 (MANUAL SELECTION)
OR AFTER A FULL SET OF AUTOMATIC RUNS IS COMPLETED.

KA, ITT, TAU, IRSS

KA = NUMBER OF LAUNCH SET TO BE USED
ITT = NUMBER OF TARGET TRAJECTORY TO BE USED
TAU = TIME POINT ON THE TARGET TRAJECTORY AT WHICH
THE MISSILE IS LAUNCHED
IRSS IS THE IRSS FLAG
IRSS = 0 NOT AN IRSS RUN
IRSS = 1, IRSS RUN
format 2I5, F5.1, I5

AFTER A MANUAL RUN IS COMPLETED, THE PROGRAM WILL CYCLE
AND READ NEW VALUES OF KA, ITT, TAU, IRSS

THERE ARE TWO SPECIAL CONVENTIONS ON KA.

KA negative - restart program at very beginning
KA > 61 - terminate program

THE FOLLOWING INPUTS ARE READ ONLY IF III = 1 (AUTOMATIC SELECTION)

NSAM QUALITY CONTROL TEST CASE SAMPLE SIZE

$2 \leq \text{NSAM} \leq 11$
format I5

ICON CONTINUATION FLAG

ICON = 1 continue after quality control failure
ICON = 2 rerun previous runs after quality control failure
format I5

INL INITIAL LAUNCH SET NUMBER

$1 \leq \text{INL} \leq \text{NL}$
format I5

(CLMS(1), CLS1(I), CLS2(I), I = 1, 10)

DATA FOR COMPUTING CONTROL LIMITS
format 3 F6.3

Q1, Q2, Q3, Q4, Q5, Q6

DATA FOR COMPUTING CONTROL LIMITS
format 6F10.4

W1, W2, W3, W4, W5, W6

DATA FOR COMPUTING CONTROL LIMITS
format 6F10.4

VARIABLE REFERENCE LIST

VARIABLE	COMMON BLOCK	USE
AAA	COMM	Speed of sound
AARUNS		Averages related to kill probabilities
AASUM		
ABRUNS		
ABSUM		
ADSF(10)		Array of analog-to-digital scale factors
ARB(20)		Array for storing miss distances relative to tailpipe
ARBT(20)		Array for storing miss distances relative to CG
ARC(20)		See ARB
ARCT(20)		See ARBT
ARM(20)	EXTRA	See ARB
ARMT(20)		See ARBT
AS		Target crossing angle
ASC(61)		Table of target crossing angles
ASEO	GTARG	Target dive angle (degrees)
AT		Initial target angle of attack
AXB(20)		See ARB
AXBT(20)		See ARBT
AXC(20)		See ARB
AXCT(20)		See ARBT
AXM(20)		See ARB
AXMT(20)		See ARBT
AYB(20)		See ARB
AYBT(20)		See ARBT
AYC(20)		See ARB
AYCT(20)		See ARBT
AYM(20)		See ARB
AYMT(20)		See ARBT
AZB(20)		See ARB
AZBT(20)		See ARBT
AZC(20)		See ARB
AZCT(20)		See ARBT
AZM(20)		See ARB
AZMT(20)		See ARBT
A1	COMP	Target angle of attack (RADIANs)
A1P1		Control limits
A1P2		
A1P3		
A1P4		

VARIABLE REFERENCE LIST (Con't)

VARIABLE	COMMON BLOCK	USE
A1P5	COMP	Control limits
A1P6	COMP	
A2P1	COMP	
A2P2	COMP	
A2P3	COMP	
A2P4	COMP	
A2P5	COMP	
A2P6	COMP	Tables related to lethality
BDHX(22)	PK	
BDHY(22)	PK	
BDHZ(22)	PK	Cosine of target angle of attack Target lift coefficient Target lift coefficient table (function of mach)
CA		
CLA		
CLAA(10)	RTCOM	Data for calculating control limits
CLMS(10)	COMP	
CLS1(10)	COMP	
CLS2(10)	COMP	Components of initial target center line vector
CLX		
CLY		
CLZ		Cosine of the angle between the line of sight and the target center line
COSE		
COSEI	RTCOM	
COSMU1	MU	Initial value of cose Terms of a transformation matrix (see subroutine PRIME)
COSMU2	MU	
COSMU3	MU	
COSSCO	ANG	Cosine of PSILR
COSO	ANG	Cosine of THETLR
CPL	RTCOM	= COSSCO
CTL	RTCOM	= COSO
CX		Components of initial horizon reference vector
CY		
C1		
DAOUT1	*DAC1	Cosine of AT
DAOUT2	*DAC1	
DAOUT3	*DAC1	
DAOUT4	*DAC1	
DAOUT5	*DAC1	
DAOUT6	*DAC1	

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
DAOUT7	*DAC1	Variables which are converted from digital to analog
DAOUT8	*DAC1	
DAOUT9	*DAC1	
DAOUT10	*DAC1	
DAOUT11	*DAC1	
DASF(11)	COMM	Array of digital to analog scale factors
DELTAR(30)	MISL	Target range table (function of time)
DT		Current time in real time
DTF	RTCOM	Value of DT at termination of real time
DTR		Conversion factor-degrees to RADIANS
DX	EXTRA	Delta range between collected data points
DX		X separation between target and missile
DXG	RTCOM	Value of DX at termination of real time
DY		Y separation between target and missile
DYG	RTCOM	Value of DY at termination of real time
DZ		Z separation between target and missile
DZG	RTCOM	Value of DZ at termination of real time
ECOS(17)	RTCOM	Table used in calculating IRIS ratio 7
EDOT	RTCOM	GGG/G
FCI77(9)	RTCOM	Table used in calculating IRIS ratio 7
FI7T(9)	RTCOM	Table used in calculating IRIS ratio 7
FXA	GTARG	Terms of a transformation matrix (see subroutine MISCOM)
FXB	GTARG	
FXC	GTARG	
FYA	GTARG	
FYB	GTARG	
FYC	GTARG	
FZA	GTARG	
FZB	GTARG	
FZC	GTARG	
G	RTCOM	Estimated time at 1000 feet to go
GGG	RTCOM	Parameter used in variable analog scale factor
HR7EE(17)	RTCOM	Table used in calculating IRIS ratio 7
IADIN1	*ADC1	Values resulting from analog to digital conversion
IADIN2	*ADC1	
IADIN3	*ADC1	
IADIN4	*ADC1	
IADIN5	*ADC1	
IADIN6	*ADC1	

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
IADIN7 IADIN8 IADIN9 IADIN10 ICN	*ADC1 *ADC1 *ADC1 *ADC1 MISD	Values resulting from analog to digital conversion Number of the current real time run (1 ICN NR)
ICON		Flag to indicate continuation after quality control failure
IERR		Error flag for equipment reservation
IFT	COMP	Flag for quality control failure
III	MANEUV	Flag to indicate manual or automatic launch selection
IIN	*IDIS2	Input discrete word
INFLRT	COMM	Flag to indicate first pass through real time code
INL		Launch set number (automatic selection)
IOUT	*ODIS2	Output discrete word
IPASS		Flag to indicate first pass through main program
IPLANE	COMP	Parameter used in quality control test
IPTS	RTCOM	Number of data points to be collected before intercept
IQC1		Flag to indicate first launch set (automatic sel.)
IRSS		Flag to indicate IRSS run
IS1	PRNT	Flag to indicate full or partial printout
ITAU(60)	MANEUV	Table of launch times (see TAU)
ITRAJ(60)	MANEUV	Table of target trajectory numbers
ITT	MANEUV	Number of current target trajectory
I88		Flag to indicate last launch set (automatic selection)
I99	COMP	Flag to indicate test case is due
KA		Number of current launch conditions
KILL(22)	PK	Table related to lethality
LEVEL	RTCOM	Flag to indicate target maneuver in progress
LOOP1	COMM	Counters for the two loops in the real time code
LOOP2	COMM	
LTMAX	COMM	Maximum execution time of real time loop
NADJ	MANEUV	Number of entries in range table (see XXS)
NERR		Error flag for subroutine INTERP
NL		Number of sets of launch conditions

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
NPATH	COMM	Flag to indicate which loop to execute in real time code
NPTS	EXTRA	Desired number of data points
NPX		Number of data points used in interpolation (NPX = 2 is linear interpolation)
NR		Number of flights to be performed in current run
NRUNS		Desired number of runs per flight condition
NSAM	COMP	Quality control test case sample size (2 NSAM 11)
NT	RTCOM	Number of points in target trajectory tables
NX		Argument for subroutine interp-number of points in tables
PH0		Air density
PI		3.14159265
PIO2		PI/2.
PPX(50)	RTCOM	Arrays for storing DX, DY, and DZ
PPY(50)	RTCOM	respectively at points corresponding
PPZ(50)	RTCOM	to range table entries (see XXS)
PSIL		PSI launch-one of the two euler angles in the transformation from earth to launch coordinate system (degrees)
PSILR		PSIL converted to RADIANS
QM		Target mach number
QMM(10)	RTCOM	Table of mach numbers (goes with CLAA(10))
Q1	COMP	Data for calculating control limits
Q2	COMP	
Q3	COMP	
Q4	COMP	
Q5	COMP	
Q6	COMP	
RI	RTCOM	Initial range-missile to target
RLB		Apparent plume length to breadth ratio
RLBI	RTCOM	Initial value of RLB
RLBK	RTCOM	Actual plume length to breadth ratio
RM(3)	MISD	MISS distance array
RN		IRIS ratio 7
RNI	RTCOM	Initial value of RN

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
RR(61)		Table of target initial ranges
RTD		Conversion factor-radians to degrees
SA		Sine of target angle of attack
SEO		Target dive angle (RADIANS)
SINMU1	MU	Terms of a transformation matrix (see subroutine PRIME)
SINMU2	MU	
SINMU3	MU	
SINSCO	ANG	
SINSO	ANG	Sine of PSILR
SL0		Sine of THETLR
SL5		Sense line zero
SL6		Sense line five
SL15		Sense line six
SPHG	PK	Sense line fifteen
SPHS	PK	Variables related to kill probabilities
SPK	PK	
SPL	RTCOM	= SINSCO
SPM	PK	See SPHG
SPO		Plume rotation angle
SPOI	RTCOM	Initial value of SPO
STL	RTCOM	= SINSO
S1		Sine of AT
S1P1	COMP	Control limits
S1P2	COMP	
S1P3	COMP	
S1P4	COMP	
S1P5	COMP	
S1P6	COMP	
S2	RTCOM	Term of earth-to-launch transformation matrix
S2P1	COMP	
S2P2	COMP	Control limits
S2P3	COMP	
S2P4	COMP	
S2P5	COMP	
S2P6	COMP	
S3	RTCOM	See S2
S4	RTCOM	
S5	RTCOM	

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
TAMA(30)	MISL	Table of times-goes with DELTAR (30) and VM (30)
TAU		Time point on target trajectory at which missile is launched
THETAL	RTCOM	THETA launch - see PSIL (degrees)
THETLR		THETAL converted to RADIANS
TIME(50)	RTCOM	Array for storing DT at points corresponding to range table entries (See XXS)
TM(30)		Table of times-goes with XDEM, YDEM, ZDEM
TMA(30)	RTCOM	Table of times-goes with XDM, YDM, ZDM = SPO
TRP		
VM(30)	MISL	Target velocity table (function of time)
VMX(50)	RTCOM	Arrays for storing XDOT, YDOT and ZDOT
VMY(50)	RTCOM	Respectively at points corresponding
VMZ(50)	RTCOM	To range table entries (see XXS)
VT	GTARG	Target velocity (in subroutine MISCOM)
VTI		Target velocity in real time
VVVV	EXTRA	Initial target velocity
W1	COMP	Data for calculating control limits
W2	COMP	
W3	COMP	
W4	COMP	
W5	COMP	
W6	COMP	
X		Initial target X corrdinate in earth system
XC		Target velocity X component-earth system
XCOMP		Target velocity X component-launch system
XD	COMB	Used in earth-to-launch transformation (subroutine GUID)
XDDE	COMB	Target acceleration over data collection range-X component
XDEF	COMB	Target velocity at first range table entry-X component
XDEM(30, 45)	MANEUV	Array of 45 target velocity tables in earth system-X components
XDH(22)	PK	Table related to lethality
XDM(30)	RTCOM	Current target velocity table in earth system-X component
XDO	RTCOM	Value of XDOT at termination of real time

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
XDOT		Target-missile relative velocity-X component
XDTG	COMB	See XD
XDTGMS(30)	RTCOM	Current target velocity table in launch system-X component
XDTGO	RTCOM	Target initial velocity in launch system-X component
XE(30)	RTCOM	Target acceleration table-X component
XLOS		Missile to target line of sight-X component
XM(3)	MISD	MISS distance array
XMAN(4, 50)	RTCOM	Array for storing DT, XCOMP, YCOMP, ZCOMP at range table entries
XMISS(7)	RTCOM	Array for storing DX, DY, DZ, XDOT, YDOT, ZDOT and XMISSC if missile misses target
XMISSC		Variable which indicates a miss
XTERM	EXTRA	X separation between missile and target at which real time is terminated
XXS(50)	RTCOM	Range table for data collection-NADJ points separated by DX and ending with XTERM
XXX		X separation between target and missile- comes from an analog value which is scaled ten times smaller than DX
Y		Initial target Y coordinate in earth system
YA	COMD	Related to MISS distance
YC		Target velocity Y component-earth system
YCOMP		Target velocity Y component-launch system
YD	COMB	See XD
YDDE	COMB	See XDDE-Y component
YDEF	COMB	See XDEF-Y component
YDEM(30, 45)	MANEUV	See XDEM-Y components
YDH(22)	PK	See XDH
YDM(30)	RTCOM	See XDM-Y component
YDO	RTCOM	Value of YDOT at termination of real time
YDOT		See XDOT-Y component
YDTG	COMB	See XD
YDTGMS(30)	RTCOM	See XDTGMS-Y component
YDTGO	RTCOM	See XDTGO-Y component
YE(30)	RTCOM	See XE-Y component

VARIABLE REFERENCE LIST (Con't.)

VARIABLE	COMMON BLOCK	USE
YLOS	MISD	See XLOS-Y component
YM(3)		MISS distance array
YYY		See XXX-Y component
Z	COMD	Initial target Z coordinate in earth system
ZA		See YA
ZABOVE		Altitude of launch site (negative)
ZALT	RTCOM	Target altitude (negative)
ZC		Target velocity Z component-earth system
ZCOMP		Target velocity Z component-launch system
ZD	COMB	See XD
ZDDE	COMB	See XDDE-Z component
ZDEF	COMB	See XDEF-Z component
ZDEM(30, 45)	MANEUV	See XDEM-Z component
ZDH(22)	PK	See XDH
ZDM(30)	RTCOM	See XDM-Z component
ZDO	RTCOM	Value of ZDOT at termination of real time
ZDOT	COMB	See XDOT-Z component
ZDTG		See XD
ZDTGMS(30)		See XDTGMS-Z component
ZDTGO	RTCOM	See XDTGO-Z component
ZE(30)	RTCOM	See XE-Z component
ZLOS	MISD	See XLOS-Z component
ZM(3)		MISS distance array
ZTEQ(61)		Table of target initial altitudes
ZZZ		See XXX-Z component

COMMON BLOCK CROSS-REFERENCE TABLE

	ANG	COMB	COMD	COMM	COMP	EXTRA	GTARG	MANEUV	MISD	MISL	MU	PK	PRNT	RTCOM
MAIN	X		X		X	X		X	X			X	X	X
BLOCK DATA								X		X		X		X
FLIGHT				X										X
GUID	X	X												
HWFLOT														
INIT		X				X		X						X
INTERP														
KSCALE										X			X	X
LETH			X				X	X	X			X	X	X
LINTRP														
MEAN					X									
MISCOM		X	X			X	X	X	X		X		X	X
PRIME		X						X	X		X		X	X
QCLIM					X									
REALT				X										X

COMMON/ANG/

COSSCO

COSCO

SINSCO

SINSO

COMMON/COMB/

XD

XDDE

XDEF

XDTG

YD

YDDE

YDEF

YDTG

ZD

ZDDE

ZDEF

ZDTG

COMMON/COMD/

YA

ZA

COMMON/COMM/

ADSF (10)

DASF (11)

INFLRT

LOOP1

LOOP2

LTMAX

NPATH

COMMON/COMP/

A1P1	S1P3
A1P2	S1P4
A1P3	S1P5
A1P4	S1P6
A1P5	S2P1
A1P6	S2P2
A2P1	S2P3
A2P2	S2P4
A2P3	S2P5
A2P4	S2P6
A2P5	W1
A2P6	W2
CLMS (10)	W3
CLS1(10)	W4
CLS2(10)	W5
IFT	W6
IPLANE	
I99	
NSAM	
Q1	
Q2	
Q3	
Q4	
Q5	
Q6	
S1P1	
S1P2	

COMMON/EXTRA/

AS

DX

NPTS

VVVV

XTERM

COMMON/GTARG/

AT

FXA

FXB

FXC

FYA

FYB

FYC

FZA

FZB

FZC

VT

COMMON/MANEUV/

III

ITAU(60)

ITRAJ(60)

ITT

NADJ

XDEM(30, 45)

YDEM(30, 45)

ZDEM(30, 45)

COMMON/MISD/

ICN

RM(3)

XM(3)

YM(3)

ZM(3)

COMMON/MISL/

DELTAR(30)

TAMA(30)

VM(30)

COMMON/MU/

COSMU1

COSMU2

COSMU3

SINMU1

SINMU2

SINMU3

COMMON/PK/

BDHX(22)

BDHY(22)

BDHZ(22)

KILL(22)

SPHG

SPHS

SPK

SPM

XDH(22)

YDH(22)

ZDH(22)

COMMON/PRNT/

IS1

COMMON/RTCOM/

CLAA(10)	RLBI
COSEI	RLBK
CPL	RNI
CTL	SPL
DTF	SPOI
DXG	STL
DYG	S2
DZG	S3
ECOS(17)	S4
EDOT	S5
FCI77(9)	THETAL
FI7T(9)	TIME(50)
G	TMA(30)
GGG	VMX(50)
HR7EE(17)	VMY(50)
IPTS	VMZ(50)
LEVEL	XDM(30)
NT	XDO
PPX(50)	XDTGMS(30)
PPY(50)	XDTGO
PPZ(50)	XE(30)
	XMAN(4, 50)
RI	XMISS(7)

COMMON/RTCOM/ (Con't)

XXS(50)

YDM(30)

YDO

YDTGMS(30)

YDTGO

YE(30)

ZALT

ZDM(30)

ZDO

ZDTGMS(30)

ZDTGO

ZE(30)

EXPLANATION OF FLOW DIAGRAMS

The flow diagrams included here are hierarchical in nature with a top-down structure. In the first-level flow diagram, the program is broken down into its major modules, numbered I., II., III., etc., and the relationships among these modules are shown.

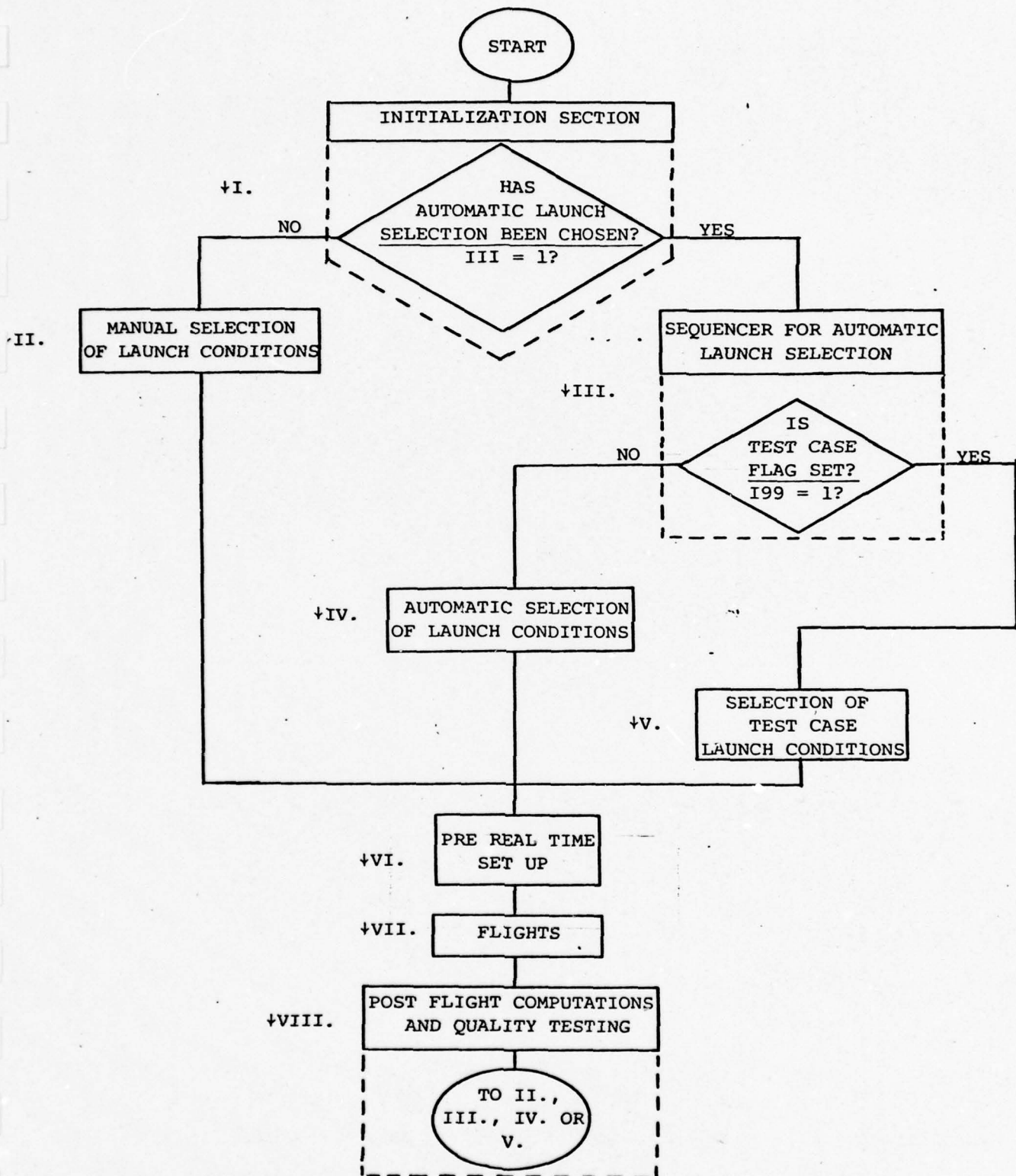
Each module in the first-level diagram is analyzed in more detail in a second-level flow diagram. For example, module III. in the first-level diagram is broken down into submodules numbered III. A., III. B., III. C., etc.

Some of the second-level modules are broken down further in third-level diagrams. For example, module III. K. in the second-level diagram devoted to module III. is broken down in a third-level diagram into blocks numbered III. K. 1., III. K. 2., etc.

The symbol + appearing before a block number indicates that there is a lower-level diagram devoted to that block.

MAIN PROGRAM
STINGER HYBRID SIMULATION
FIRST-LEVEL FLOW DIAGRAM

MAIN PROGRAM
STINGER HYBRID SIMULATION



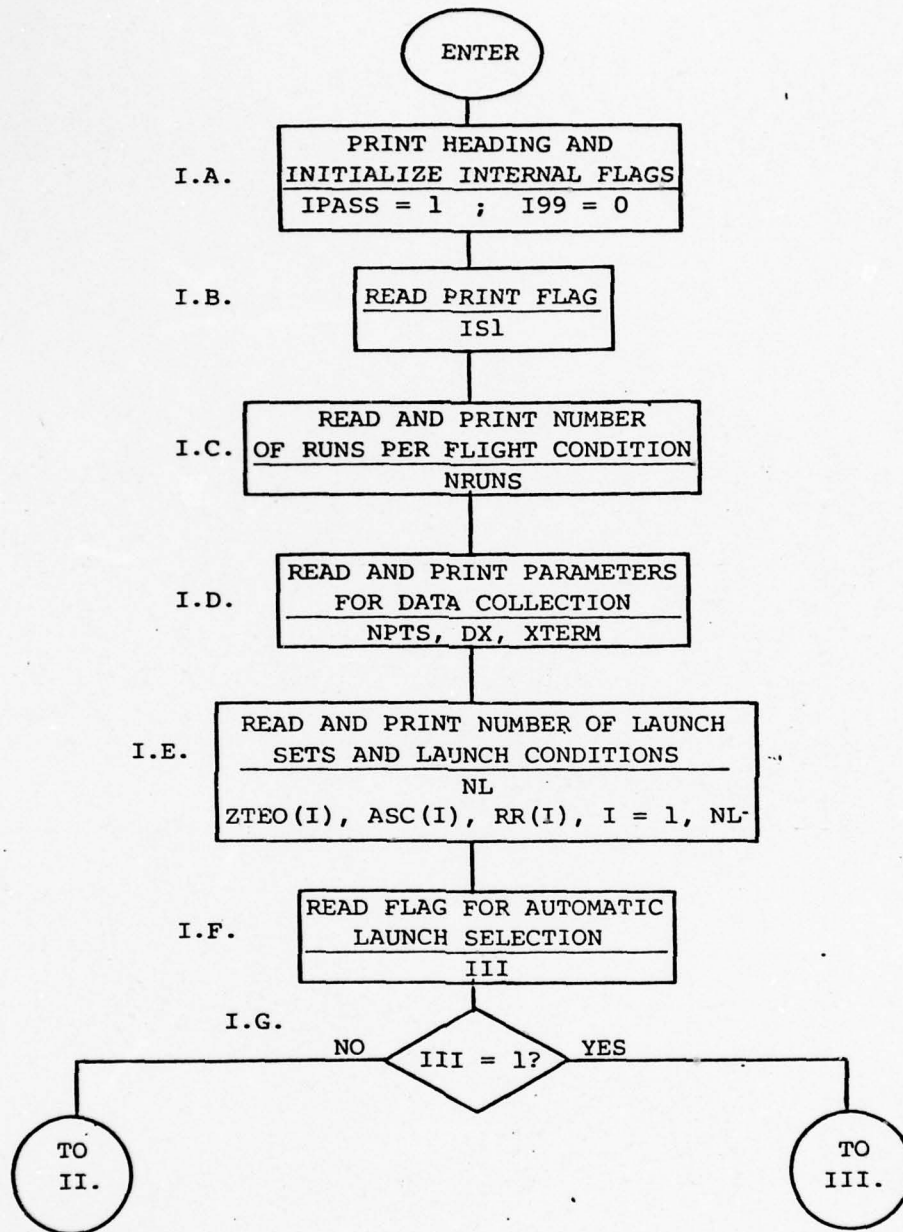
MAIN PROGRAM

STINGER HYBRID SIMULATION

SECOND-LEVEL FLOW DIAGRAMS

I.

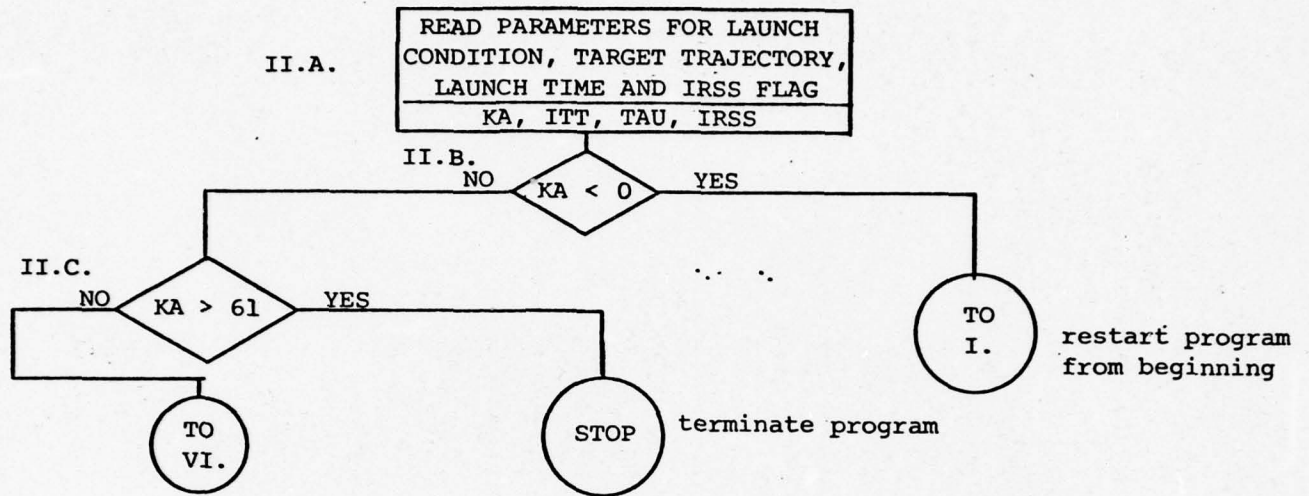
INITIALIZATION SECTION



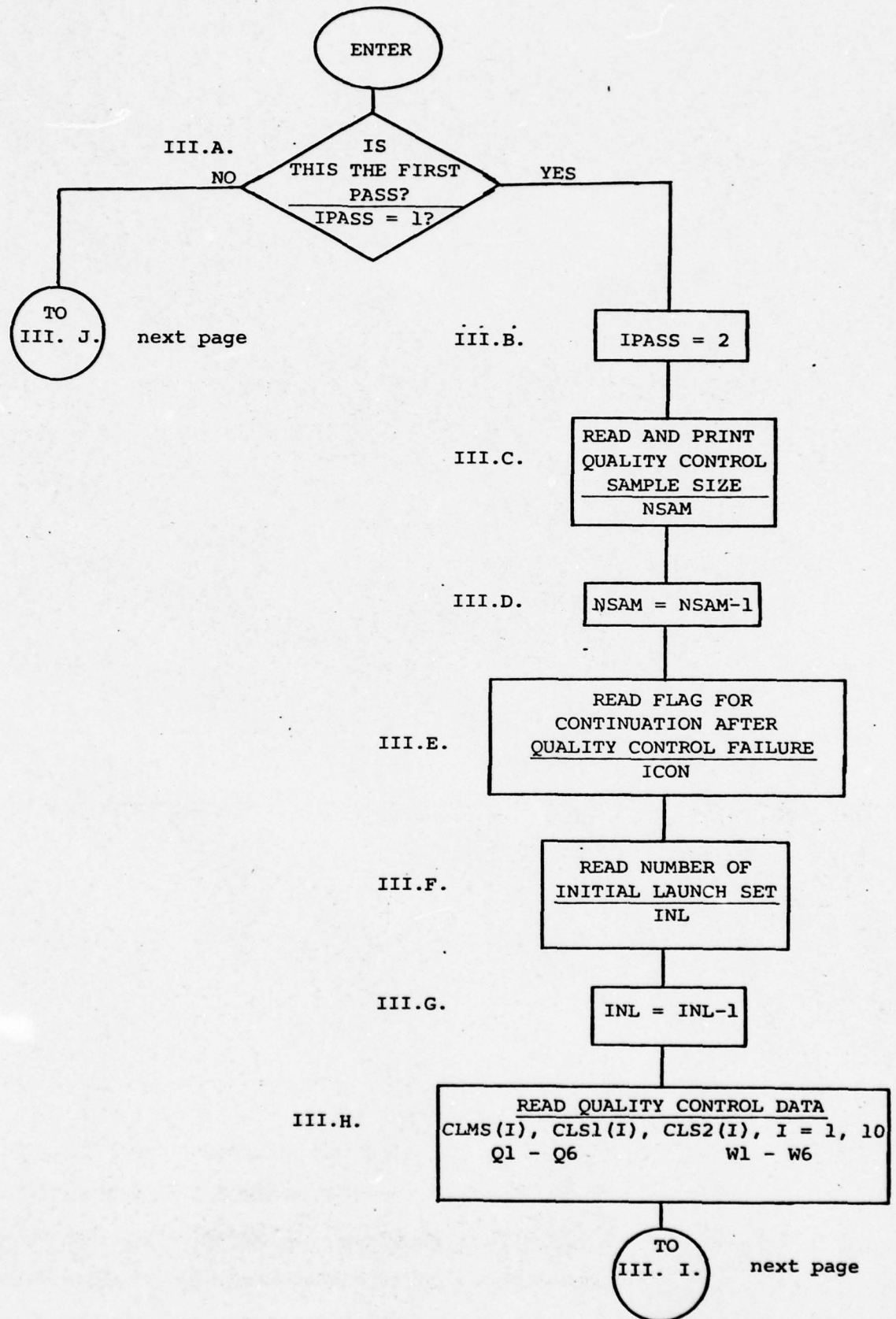
II.

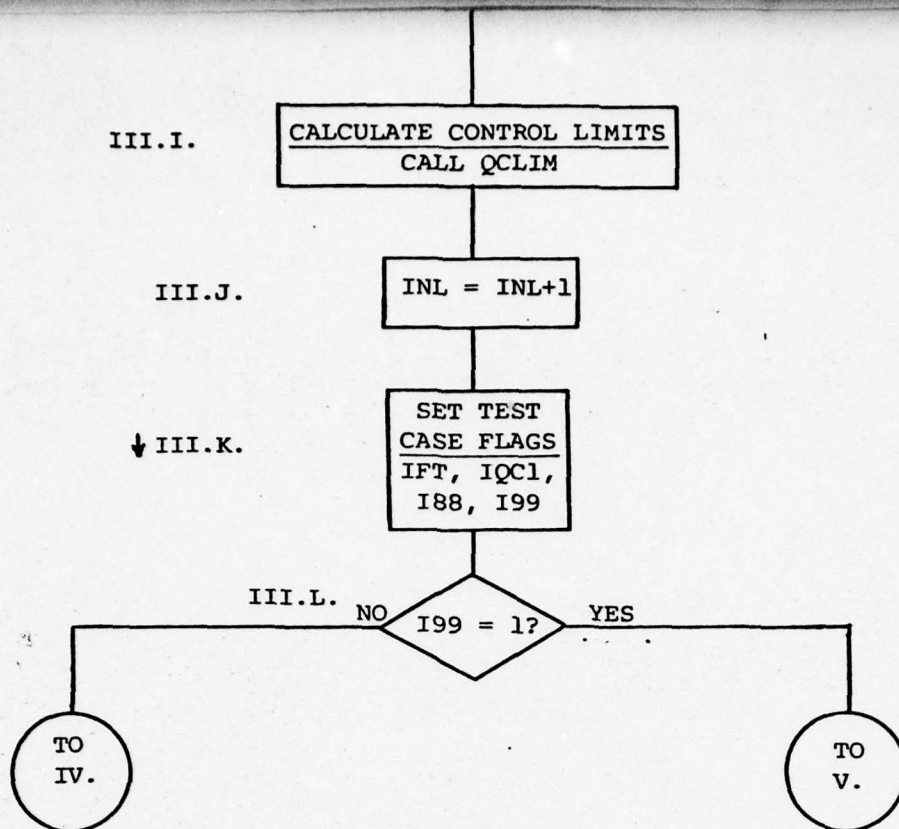
MANUAL SELECTION OF
LAUNCH CONDITIONS

ENTER



III.
SEQUENCER FOR AUTOMATIC
LAUNCH SELECTION

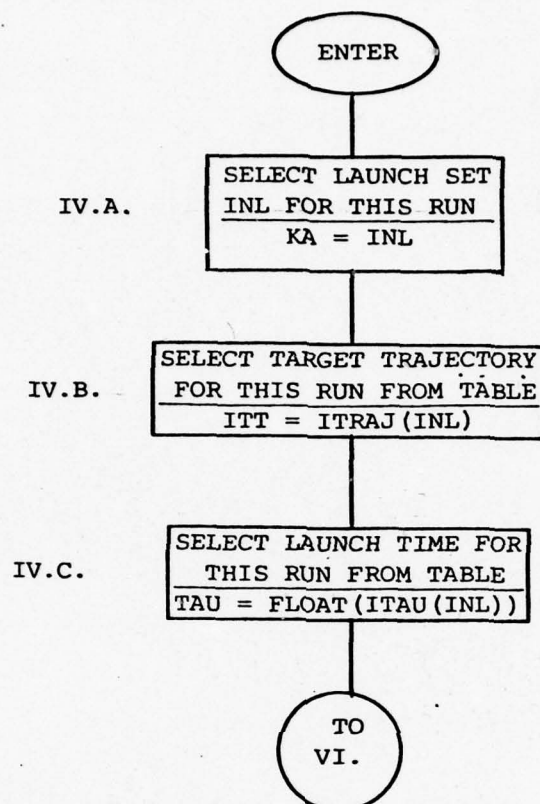




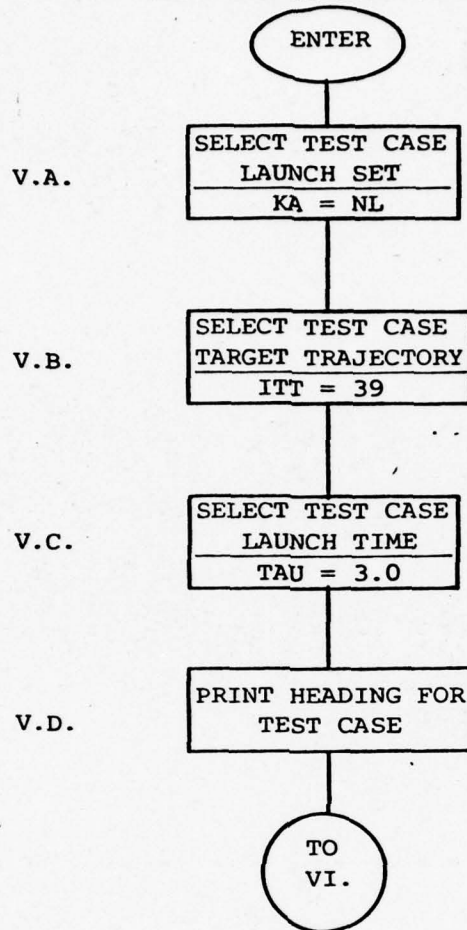
AUTOMATIC

X

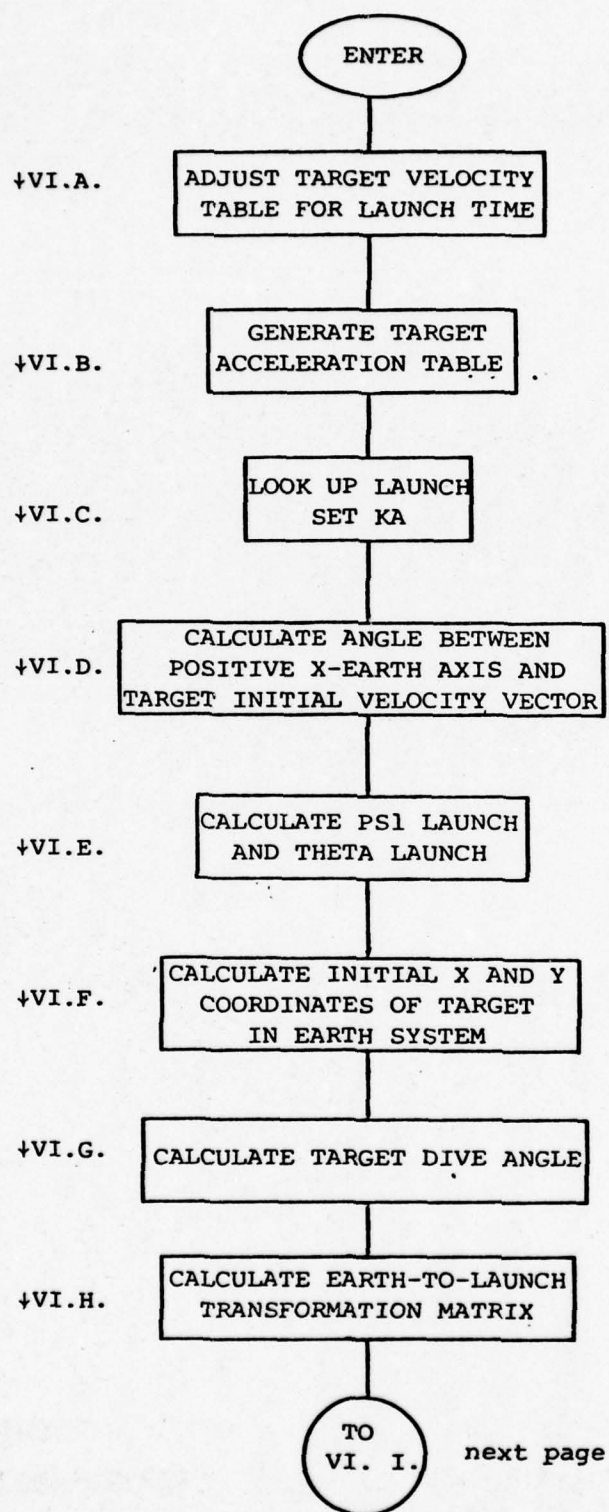
IV.
AUTOMATIC SELECTION
OF LAUNCH CONDITIONS



V.
SELECTION OF TEST
CASE LAUNCH CONDITIONS



VI.
PRE REAL TIME
SET UP



VI.I.

CALCULATE OTHER
INITIAL CONDITIONS
CALL INIT

VI.J.

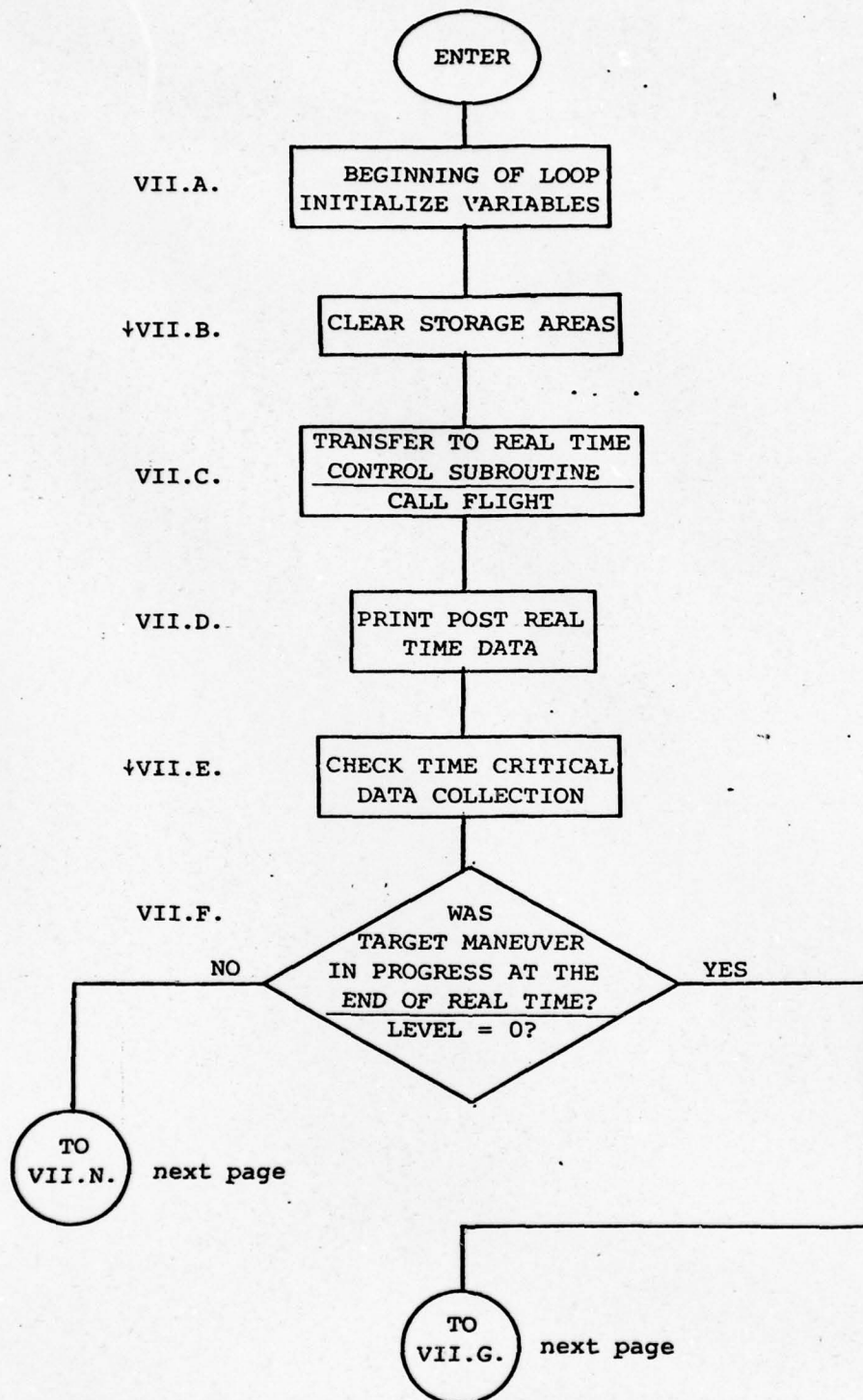
PRINT FLIGHT
CONDITIONS

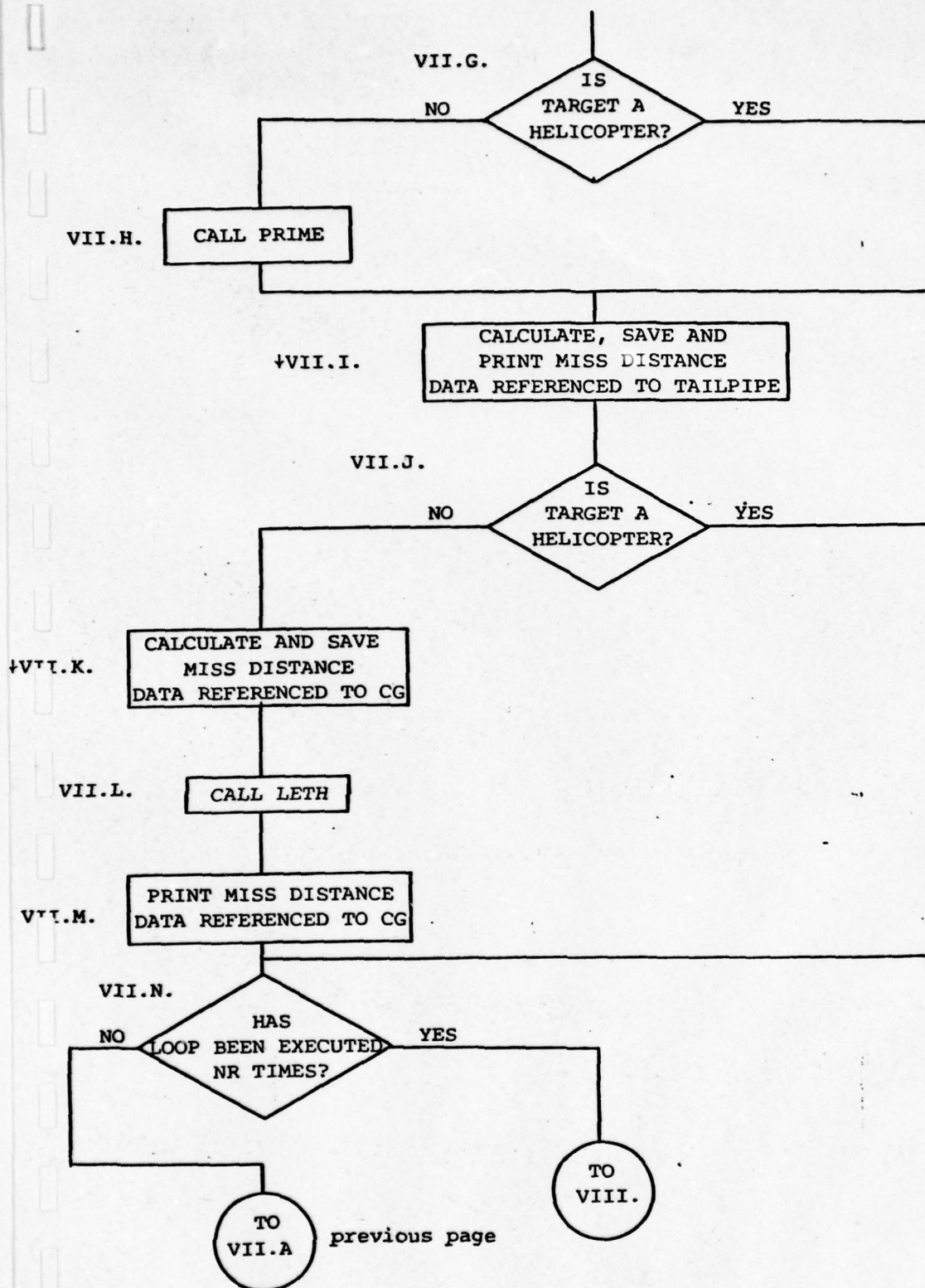
VI.K.

PREPARE TO
MAKE FLIGHTS

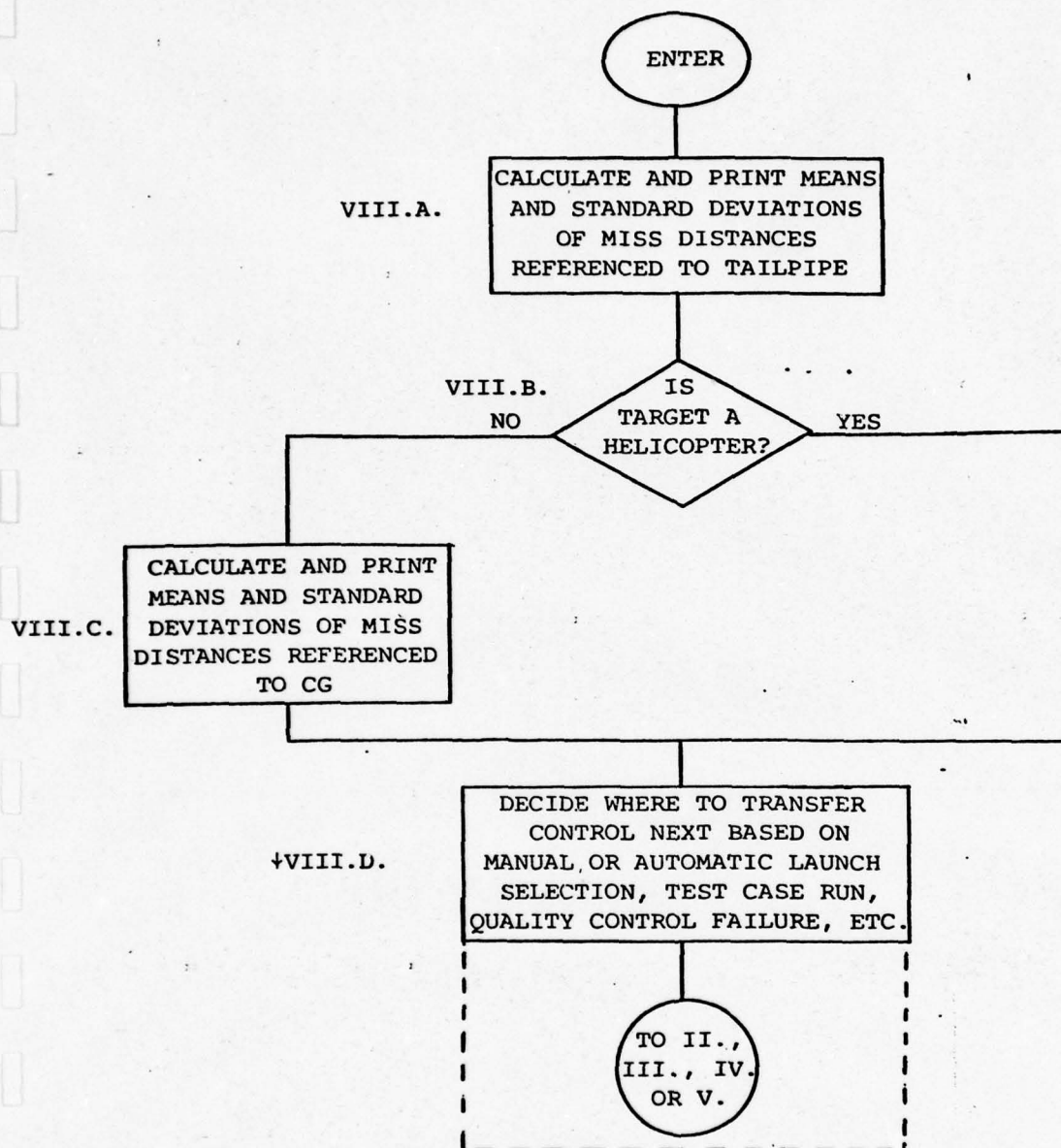
TO
VII.

VII.
FLIGHTS





VIII.
POST FLIGHT COMPUTATIONS
AND QUALITY TESTING

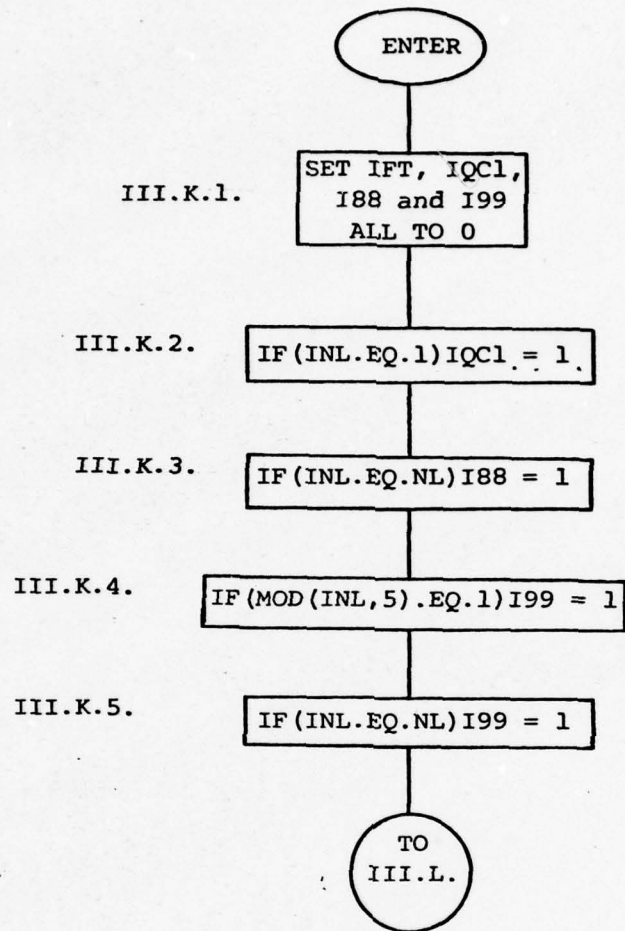


MAIN PROGRAM

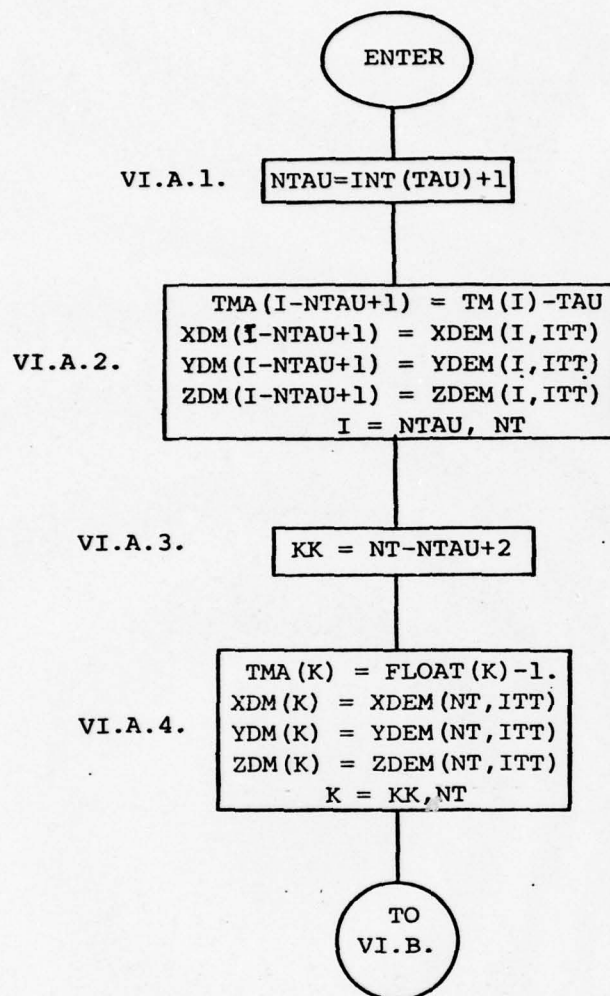
STINGER HYBRID SIMULATION

THIRD LEVEL FLOW DIAGRAMS

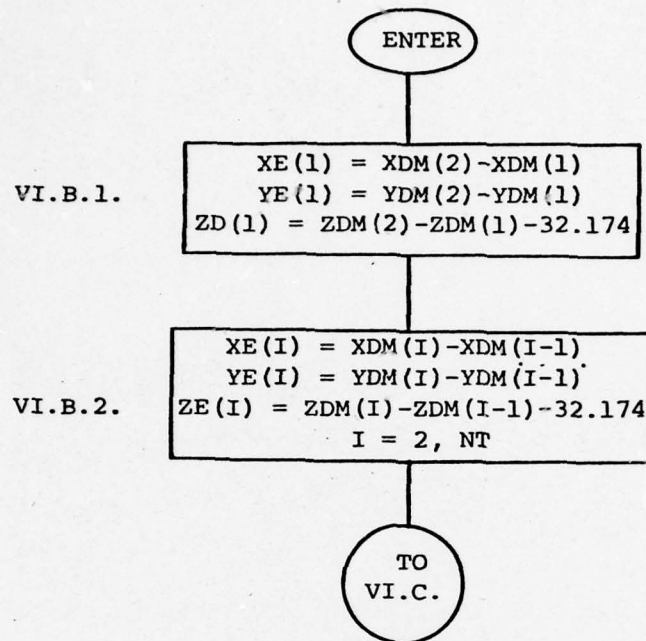
III.K.
SET TEST
CASE FLAGS



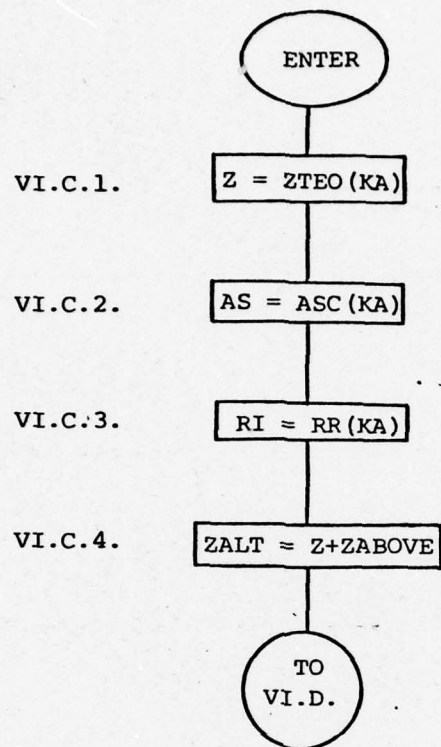
VI.A.
ADJUST TARGET VELOCITY
TABLE FOR LAUNCH TIME



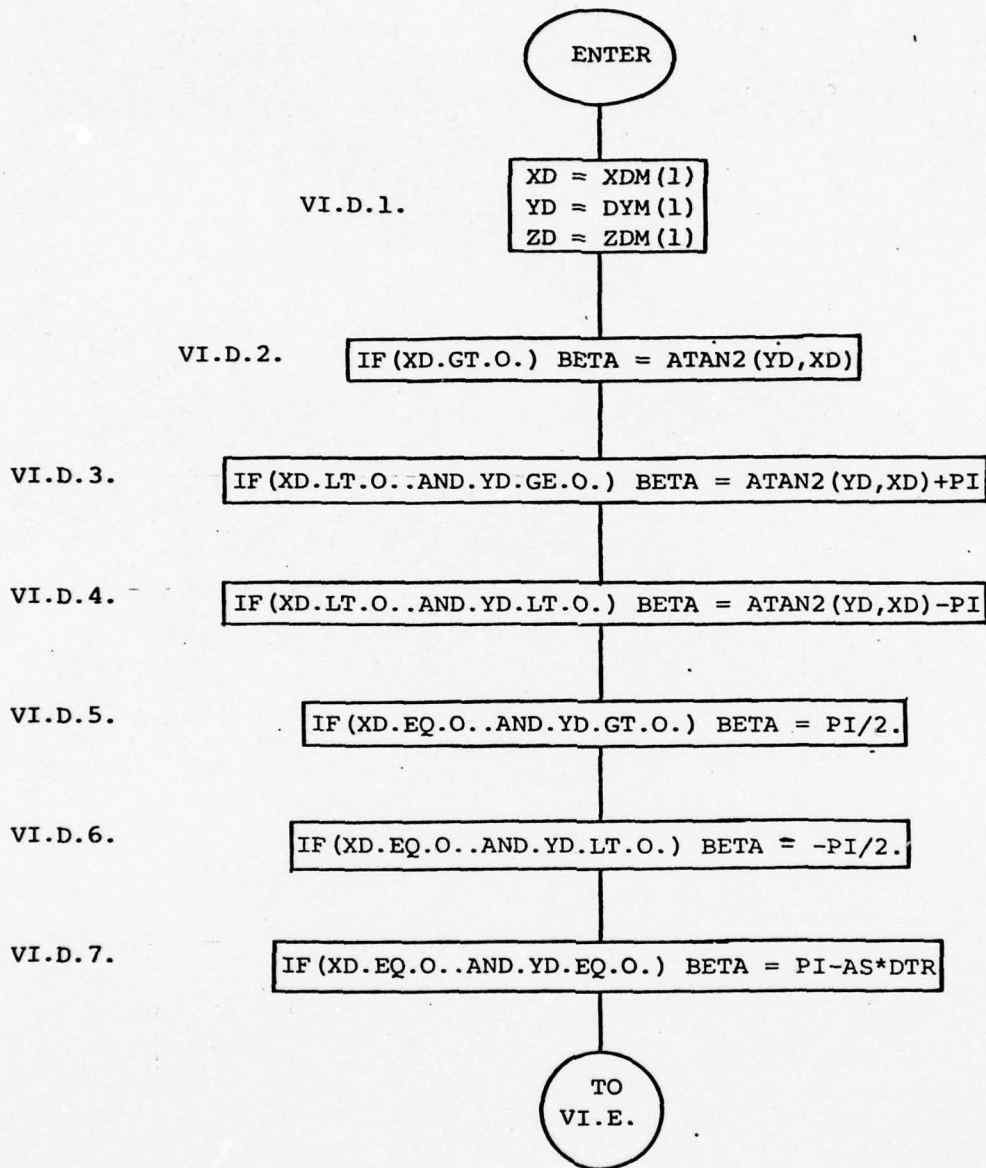
VI.B.
GENERATE TARGET
ACCELERATION TABLE



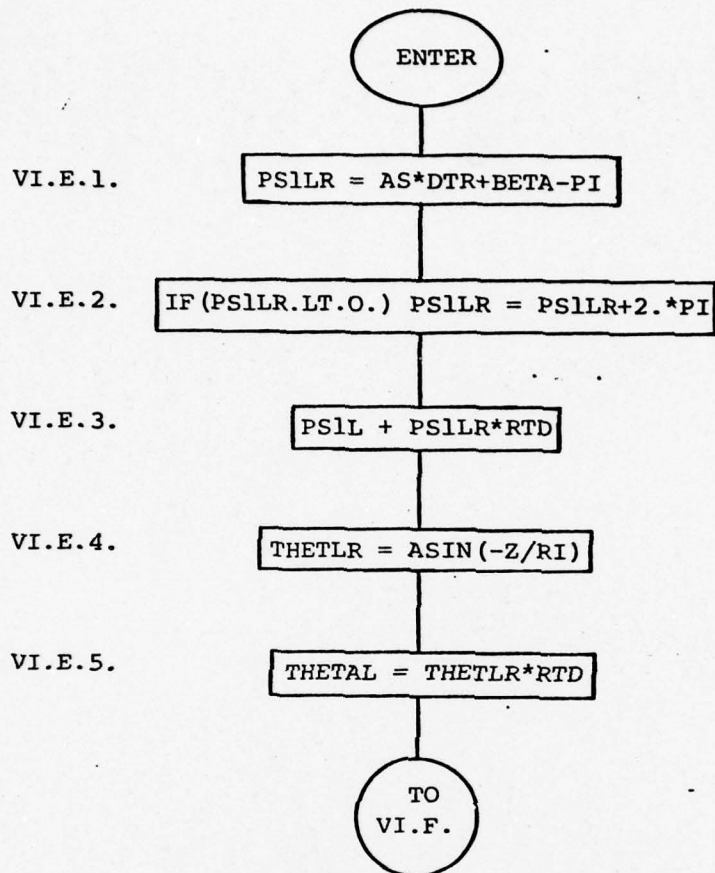
VI.C.
LOOK UP LAUNCH
SET KA



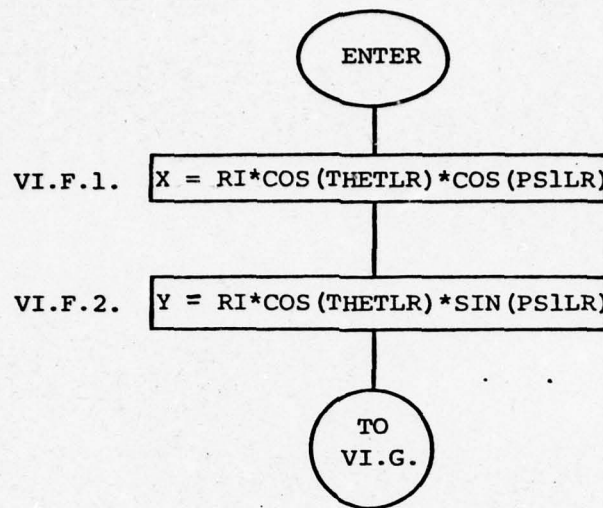
VI.D.
CALCULATE ANGLE BETWEEN
POSITIVE X-EARTH AXIS AND
TARGET INITIAL VELOCITY VECTOR



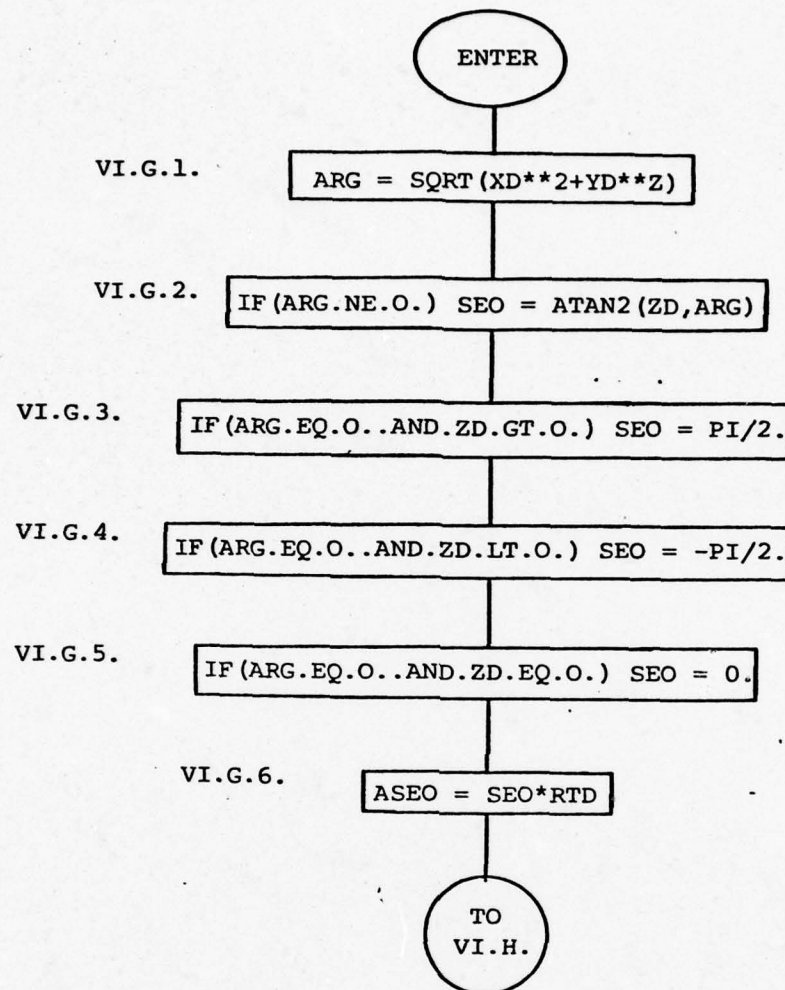
VI.E.
CALCULATE PS1 LAUNCH
AND THETA LAUNCH



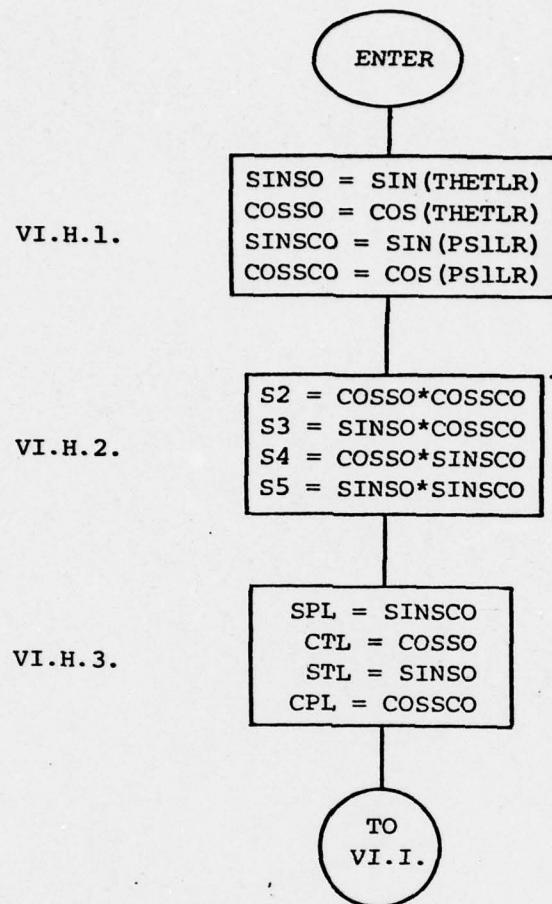
VI.F.
CALCULATE INITIAL X AND Y
COORDINATES OF TARGET
IN EARTH SYSTEM



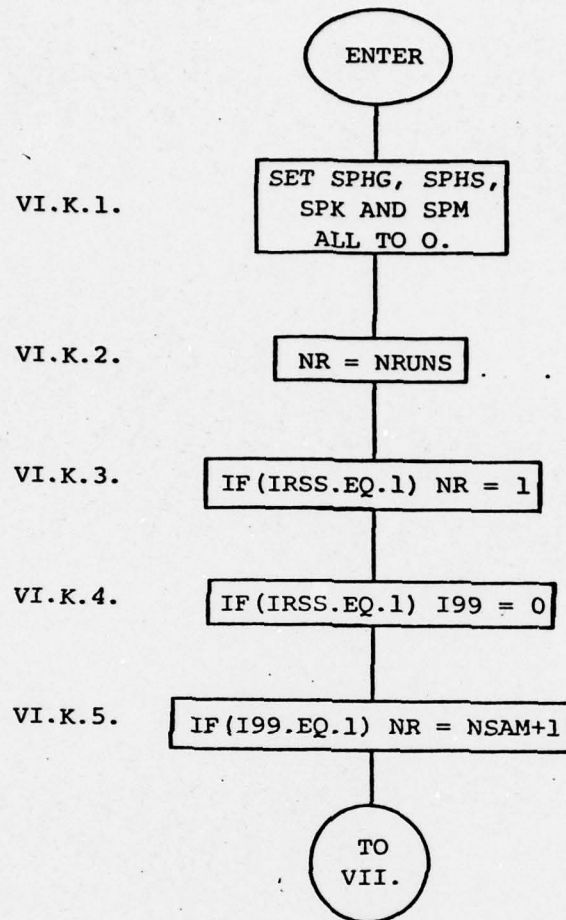
VI.G.
CALCULATE TARGET
DIVE ANGLE



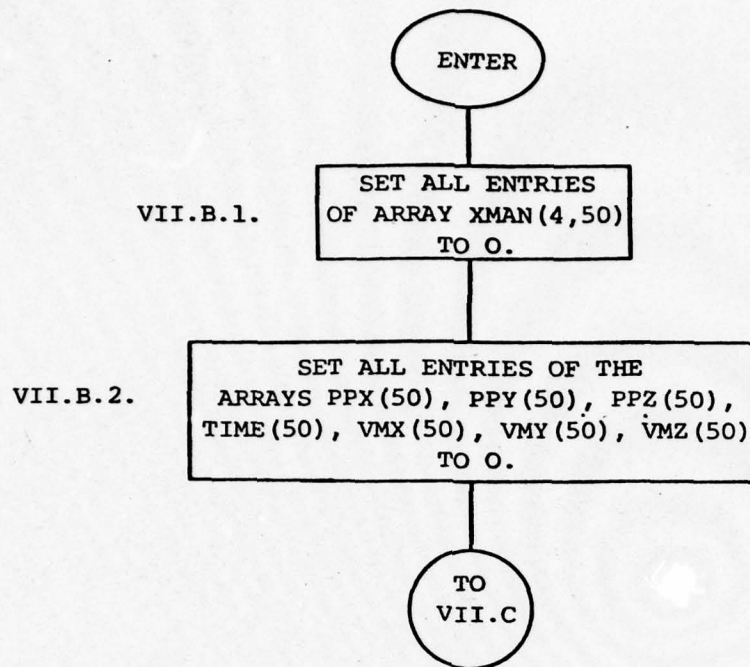
VI.H.
CALCULATE EARTH-TO-LAUNCH
TRANSFORMATION MATRIX



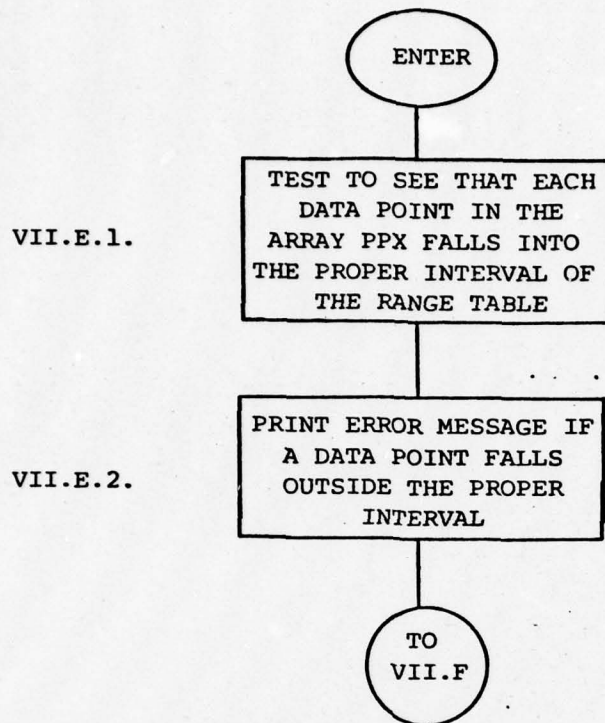
VI.K.
PREPARE TO
MAKE FLIGHTS



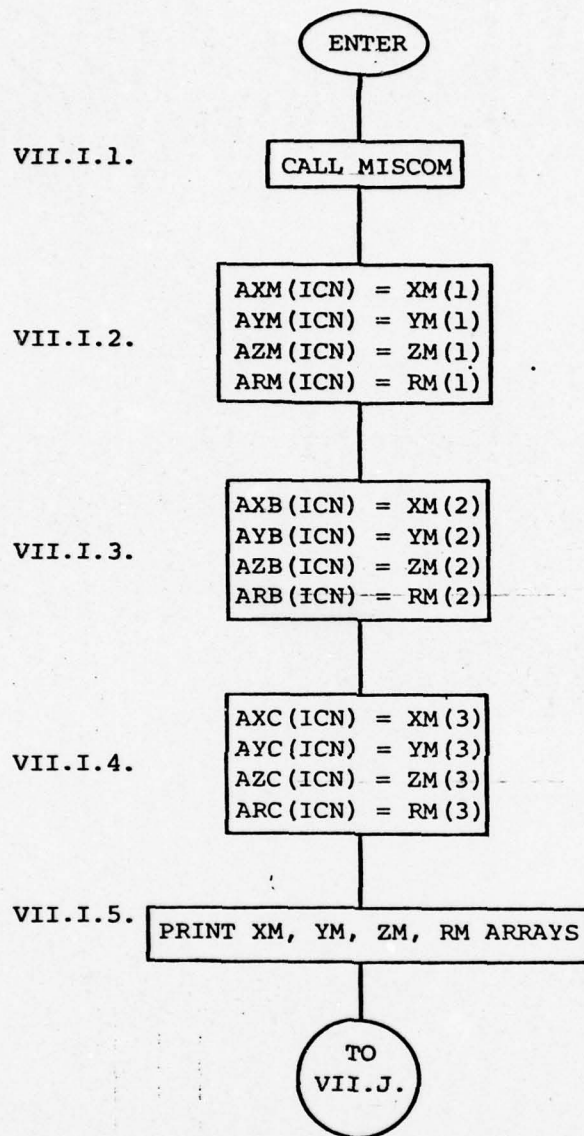
VII.B.
CLEAR STORAGE AREAS



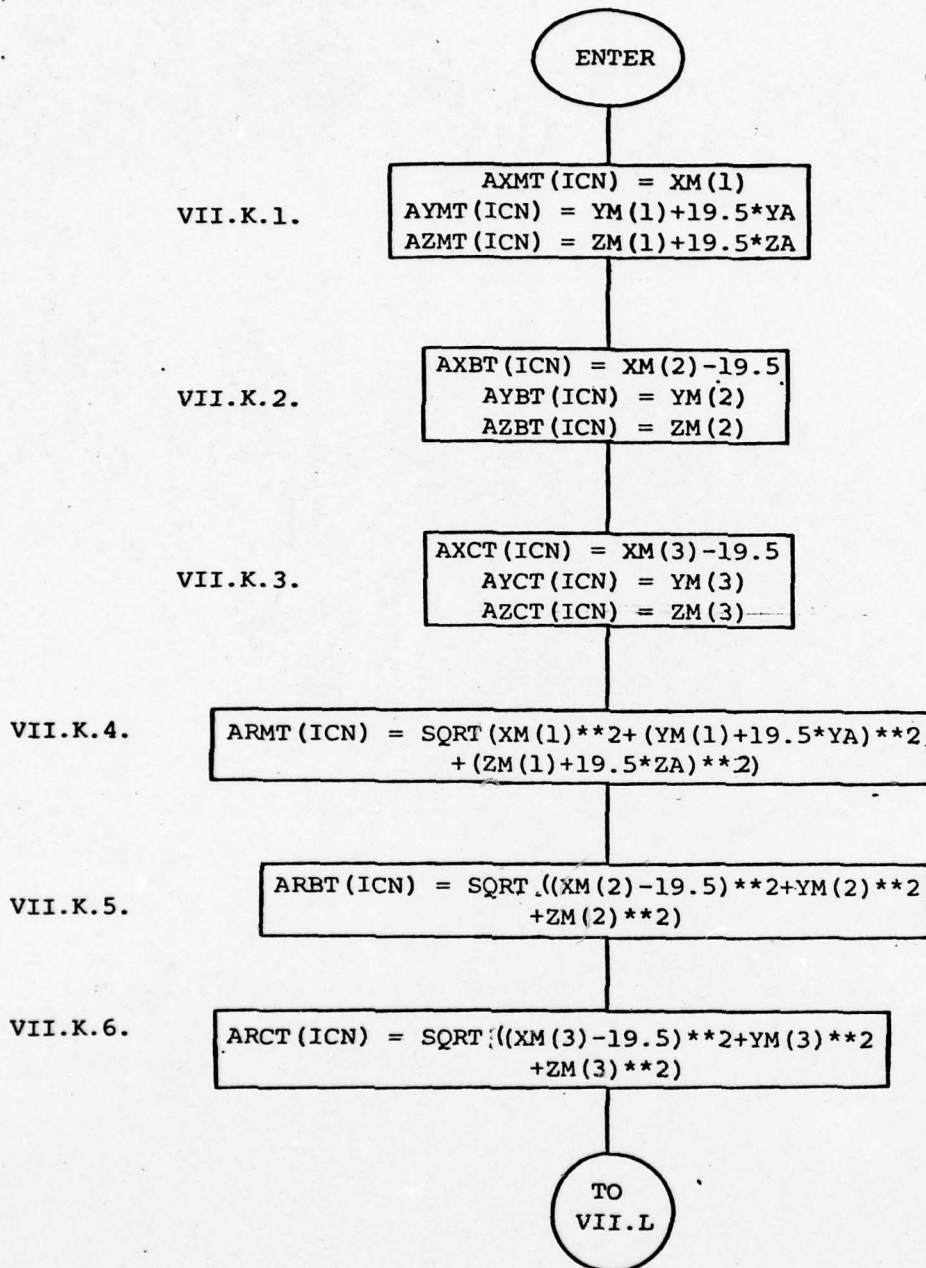
VII.E.
CHECK TIME CRITICAL
DATA COLLECTION



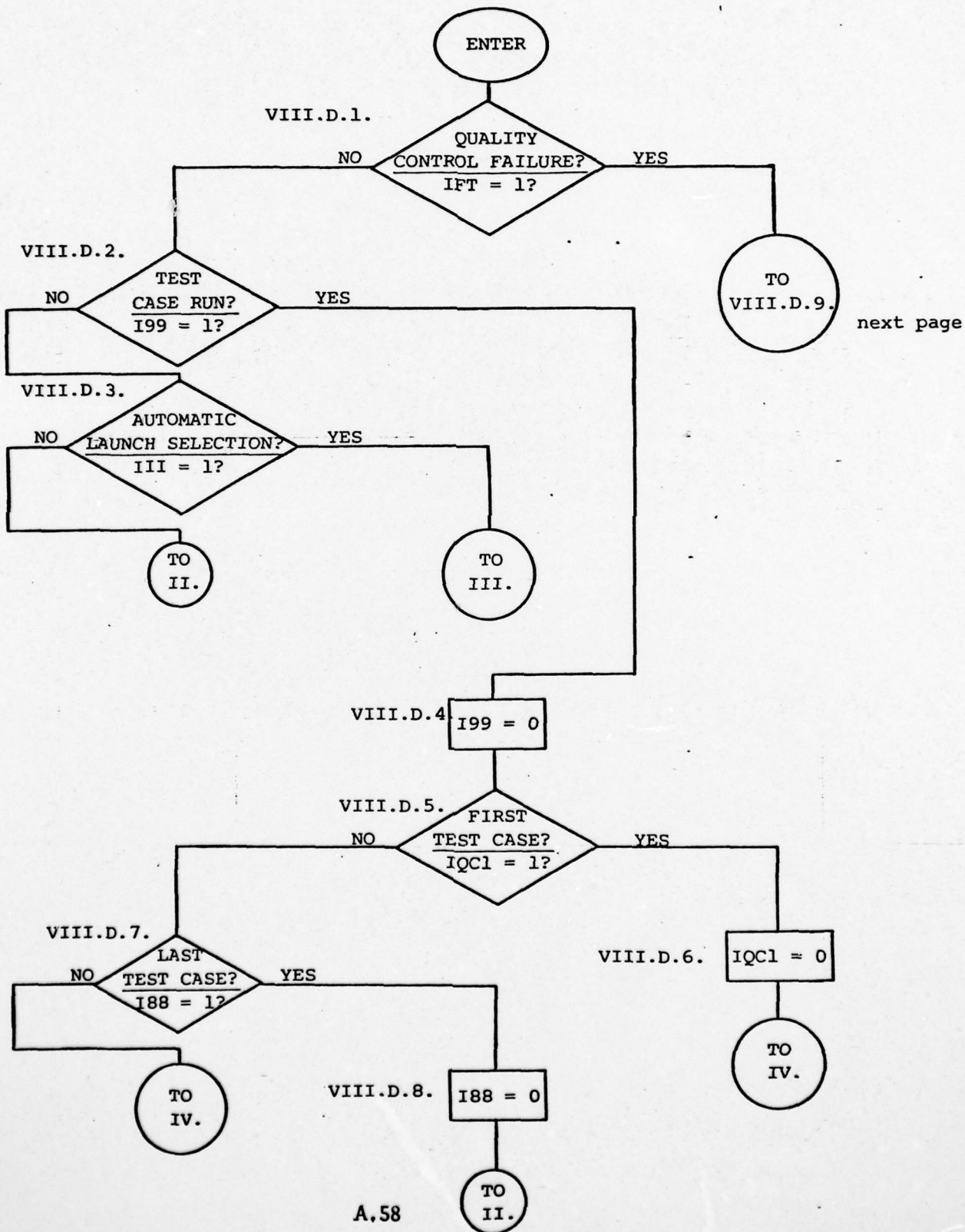
VII.I.
CALCULATE, SAVE AND PRINT MISS
DISTANCE DATA REFERENCED TO TAILPIPE



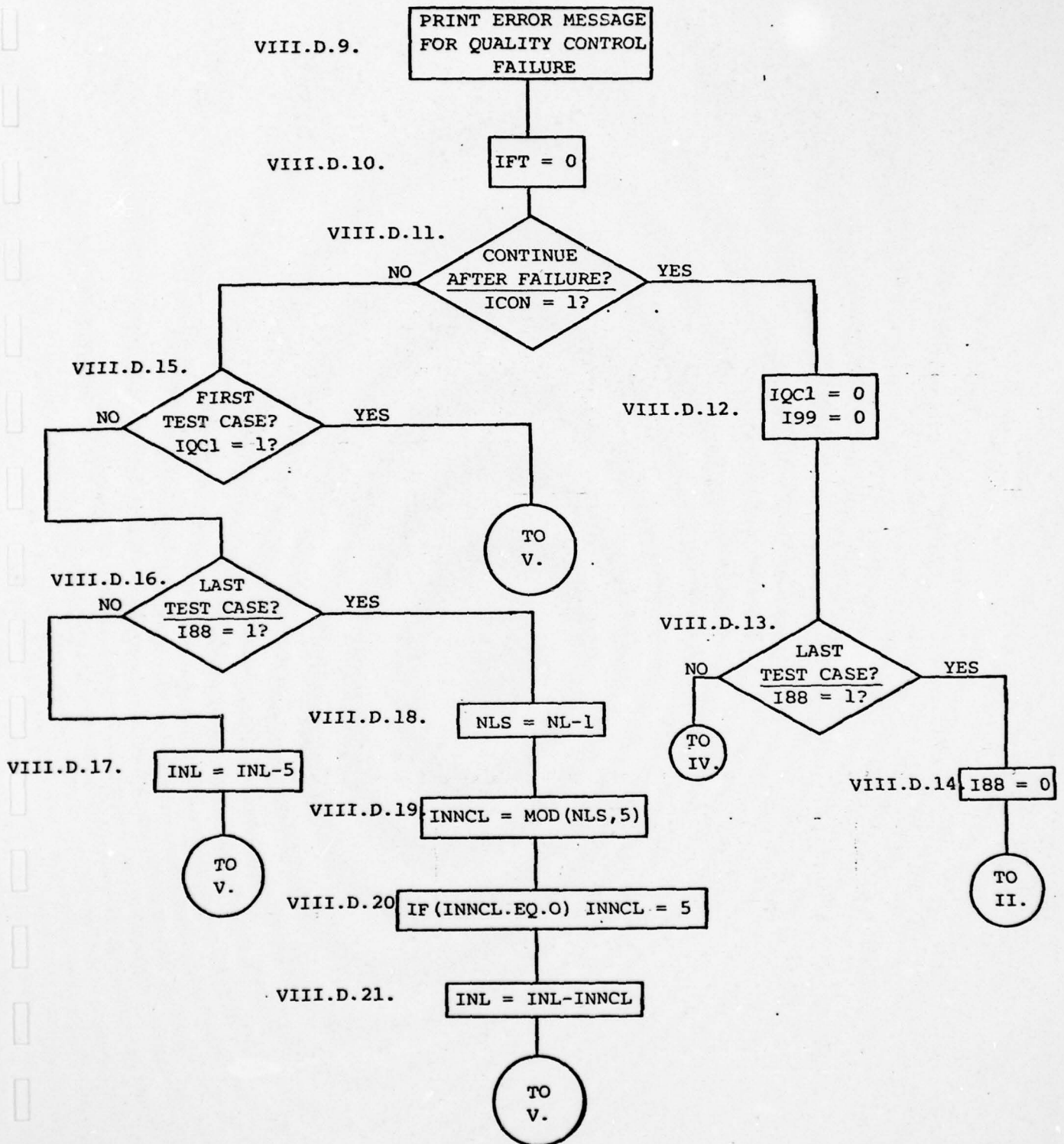
VII.K.
CALCULATE AND SAVE MISS DISTANCE
DATA REFERENCED TO CG



VIII.D.
 DECIDE WHERE TO TRANSFER CONTROL
 NEXT BASED ON MANUAL OR AUTOMATIC
 LAUNCH SELECTION, TEST CASE RUN, QUALITY
 CONTROL FAILURE, ETC.



VIII.D. (Continued)



AD-A052 676

B-K DYNAMICS INC ROCKVILLE MD
SUMMARY REPORT OF STINGER CONVERSION ACTIVITIES.(U)
JUL 76

F/G 9/2

DAAH01-75-C-0194

NL

UNCLASSIFIED

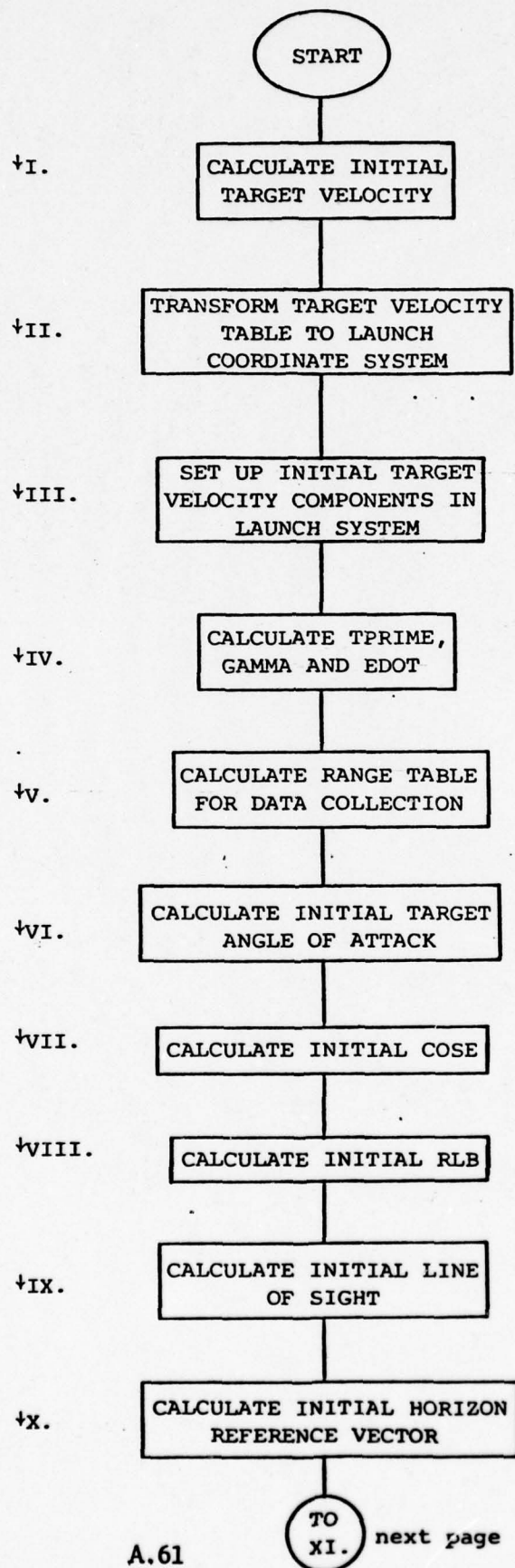
BKD-TR-3-206

3 of 4
AD
A052 676



SUBROUTINE INIT
FIRST LEVEL FLOW DIAGRAM

SUBROUTINE INIT



SUBROUTINE INIT (Continued)

↓XI.

CALCULATE INITIAL TARGET
CENTER LINE VECTOR

↓XII.

CALCULATE INITIAL PLUME
ROTATION ANGLE

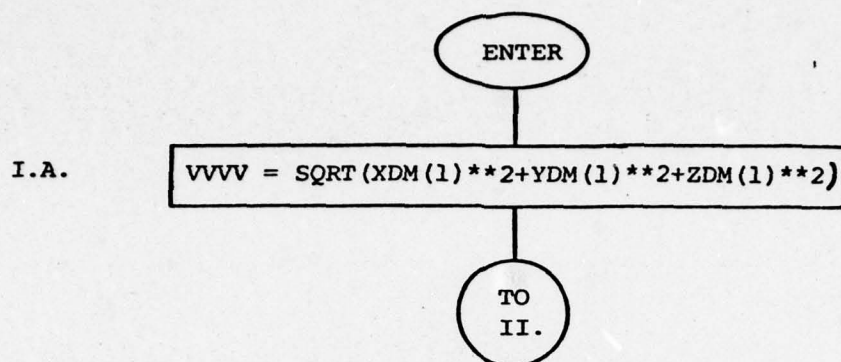
↓XIII.

CALCULATE INITIAL
IRIS RATIO 7

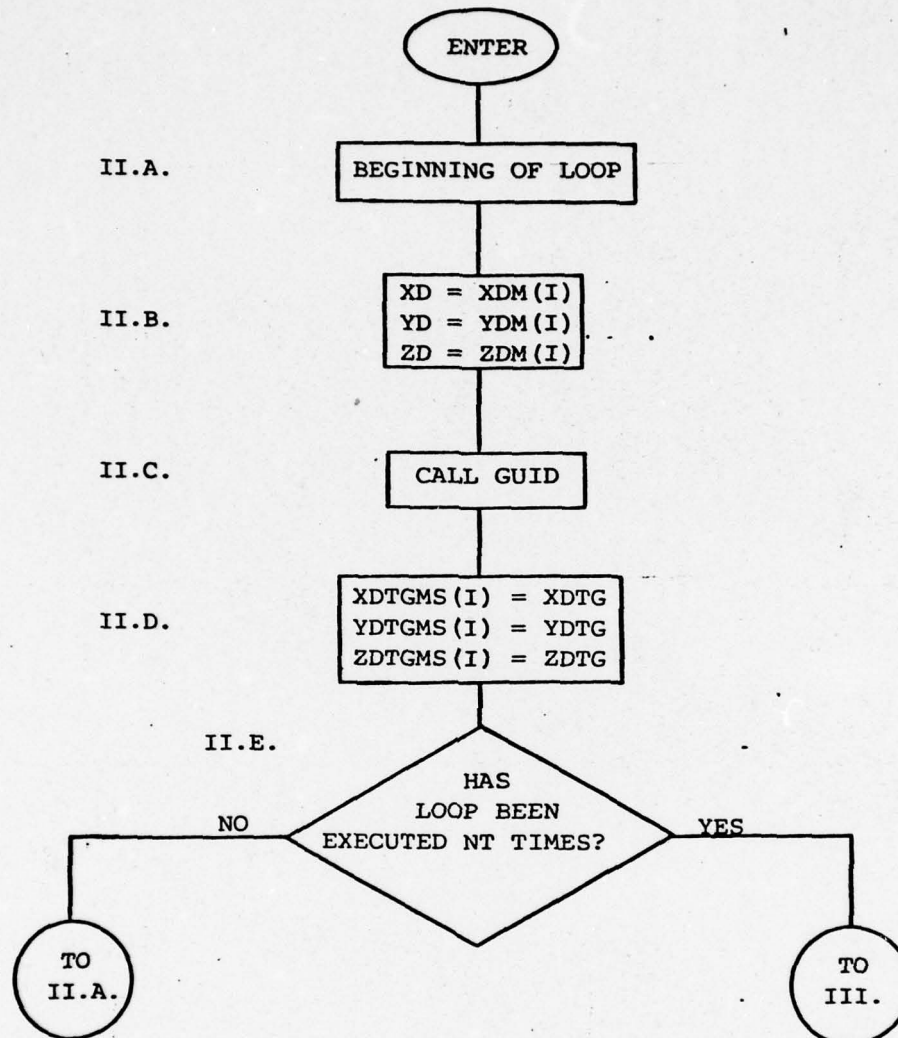
RETURN

SUBROUTINE INIT
SECOND LEVEL FLOW DIAGRAMS

I.
CALCULATE INITIAL
TARGET VELOCITY

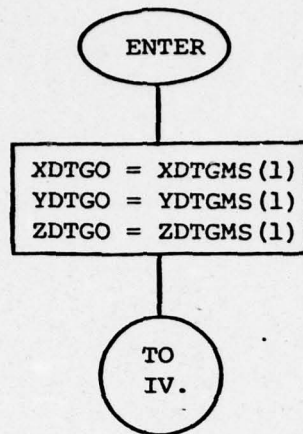


II.
TRANSFORM TARGET VELOCITY
TABLE TO LAUNCH
COORDINATE SYSTEM

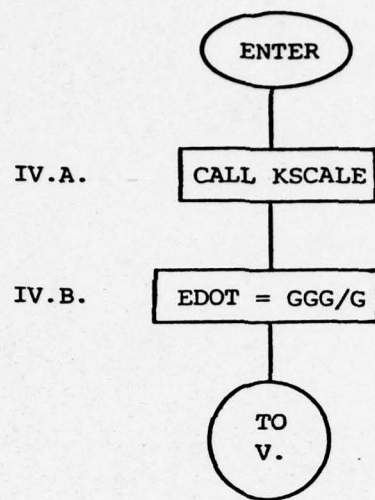


III.
SET UP INITIAL TARGET
VELOCITY COMPONENTS
IN LAUNCH SYSTEM

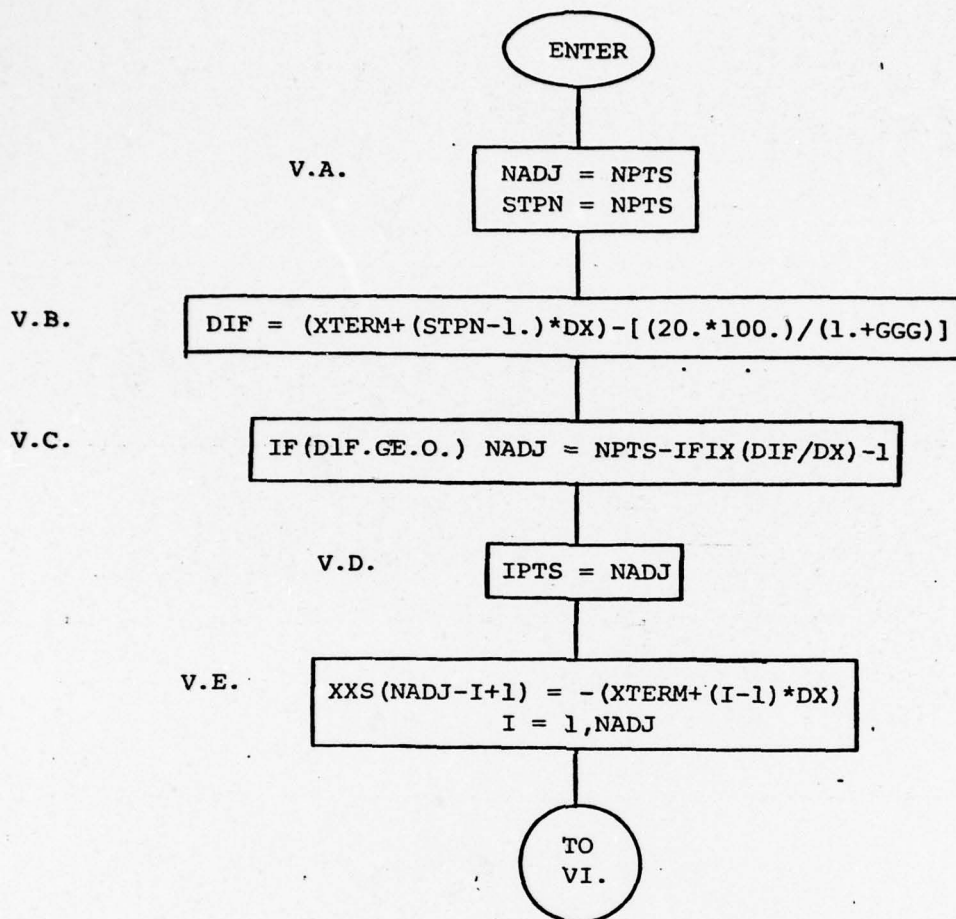
III.A.



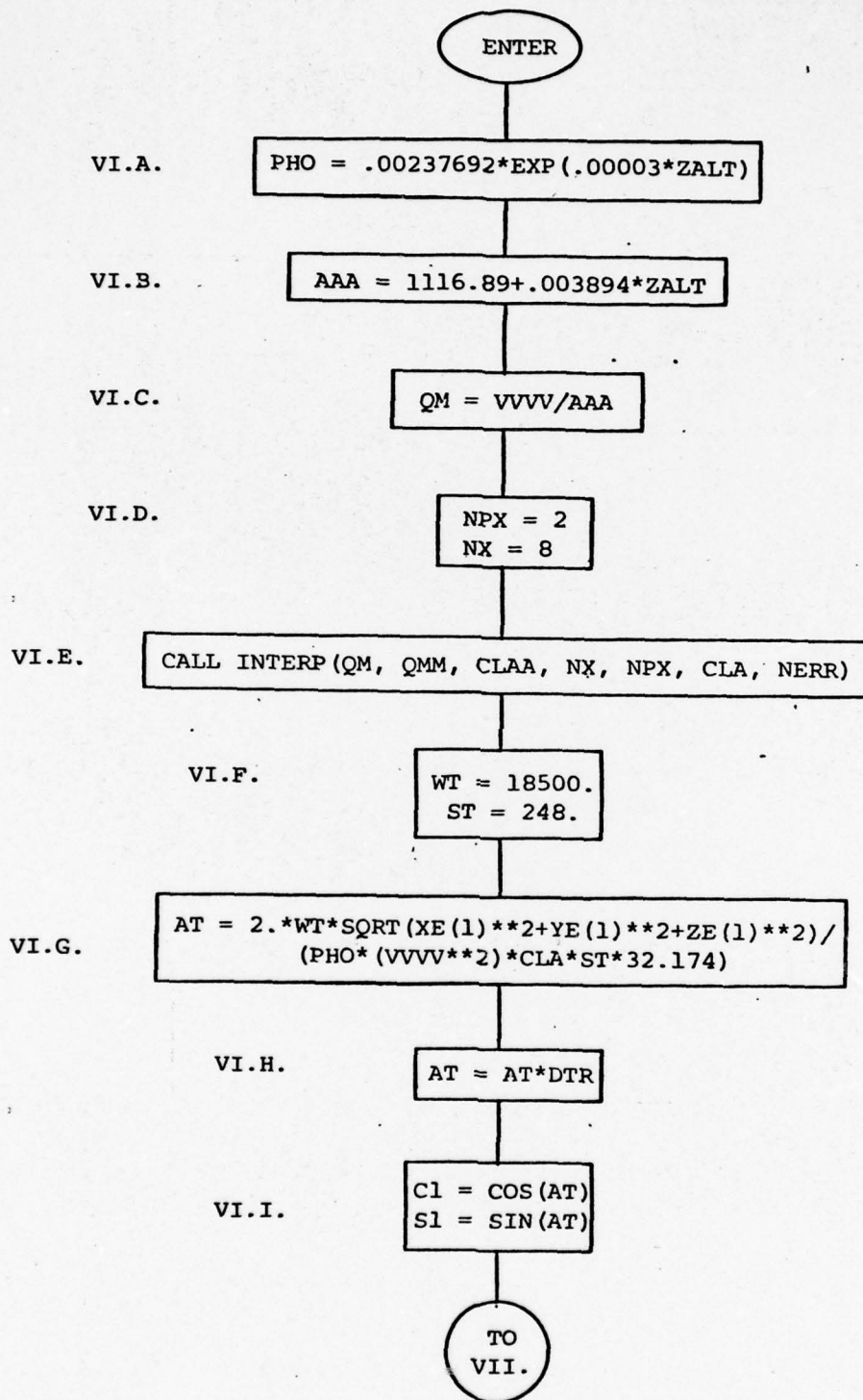
IV.
CALCULATE TPRIME,
GAMMA AND EDOT



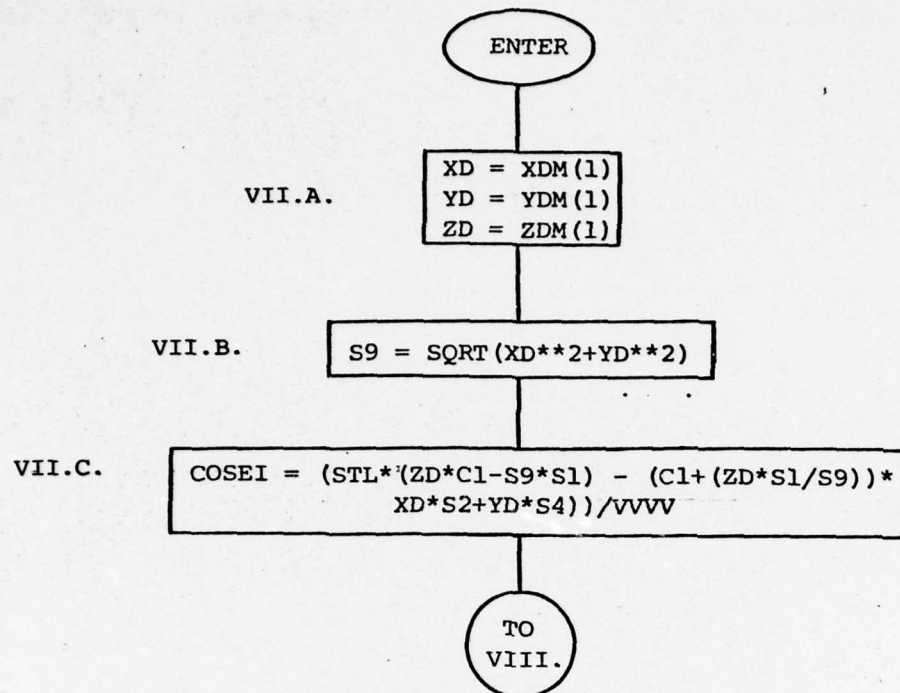
V.
CALCULATE RANGE TABLE
FOR DATA COLLECTION



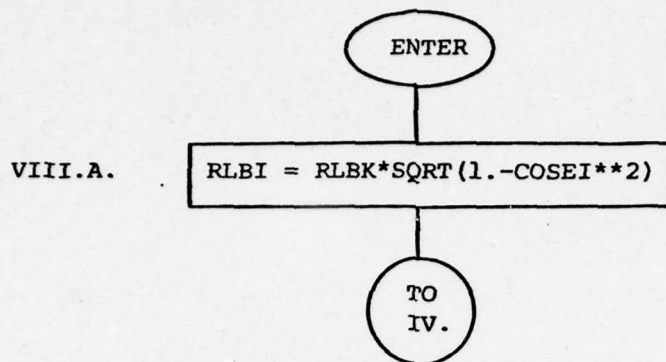
VI.
CALCULATE INITIAL TARGET
ANGLE OF ATTACK



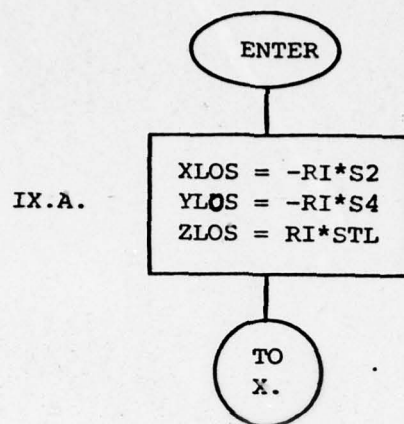
VII.
CALCULATE INITIAL COSE



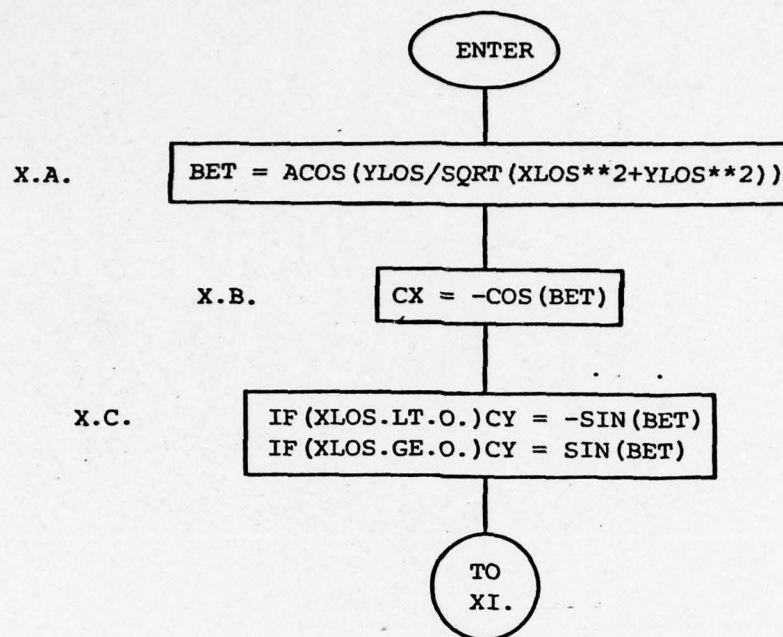
VIII.
CALCULATE INITIAL RLB



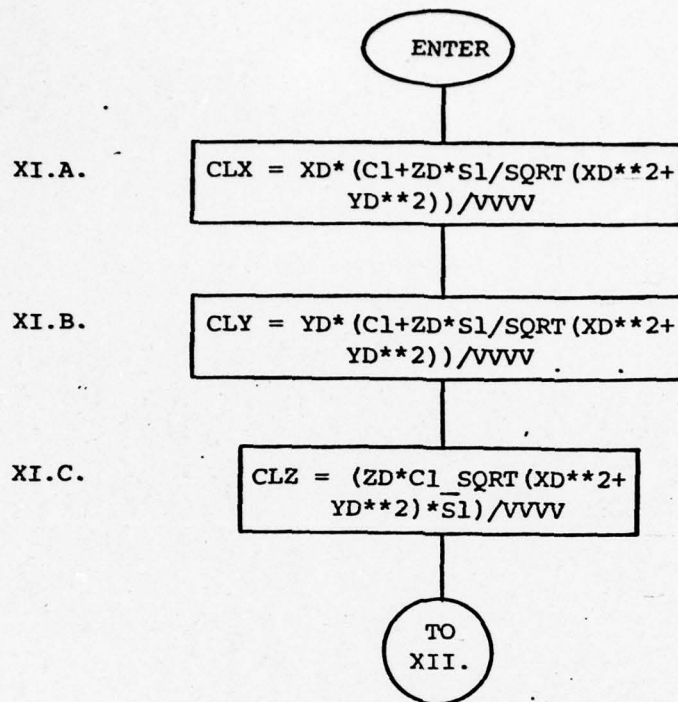
IX.
CALCULATE INITIAL
LINE OF SIGHT



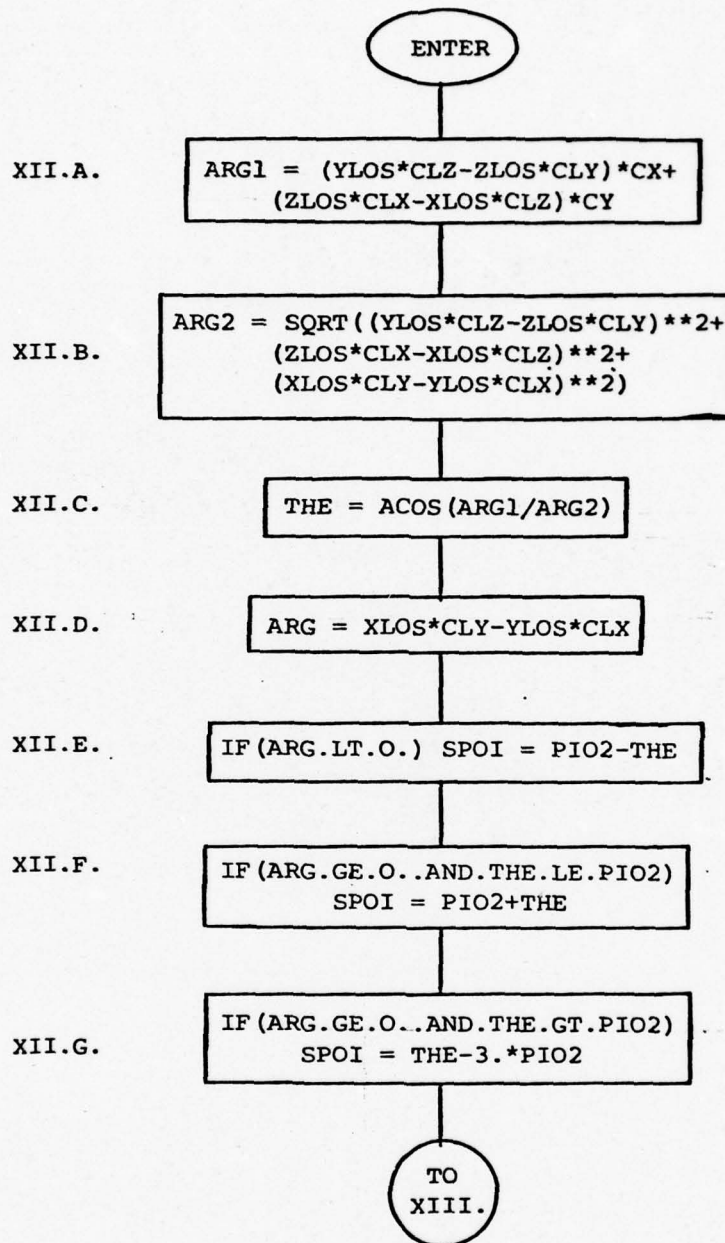
X.
CALCULATE INITIAL HORIZON
REFERENCE VECTOR



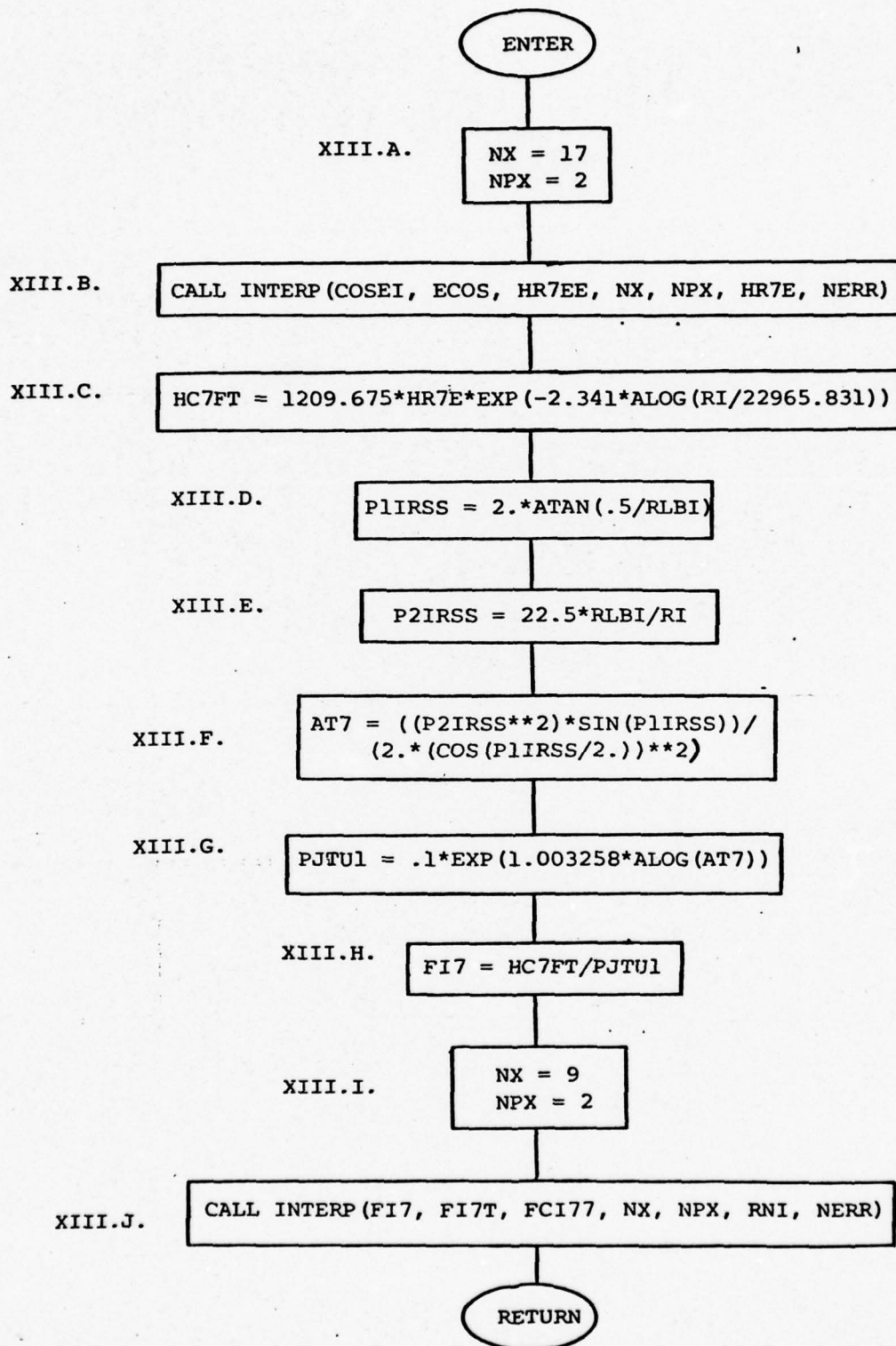
XI.
CALCULATE INITIAL TARGET
CENTER LINE VECTOR



XII.
CALCULATE INITIAL PLUME
ROTATION ANGLE



XIII.
CALCULATE INITIAL
IRIS RATIO 7



APPENDIX B. STRUCTURED MAIN AND SUBROUTINE INIT

DAOUT1,DAOUT2,DAOUT3,DAOUT4,DAOUT5,DAOUT6,

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PAGE 2

FINH 4.2+75348

01/12/76 14.30.11.

PROGRAM MAIN 74774 OPT=1

*DAOUT7,DAOUT9,DAOUT9,DAOUT10,DAOUT11

COMMON/DOIS2/IOUT

JAN,OFF

60

C***

C*** NEXT CARJ IS TAPE SPECIFIC FOR LAUNCH AT WSHR

DATA ZADOVE/-3999.7

DATA RTD-DTR/57.2957795,0.01745329/

DATA RTD-DTR/0.1,1.2,3.4,5.6,7.8,9,10,11,12,13,14,15,16,17,18,19,20,21,22,23,24,25,26,1

SCALE = 102.375

SCALE1 = 102.375 / 10.

SCALE2 = 200. * 102.375

SCALE3 = 20. * 102.375

SCALE4 = 6. * 1.02375

SCALE5 = 20. * 102.375

70

KASEO

RUK=3.3333

10 CONTINUE

READ(5,2000) ISI,NSAM,ICON,INL

PRINT 2012

PRINT 800

PRINT 2002, ISI,NSAM,ICON,INL

PRINT 300

DO 11 I=1,10

READ(5,620) CLMS(I),CLS1(I),CLS2(I)

PRINT 2005, CLMS(I),CLS1(I),CLS2(I)

11 CONTINUE

READ(5,621) Q1,Q2,Q3,Q4,Q5,Q6

PRINT 800

PRINT 2006, Q1,Q2,Q3,Q4,Q5,Q6

READ(5,621) W1,W2,W3,W4,W5,W6

PRINT 800

PRINT 2007, W1,W2,W3,W4,W5,W6

CALL SCLTN

READ(5,902) NRUNS

PRINT 800

PRINT 2010, NRUNS

IF (NRUNS.LE.20) GO TO 15

PRINT 302, NRUNS

NRUNS = 20

15 CONTINUE

READ(5,903) NPTS,DX,XTERM

PRINT 800

PRINT 2008, NPTS,DX,XTERM

C*** READ IN LAUNCH CONDITIONS. NL IS NUMBER OF LAUNCH SETS.

READ(5,902) NL

PRINT 800

PRINT 2011, NL

IF (NL.LE.61) GO TO 30

PRINT 823, NL

GO TO 3

30 CONTINUE

PRINT 800

IF (ISI.NE.1) PRINT 833

C*** READ AND PRINT LOADED LAUNCH CONDITION SETS.

NL=NL+1

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PAGE 3

01/12/76 14:30:11.

FINH 4.2475348

74774 OPT=1

PROGRAM MAIN

```
115 PRINT 800
DO 40 I=1,NLL
READ (5,904) ZTEO(I),ASC(I),RR(I)
ZTE = -ZTEO(I)
IF (IS1.NE.1) PRINT 835, I,ZTE,ASC(I),RR(I)
40 CONTINUE
3 CONTINUE
PRINT 807
NT=27
IQCIF=0
GO TO 42
C*** AUTOMATIC SELECTION OF LAUNCH CONDITIONS.
41 INL=INL+1
IFT=0
C INDEX FOR AUTO TEST CASE CHECK
63 I99=0
U77=FLOAT(INL)
U73=(U77-1.)/5.
I77=IFIX(U73)
U79=FLOAT(I77)
U80=U78-U79
C TEST FOR EVERY FIFTH LAUNCH SET
IF (U80.LT.0.01) I99=1
C TEST CASE CHECK REQUIRED AFTER LAST LAUNCH SET
IF (INL.EQ.1) I99=1
IF (INL.EQ.1) I0C1=1
C INDEX FOR OTHER RUNS
I88=2
C TEST FOR LAST TEST CASE CHECK
IF (INL.GT.NL) I88=1
C TEST CASE CHECK REQUIRED AFTER LAST LAUNCH SET
IF (INL.GT.NL) I99=1
IF (I99.EQ.1) GO TO 62
028 I88=1
KA=KASE
PRINT 918, KA
ITT=ITRAJ(INL)
PRINT 915,ITT
ITT=ITAU(INL)
PRINT 917,ITT
TAU=FLOAT(ITT)
GO TO 51
42 READ(5,2000) III,IRSS,KA,ITT,NOGO
PRINT 800
PRINT 2003, III,IRSS,KA,ITT,NOGO
READ(5,2001) T43
PRINT 830
PRINT 2004,TAU
IF (III.EQ.1) GO TO 41
53 CONTINUE
5 PRINT 800
23 CONTINUE
C*** LAUNCH CONDITIONS HAVE BEEN SELECTED.
62 CONTINUE
GO TO 51
PRINT 925
TAU=3.0
```

PROGRAM MAIN 7476 OPT=1 FTHH 4.2+75348 01/12/76 16.30.11. PAGE 4

C INDEX FOR TEST CASE DATA CARD OF LAUNCH CONDITIONS

KA=NL+1

C INDEX FOR TEST CASE TARGET MANEUVER

C*** NEXT CARD IS TAPE SPECIFIC FOR ITT=39 FOR TEST CASE MANEUVER

ITT=39

C*** ADJUST FOR TAU AND SCALE TARGET VELOCITY-TIME MANEUVER TABLE.

51 NTAU = INT(TAU) + 1

DO 25 I = NTAU, NT

K = I - NTAU + 1

THA(K)=THA(1)-TAU

THAS(K)=THA(K)

XOM(K)=XOM(1,ITT)

YOM(K)=YOM(1,ITT)

ZOM(K)=ZOM(1,ITT)

25 CONTINUE

KK=NT-INT(TAU)+1

DO 26 K=KK, NT

THA(K)=FLOAT(K)-1.

XOM(K)=XOM(NT,ITT)

YOM(K)=YOM(NT,ITT)

ZOM(K)=ZOM(NT,ITT)

26 CONTINUE

C*** GENERATE TARGET AERODYNAMIC ACCELERATION TABLE

XE(1)=XOM(2)-XOM(1)

YE(1)=YOM(2)-YOM(1)

ZE(1)=ZOM(2)-ZOM(1)-32.174

DO 31 I=2, NT

IV=I-1

XE(I)=XOM(I)-XOM(IV)

YE(I)=YOM(I)-YOM(IV)

ZE(I)=ZOM(I)-ZOM(IV)-32.174

31 CONTINUE

KASE=KA

ZET=ED(KASE)

ZZ=Z+ZABOVE

ZALT=ZZZ

AS=ASC(KASE)

QR=QR(KASE)

XO=XOM(1)

YO=YOM(1)

ZO=ZOM(1)

C CHECK FOR HELICOPTER

WVV=SQRT(XO*XO+YO*YO+ZO*ZO)

IF(WVV.LT.338.0) PRINT 199

C***

KK=0

IF(XD.EQ.0.0.AND.YD.EQ.0.0) GO TO 55

IF(YD.EQ.0.0.AND.ZD.EQ.0.0) GO TO 53

IF(XD.EQ.0.0.AND.YD.LT.0.0) GO TO 54

KK=1

SC=0.0

KSC=0.0

IF(ZD.EQ.0.0) GO TO 52

IF(ZD.GT.0.0) SED=90.*DTR

IF(ZD.LT.0.0) SED=-90.*DTR

PRINT 913

GO TO 56

PROGRAM MAIN 74774 OPT=1 FINH 6.2875368 01/12/76 16.30.11. PAGE 5

52 PRINT 914

230 SED=0.0

GO TO 60

53 BETA=90.

50 TO 55

54 BETA=270.

GO TO 55

55 BETA=ATAN2(YU,XO)*RTD

56 ASCO=AS*BETA-180.

IF(ASCO.GT.0) GO TO 60

ASCO=360.+ASCO

240 60 CONTINUE

SCO=ASCO*OTR

ARC=Z/R

50=ASIN(ARC)

THETA=SC*RTD

ASO=SO*RTD

X=R*COS(SO)*COS(SCO)

Y=R*CO.1301*SIN(SCO)

PRINT 309, ASCO,ASO,R

PRINT 912,X,Y,Z

250 C*** CALCULATE CONSTANTS FOR COORDINATE TRANSFORMATION

SINSO=SIN(SO)

COSCO=COS(SO)

SINSCO=SIN(SCO)

COSCO=COS(SCO)

S2=CJ30*COSJCO

S3=SINJ30*COSJCO

S4=COSJ30*SINSCO

S5=SINJ30*SINSCO

JL=SINSCO

CL=COSSCO

JL=JLMSO

CL=CLSSCO

CPL=COSSCO

C*** MAKE EARTH TO GUIDANCE TRANSFORMATION

CALL GUID

XUIGO = XUIG

YUIGO = YUIG

ZUIGO = ZUIG

C*** CALCULATE SCALE FACTOR EQUATION

91=R

CALL KSCALE,RETURNS1501

EDOT=GG/G

C*** READY TO MAKE FLIGHTS AND COLLECT POSITION POINTS

SPK=0.

SPHG=1.

SPHS=0.

SPHEJ.

H11=HQJMS

IF(1RSS.EQ.1) NRUNS=1RSS

IF(1RSS.EQ.1) NR=1RSS

IF(1RSS.EQ.1) T99=0

IF(199.EQ.1) NRUNS=NSAM+1

IF(199.EQ.1) NR=NRUNS

DO 150 I=1,NRUNS

CALL INIT

IF(151.EQ.1) PRINT 77,RN

245


```

ICN = 1
XMISS(7) = -77
C*** ZERO STORAGES AREA
DO 85 J=1,50
  DO 85 K=1,4
    XMAN(K,J) = 0.
85 CONTINUE
DO 90 J=1,50
  PPX(J) = 0.0
  PPZ(J) = 0.0
  TIME(J) = 0.0
  VMX(J) = 0.0
  VMY(J) = 0.0
  VMZ(J) = 0.0
90 CONTINUE
IPYS=NAOJ
LEVEL=-7
CALL FLIGHT
PRINT 2312
IF (ISL.EQ.1) GO TO 91
PRINT 999,RI,GAM,EDDT,XUTG3,YDTG3,ZDTG3,RN,RLB,SP3
PRINT 999,XCOMP,YCOMP,ZCOMP,G,GGG,XDO,YDO,ZDO,DXG,DYG
PRINT 999,DZG,S2,S3,S4,S5,RLBK,SCALEP,COSE,F1,F2
PRINT 999,F3,G1,G2,G3,XG,YG,ZG,S1,R3R,S3
PRINT 999,SP,CTL,STL,CPL,A1,VT1,ZALT,CLA,PHO,ARG
PRINT 999,AAA,SCALET,TREAL,XTA,YTA,ZTA,SCALEV,QM,S4,CA
PRINT 996,LEVEL,IPTS,NT,NERR,NPX,NX
PRINT 999,TRP,XLOS,YLOS,ZLOS,CO,CX,CY,CLY,CLZ,VVVV
PRINT 999,CCI,AS,SEO,SC,ASEO,R,SCALEL,THEIAL,THE
91 CONTINUE
NCP1 = NAOJ
C*** SCALE AND WRITE THE POSITION POINTS
IF (ISL.EQ.1) PRINT 808
IF (XMISS(7).GE.0.) PRINT 908, XMISS
IF (ISL.EQ.1) PRINT 809,ICN
IF (ISL.NC.1) PRINT 810,ICN
95 IF (IPIS.EQ.0) GO TO 150
DO 110 J=1,NAOJ
  PPXS(J)=PPX(J)
  PPYS(J)=PPY(J)
  PPZS(J)=PPZ(J)
  TIMES(J)=TIME(J)
  VMXS(J)=VMX(J)
  VMYS(J)=VMY(J)
  VMZS(J)=VMZ(J)
IF (ISL.EQ.1) GO TO 110
PRINT 111, PPXS(J),PPYS(J),PPZS(J),TIMES(J)
110 CONTINUE
C CHECK DIGITAL TIME CRITICAL DATA COLLECTION
NOA=NAOJ-1
UT 330-HEI,NOK
XCONE=XXIM
XCONE=PPXSIM
XCONE=XX(M+1)
IF (XCONE.LT.XCOLL.AND.XCOLL.LT.XCONE) GO TO 330
GO TO 329

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330 CONTINUE
XCOMH=XXINADJ
XCOLL=PPXS(NADJ)
345 XCDX=XXINADJ*DX
IF (XCOMH.LT.XCOLL.AND.XCOLL.LT.XCDX) GO TO 83
329 DO 331 M=1,20
331 PRINT 332
83 CONTINUE
IF (LEVEL.LI.0) GO TO 116
C*** SCALE AND WRITE THE MANOEUVRE DATA
IF (ISL.EI.1) GO TO 111
PRINT 907
355 111 CONTINUE
DO 114 J=1,NADJ
IF (ISL.EI.1) GO TO 114
PRINT 908, (XMANIK,J),K=1,4)
114 CONTINUE
IF (ISL.NE.1) PRINT 919,XD0,YD0,ZD0
116 CONTINUE
C*** NEXT CARD IS TAPE SPECIFIC FOR ITT-1 FOR STATIONARY TARGET
IF (ITT.NE.1.AND.LEVEL.EQ.0.AND.VVVV.GE.338.0) CALL PRIME
IF (LEVEL.NE.0) GO TO 150
365 C*** CALCULATE THE MISS-DISTANCE
CALL MISSCOM
PRINT 815
PRINT 813
DO 120 K=1,3
PRINT 814, XH(K),YH(K),ZH(K),RH(K)
120 CONTINUE
C*** SAVE THE MISS-DISTANCE DATA
AXH(ICN) = XH(1)
AYH(ICN) = YH(1)
AZH(ICN) = ZH(1)
ARH(ICN) = RH(1)
AXH(ICN) = XH(2)
AYH(ICN) = YH(2)
AZH(ICN) = ZH(2)
ARH(ICN) = RH(2)
AXH(ICN) = XH(3)
AYH(ICN) = YH(3)
AZH(ICN) = ZH(3)
ARH(ICN) = RH(3)
375 IF (VVVV.LT.338.0) GO TO 150
XHI(1)=XH(1)
YHI(1)=YH(1)+19.5*YA
ZHI(1)=ZH(1)+19.5*ZA
XHI(2)=XH(2)-19.5
YHI(2)=YH(2)
ZHI(2)=ZH(2)
XHI(3)=XH(3)-19.5
YHI(3)=YH(3)
ZHI(3)=ZH(3)
380 AXHI(ICN)=XHI(1)
AYHI(ICN)=YHI(1)
AZHI(ICN)=ZHI(1)
AXHI(ICN)=XHI(2)
AYHI(ICN)=YHI(2)
AZHI(ICN)=ZHI(2)
390
395

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```
400 AZBT(ICN)=ZMT(2)
    AXCT(ICN)=XMT(3)
    AYCT(ICN)=YMT(3)
    AZCT(ICN)=ZMT(3)
    DO 121 K=1,3
121 RMT(K)=SQRT(XMT(K)**2+YMT(K)**2+ZMT(K)**2)
    PRINT 800
    ARMT(ICN)=RMT(1)
    ARCT(ICN)=RMT(2)
    AZCT(ICN)=RMT(3)
    PRINT 815
    PRINT 813
    DO 122 K=1,3
122 RMT(K)=XMT(K),YMT(K),ZMT(K),RMT(K)
    CALL LEYH
125 C*** GO BACK FOR THE NEXT FLIGHT
150 CONTINUE
C*** AFTER FLIGHTS HAVE BEEN COMPLETED, CALCULATE MEAN AND STD DEV
    PRINT 815
    PRINT 830
    IPCANE0
    CALL MEAN (AXM,AYM,AZM,ARM,NRUNS,XM(1),YM(1),ZM(1),RM(1))
    PRINT 831
    CALL MEAN (AXB,AYB,AZB,ARB,NRUNS,XM(2),YM(2),ZM(2),RM(2))
    PRINT 832
    CALL MEAN (AXC,AYC,AZC,ARC,NRUNS,XM(3),YM(3),ZM(3),RM(3))
C*** GO BACK FOR THE NEXT SET OF FLIGHT CONDITIONS
    IF(VVVV.LT.338.0) GO TO 197
    PRINT 800
    PRINT 815
    PRINT 830
    IF(I99.EQ.1) IPLANE = 1
    CALL MEAN (AXMT,AYMT,AZMT,ARMT,NRUNS,XMT(1),YMT(1),ZMT(1),RMT(1))
    PRINT 831
    IF(I99.EQ.1) IPLANE = 2
    CALL MEAN (AXMT,AYMT,AZMT,ARMT,NRUNS,XMT(2),YMT(2),ZMT(2),RMT(2))
    PRINT 832
    IF(I99.EQ.1) IPLANE = 3
    CALL MEAN (AXMT,AYMT,AZMT,ARMT,NRUNS,XMT(3),YMT(3),ZMT(3),RMT(3))
    AASUM=SPHG/NR
    ABRUNS=SPHS/NR
    PRINT 102,ABRUNS,ABSUM,AASUM,AARUNS
445 197 CONTINUE
    NRUNS = N111
    RT = N111
    IF(IFT.NE.1) GO TO 602
    DO 530 I=1,10
530 PRINT 601
    IFT=3
    IF(ICOM.EQ.1) GO TO 635
503 CONTINUE
    IF(I101.EQ.1) GO TO 62
    IF(I183.EQ.1) GO TO 240
    INL=INL+4
```



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        GO TO 62
240 INCL=INC
241 INCL=INCL-5
        IF (INCL.GT.5) GO TO 241
188=0
        INCL=INCL-INCL
        GO TO 62
602 IF (IR9.NE.1) GO TO 627
        IF (IQ1.EQ.1) GO TO 626
        IF (IR8.EQ.1) GO TO 50
        GO TO 633
626 IQ1=0
        GO TO 633
627 IF (IR33.NE.1) GO TO 50
        GO TO 41
635 IQ1=0
        IF (IR8.EQ.1) GO TO 50
633 199=0
        GO TO 623
198 GO TO 50
200 CONTINUE
        IF (IR33.EQ.0) GO TO 300
        GO TO 3
490 201 PRINT 840
        77 FORMAT(10,10X,17H RANDOM NUMBER IS,E15.8)
        102 FORMAT(10,8H =,F6.4,3X,8H =,F6.4,3X,3H =,F6.4,
        *3X,8H =,F6.4)
        193 FORMAT(10X,37H TARGET IS ASSUMED TO BE A HELICOPTER)
        332 FORMAT(33H TIME CRITICAL DATA COLLECTION FAILURE.)
        500 FORMAT(10X,51H IF AUTOMATIC MODE SELECTION IS PLANNED, SELECT THE
        * 45H DESIRED STARTING LAUNCH SET NUMBER WITH SENSE
        * 10H SWITCHES./
        * 10X,52H IF MANUAL MODE SELECTION IS PLANNED, SENSE SWITCHES
        * 31H WILL BE IGNORED AT THIS POINT./
        * 10X,12H PUSH START./
        * 10X,12H PUSH START./
        601 FORMAT(10X,16H TEST BASE OUT OF LIMITS //)
        605 FORMAT(10X,49H IF COMPLETE PRINTOUT IS DESIRED, SELECT 1 WITH
        * 16H SENSE SWITCHES./
        * 10X,51H IF ONLY ESSENTIAL PRINTOUT IS DESIRED, SELECT 0
        * 23H WITH SENSE SWITCHES./
        * 10X,12H PUSH START./
        620 FORMAT(3F6.3)
        621 FORMAT(6F10.4)
        622 FORMAT(10X,49H SELECT THE QUALITY CONTROL TEST CASE SAMPLE SIZE
        * 21H WITH SENSE SWITCHES./
        * 10X,43H SAMPLE SIZE MUST BE IN RANGE 2 THROUGH 11.)
        623 FORMAT(10X,50H IF AUTOMATIC MODE SELECTION IS PLANNED, AND IT IS
        * 49H DESIRED TO CONTINUE IF A QUALITY CONTROL FAILURE
        * 8H OCCURS./
        * 10X,48H THEN SELECT 1 WITH SENSE SWITCHES. OTHERWISE,
        * 13H SELECT 2
        525 FORMAT(10X,16H TEST CASE :....//)
        540 FORMAT(10X,43H IF THIS IS A MICOM 4Y8RTJ/IR33 RUN, SELECT
        * 23H 1 WITH SENSE SWITCHES./
        * 10X,44H IF IT IS NOT, SELECT 2 WITH SENSE SWITCHES./
        * 10X,12H PUSH START./
        710 FORMAT(10X,46H SELECT TARGET TRAJECTORY WITH SENSE SWITCHES./

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* 10X,18H THEN PRESS START./
515 715 FORMAT(10X,20H TARGET TRAJECTORY *12,15H WAS SELECTED./
* 10X,32H IF THIS IS CORRECT, PUSH START./
* 10X,36H IF THIS IS WRONG, TURN SWITCHES OFF
* 16H AND PUSH START./
720 FORMAT(10X,49H SELECT POINT TAU ON TARGET TRAJECTORY AT TIME OF
* 16H MISSILE LAUNCH./10X,20H USE SENSE SWITCHES./
725 FORMAT(10X,64H TAJ = *12,39H WAS SELECTED. TO CONTINUE, SELECT 1
* 41H WITH SENSE SWITCH IF TAU=0 WAS SELECTED./
* 10X,52H IF TAU=0 WAS NOT SELECTED, LEAVE SENSE SWITCHES AS
* 3H THEY ARE./
* 10X,12H PUSH START./
525 800 FORMAT (140)
801 FORMAT(10X 50H SELECT THE LAUNCH CONDITIONS WITH SENSE SWITCHES./
* 10X 18H THEN PRESS START./
* 10X 50H TO END RUN, TURN ALL SWITCHES ON AND PRESS START )
530 802 FORMAT (10X 15, 39H IS TOO MANY RUNS. IT IS CHANGED TO 20 )
803 FORMAT(10X,18H LAUNCH CONDITIONS,15,4X,10H WERE SET./
* 10X 32H IF THIS IS CORRECT, PUSH START. /
* 10X 36H IF THIS IS WRONG, TURN SWITCHES OFF
* 16H AND PUSH START./
535 805 FORMAT(10X,13H PSI LAUNCH =F7.2,4H DEG,5X,15H THETA LAUNCH =F6.2,
* 4H DEG,5X,16H INITIAL RANGE =F9.2,3H FT)
809 FORMAT(10X,11H FLIGHT NO. 15)
810 FORMAT (5X 11H FLIGHT NO. 15,20X 14X 19X 14Y 19X 14Z 18X 5H TIME)
540 811 FORMAT(20X *4(5X F15.4))
813 FORMAT (10X 14H
12X 3H 2H )
814 FORMAT (24X 3(5X F10.2),E15.8)
815 FORMAT(10X,23H REFERENCED TO TAILPIPE)
816 FORMAT(10X,17H REFERENCED TO CG)
545 823 FORMAT (5X 15,5X 20H FOR NL IS TOO LARGE )
830 FORMAT (10X 10X 20H Y-Z PLANE - - - - )
831 FORMAT (10X 10X 20H X-Y PLANE - - - - )
832 FORMAT (10X 10X 20H X-Z PLANE - - - - )
833 FORMAT (10X 27H TABLE OF LAUNCH CONDITIONS 7777)
550 835 FORMAT(10X,5H SET 12,5X,11H ALTITUDE =F9.2,2X,3H FT,2X,
* 17H CROSSING ANGLE =F7.2,2X,4H DEG,2X,15H INITIAL RANGE =F10.2,
* 2X,3H FT)
840 FORMAT (10X 26H END OF RUN. SIGNING OFF. )
555 902 FORMAT(15)
903 FORMAT(10,2F10.0)
904 FORMAT(3F10.2)
907 FORMAT (10X 4X 35H TIME XD MANEUVER YD MANEUVER
15H ZD MANEUVER)
560 908 FORMAT(1X F10.4, 3(3X F8.2,5X))
909 FORMAT (5H X = F7.4,2X 5H Y = F7.4,2X 5H Z = F7.4,2X 8H XDOT =
F7.4,2X 8H YDOT = F7.4,2X 8H ZDOT = F7.4,8H MISS= E10.3)
912 FORMAT(10X,7H XICD =F10.2,3H FT,5X,7H VIL0 =F10.2,3H FT,5X,
* 7H ZICD =F10.2,3H FT)
555 913 FORMAT(10X,62H VERTICAL TARGET TRAJECTORY. CROSSING ANGLE IS NOT A
* PPLICATION.)
914 FORMAT(10X,53H STATIONARY TARGET. CROSSING ANGLE IS NOT APPLICABLE
*)
915 FORMAT(10X,94H PUSH ALL SENSE SWITCHES ON FOR AUTOMATIC OPERATION
* OR ELSE MANUAL OPERATION WILL BE SELECTED./10X,12H PUSH START./)
570 916 FORMAT(10X,13H TARGET TRAJECTORY ,12)

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```
917 FORMAT(10X,7M TAU = ,I2)
918 FORMAT(7//10X,5H SET ,I2)
919 FORMAT(10X,5HX00 = ,F10.4,5X,5HY00 = ,F10.4,5X,5HZ00 = ,F10.4)
995 FORMAT(15)
999 FORMAT(10(1X,E11.4))
2000 FORMAT(15)
2001 FORMAT(10.0)
2002 FORMAT (5X,6HISI = ,I5,5X,7HNSAM = ,I5,5X,7HICON = ,I5,5X,6HINL = ,I5)
2003 FORMAT (5X,6HIII = ,I5,5X,7HIXSS = ,I5,5X,5HKA = ,I5,5X,6HIII = ,I5)
2004 FORMAT (5X,6HTAU = ,F10.5)
2005 FORMAT (5X,7HCLYS = ,F10.5,5X,7HCLS1 = ,F10.5,5X,7HCLS2 = ,F10.5)
2006 FORMAT (5X,5HQ1 = ,F10.5,5X,5HQ2 = ,F10.5,5X,5HQ3 = ,F10.5,5X,5HQ4
1 = ,F10.5,5X,5HQ5 = ,F10.5,5X,5HQ6 = ,F10.5)
2007 FORMAT (5X,5HMI = ,F10.5,5X,5HM2 = ,F10.5,5X,5HM3 = ,F10.5,5X,5HM4
1 = ,F10.5,5X,5HM5 = ,F10.5,5X,5HM6 = ,F10.5)
2008 FORMAT (5X,7HNPIS = ,I5,5X,5HDX = ,F10.5,5X,6HXTERM = ,F10.5)
2009 FORMAT (5X,7HZTEC = ,F10.5,5X,6HASC = ,F10.5,5X,5HRR = ,F10.5)
2010 FORMAT (5X,6HNRUNS = ,I5)
2011 FORMAT (5X,5HNL = ,I5)
2012 FORMAT(1H)
300 STOP
END
```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
43.7 MAIN

VARIABLES		SN	TYPE	RELOCATION	COVA
10106	AARUNS	REAL			
10111	AGRUNS	REAL			
10463	ARB	REAL			ARRAY
10603	ARC	REAL			ARRAY
1620	ARG	REAL			COMA
11133	ARMT	REAL			ARRAY
10627	ASC	REAL			ARRAY
7	ASEO	REAL			EXTRA
11	AT	REAL			GTARG
11137	AX3Y	REAL			ARRAY
11277	AXCT	REAL			ARRAY
11037	AXMT	REAL			ARRAY
11203	AYBT	REAL			ARRAY
11323	AYCT	REAL			ARRAY
11063	AVMT	REAL			ARRAY
11227	AZBT	REAL			ARRAY
11347	AZCT	REAL			ARRAY
11107	AZMT	REAL			ARRAY
64	A1P1	REAL			COMP
74	A1P3	REAL			COMP
104	A1P5	REAL			COMP
53	A2P1	REAL			COMP
73	A2P3	REAL			COMP
103	A2P5	REAL			COMP
102	BDHX	REAL			PK
156	BDHZ	REAL			PK
1702	CA	REAL			COMA
1605	CLAA	REAL			COMA
15	CLSL	REAL			COMA
23	CLY	REAL			EXTRA
17	CO	REAL			EXTRA
1	COSB	REAL			COMD
2	COSG	REAL			COMD
1	COSJ	REAL			ANG
1441	JTL	REAL			COMA
21	CY	REAL			EXTRA
502160	DAOUT1	REAL			
502172	DAOUT11	REAL			
502162	DAOUT3	REAL			
502164	DAOUT5	REAL			
502166	DAOUT7	REAL			
502178	DAOUT9	REAL			
6144	DIR	REAL			
1261	DXG	REAL			COMA
1263	DZG	REAL			COMA
74	EDOT	REAL			COMA
2173	F171	REAL			ARRAY
3	FXB	REAL			GTARG
1	FYA	REAL			GTARG
7	FYC	REAL			GTARG
5	FZB	REAL			GTARG
1507	CL1	REAL			COMA
27	CL3	REAL			COMA
23	CL2	REAL			EXTRA
0	COS4	REAL			COMD
70	COS6	REAL			COMA
3	COS8	REAL			ANG
1443	SPL	REAL			COMA
20	CX	REAL			EXTRA
13	CI	REAL			EXTRA
502171	DAOUT13	REAL			
502151	DAOUT12	REAL			
502153	DAOUT4	REAL			
502165	DAOUT6	REAL			
502167	DAOUT8	REAL			
116J	DELTA	REAL			COMA
1	JX	REAL			EXTRA
1252	JYG	REAL			COMA
2131	CCS	REAL			COMA
2204	FC177	REAL			COMA
0	FXA	REAL			GTARG
6	FXC	REAL			GTARG
5	FYD	REAL			GTARG
2	FZA	REAL			GTARG

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
4567 MAIN

VARIABLES	SN	TYPE	RELOCATION	COMA
1621 1AA	REAL			
10107 1ASJH	REAL			
10110 1ASUM	REAL			
11253 1ASJ	REAL	ARRAY		
11273 1ACI	REAL	ARRAY		
10343 1AM	REAL	ARRAY		
4 AS	REAL	EXTRA		
10671 ASGO	REAL			
10674 ASO	REAL			
10337 AXB	REAL	ARRAY		
10507 AXG	REAL	ARRAY		
10247 AXH	REAL	ARRAY		
10413 AXB	REAL	ARRAY		
10533 AVC	REAL	ARRAY		
10273 AYH	REAL	ARRAY		
10437 AZ3	REAL	ARRAY		
10537 AZC	REAL	ARRAY		
10317 AZH	REAL	ARRAY		
1444 AI	REAL	COMA		
70 AIP2	REAL	COMP		
100 AIP4	REAL	COMP		
110 AIP5	REAL	COMP		
67 AIP2	REAL	COMP		
77 AIP5	REAL	COMP		
107 AIP6	REAL	COMP		
130 AIPY	REAL	PK		
10072 AETA	REAL	ARRAY		
1632 CLA	REAL	COMA		
4 QM3	REAL	ARRAY		
27 QLS2	REAL	EXTRA		
23 QLS2	REAL	EXTRA		
0 COSA	REAL	COMD		
70 COSB	REAL	COMA		
3 COS500	REAL	ANG		
1443 CPL	REAL	COMA		
20 CX	REAL	EXTRA		
13 CX	REAL	EXTRA		
502171 JAOUT10	REAL			
502161 JAOUT12	REAL			
502153 JAOUT14	REAL			
502165 JAOUT16	REAL			
502157 JAOUT18	REAL			
1150 JELI4	REAL	ARRAY		
1 JX	REAL	COMA		
132 JYG	REAL	EXTRA		
2131 JCS	REAL	COMA		
224 FCI77	REAL	ARRAY		
0 FX4	REAL	GTARG		
6 FXC	REAL	GTARG		
5 FYJ	REAL	GTARG		
2 FZA	REAL	GTARG		
10106 ARUNS	REAL			
10111 ARUNS	REAL			
10463 ARB	REAL	ARRAY		
10603 ARC	REAL	ARRAY		
1620 ARG	REAL	COMA		
11133 ARMT	REAL	ARRAY		
10627 ASC	REAL	ARRAY		
7 ASEO	REAL	EXTRA		
11 AI	REAL	GTARG		
11157 AX3T	REAL	ARRAY		
11277 AXCT	REAL	ARRAY		
11037 AXMT	REAL	ARRAY		
11203 AYBT	REAL	ARRAY		
11323 AYCT	REAL	ARRAY		
11063 AYMT	REAL	ARRAY		
11227 AZBT	REAL	ARRAY		
11347 AZCT	REAL	ARRAY		
11107 AZMT	REAL	ARRAY		
64 AIP1	REAL	COMP		
74 AIP3	REAL	COMP		
104 AIP5	REAL	COMP		
63 AIP1	REAL	COMP		
73 AIP3	REAL	COMP		
103 AIP5	REAL	COMP		
102 B0HX	REAL	PK		
156 B0HZ	REAL	ARRAY		
1702 CA	REAL	COMA		
1605 CLAA	REAL	COMA		
19 BL91	REAL	COMA		
22 BLV	REAL	EXTRA		
17 CD	REAL	EXTRA		
1 COSB	REAL	COMD		
2 COSG	REAL	COMD		
1 COS50	REAL	ANG		
1441 CIL	REAL	COMA		
21 CY	REAL	EXTRA		
502160 DAOUT1	REAL			
502172 DAOUT11	REAL			
502162 DAOUT13	REAL			
502164 DAOUT15	REAL			
502166 DAOUT17	REAL			
502170 DAOUT19	REAL			
6144 DTR	REAL			
1261 DXC	REAL	COMA		
1263 DZG	REAL	COMA		
74 E00T	REAL	COMA		
2473 FI7T	REAL	ARRAY		
3 FXB	REAL	GTARG		
1 FYA	REAL	GTARG		
5 FZB	REAL	GTARG		

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FINH 4.275348

74774 OPT=1

PROGRAM MAIN

VARIABLES	SN	TYPE	RELOCATION	1424	F1	REAL	COMA
10 FZC	10	REAL	GTARG	1425	F3	REAL	COMA
1254 G	1254	REAL	COMA	1427	G1	REAL	COMA
1255 JGG	1255	REAL	COMA	1431	G3	REAL	COMA
1430 G2	1430	REAL	COMA	10043	I	INTEGER	
2152 HRT5E	2152	REAL	ARRAY	504001	IADIN10	INTEGER	
504001 IADIN1	504001	INTEGER	COMA	504002	IADIN3	INTEGER	
504002 IADIN2	504002	INTEGER		504005	IADIN3	INTEGER	
504004 IADIN4	504004	INTEGER		504007	IADIN7	INTEGER	
504006 IADIN6	504006	INTEGER		504011	IADIN3	INTEGER	
504010 IADIN8	504010	INTEGER		60	ICON	INTEGER	COMP
15 IC4	15	INTEGER	MISO	10332	III	INTEGER	MANEUV
56 IFT	56	INTEGER	COMP	10042	INL	INTEGER	
514000 IIN	514000	INTEGER		516100	IOUT	INTEGER	
10112 IN3L	10112	INTEGER		1	IPTS	INTEGER	COMA
57 IPLANE	57	INTEGER	COMP	10061	IRSS	INTEGER	
10050 IQ31	10050	INTEGER		10236	ITAU	INTEGER	MANEUV
0 ISI	0	INTEGER	COMP	0	ITF	INTEGER	MANEUV
10142 IT-AJ	10142	INTEGER	ARRAY	10066	IV	INTEGER	
10057 IT1	10057	INTEGER	MANEUV	2	I88	INTEGER	COMP
10053 I77	10053	INTEGER		10100	J	INTEGER	
1 I93	1	INTEGER	COMP	10056	KA	INTEGER	
10054 K	10054	INTEGER		208	KILL	INTEGER	PK
10041 K43E	10041	INTEGER		3	KKK	INTEGER	EXTRA
10055 KK	10055	INTEGER		10102	V	INTEGER	
0 LEVEL	0	INTEGER	COMA	1601	NERR	INTEGER	COMA
10333 MADJ	10333	INTEGER	MANEUV	10045	NLL	INTEGER	
10045 NL	10045	INTEGER		10101	NOK	INTEGER	
10052 NOG3	10052	INTEGER		0	NPTS	INTEGER	EXTRA
14 NOPT	14	INTEGER	MISO	10035	NR	REAL	
1603 NPX	1603	INTEGER	COMA	41	NSAM	INTEGER	COMP
10044 NRJVS	10044	INTEGER		10063	NTAU	INTEGER	
1116 NT	1116	INTEGER	COMA	10077	V111	REAL	
1504 NX	1504	INTEGER	COMA	1817	PH8	REAL	COMA
832 H	832	REAL	PK	8	PPXS	REAL	DELT
77 HPX	77	REAL	ARRAY	62	PPYS	REAL	DELT
161 PPY	161	REAL	COMA	144	PPZS	REAL	DELT
243 PPZ	243	REAL	ARRAY	1665	QMH	REAL	COMA
1700 QM	1700	REAL	COMA	43	Q2	REAL	COMP
42 Q1	42	REAL	COMP	45	Q4	REAL	COMP
44 Q3	44	REAL	COMP	72	Q1	REAL	COMP
46 Q5	46	REAL	COMP	1422	RLBK	REAL	COMA
10 Q	10	REAL	EXTRA	11034	RMT	REAL	
67 RL3	67	REAL	COMA	10725	RQ	REAL	ARRAY
11 RM	11	REAL	MISO	6143	R7D	REAL	ARRAY
76 RM	76	REAL	COMA	10040	SCALE0	REAL	
1436 RRR	1436	REAL	COMA	1423	SCALEP	REAL	EXTRA
1701 SA	1701	REAL	COMA	1665	SCALEV	REAL	COMA
10036 SCALE	10036	REAL	EXTRA	10073	SC0	REAL	COMA
11 SCALEL	11	REAL	COMA	2	SINSC0	REAL	ANG
1612 SCLET	1612	REAL	EXTRA	10073	S0	REAL	
10037 SCLEZ	10037	REAL	COMA	240	SPHS	REAL	PK
5 SEC	5	REAL	EXTRA	1440	SPL	REAL	COMA
0 SI350	0	REAL	ANG	71	SPO	REAL	COMA
237 SP4C	237	REAL	PK				
236 SP4	236	REAL	PK				
241 SP4	241	REAL	PK				

VARIABLES	SN	TYPE	RELOCATION	65	ZDTGO	REAL	COMA
541, ZDTGMS	REAL	ARRAY	COMA	15	ZLOS	REAL	EXTRA
1542 ZE	REAL	ARRAY	COMA	15	ZLOS	REAL	EXTRA
6 ZM	REAL	ARRAY	MISO	11031	ZMT	REAL	ARRAY
10037 ZPTIME	REAL	MANEUV		1554	ZTA	REAL	COMA
10047 ZTE	REAL			10113	ZTEO	REAL	ARRAY
11 ZTZ	REAL	COMB					

FILE NAMES	MODE	0	INPUT	2041	OUTPJT	FMT	0	TAPES	FMT
4102 HFILE									
2041 TAPE0									

EXTERNALS	TYPE	ARGS	ATAN2	REAL	2	LIBRARY
ASIN	REAL	1	LIBRARY			
COS	REAL	1	LIBRARY			
GUID		0	INIT		0	
XSCALE		0	LETH		0	
NEAR		9	MISCOM		0	
PRIME		0	QCLIM		0	
SIN	REAL	1	LIBRARY			
	REAL		SQRT	REAL		1

INLINE FUNCTIONS	TYPE	ARGS	IFIX	INTEGER	1	INTRIN
FLCAT	REAL	1	INTRIN			
INT	INTEGER	1	INTRIN			

STATEMENT LABELS	0	5	INACTIVE	0	10	INACTIVE
4723 3						
0 11	4645	15			0 23	INACTIVE
0 25		0 25			4666 30	INACTIVE
0 31		0 40			4730 41	
5002 42	5020	50			5031 51	
5157 52	5173	53			5175 54	
5177 55	5203	56			5211 60	
5023 62		0 63	INACTIVE		7050 77	FMT
5502 83		0 85			0 90	
5377 31		0 95	INACTIVE		7099 102	FMT
5419 118	5507	111			5920 114	
5526 116		0 120			0 121	
0 122	5676	150			5762 197	
0 198	7065	199	FMT			INACTIVE
0 201	6004	240			0 200	
5040 300	5474	329			6006 241	
0 331	7073	332	FMT		5463 330	
7132 601	6013	602			7101 600	FMT NO REFS
0 659	7162	620	FMT		7137 603	FMT NO REFS
7156 622	7205	623	FMT NO REFS		7164 621	FMT
6021 626	6023	627			7232 625	FMT
0 630	6031	633			4764 626	
7236 640	7255	710	FMT NO REFS		6026 635	
7307 720	7323	725	FMT NO REFS		7267 715	FMT NO REFS
7352 801	7371	802	FMT		7350 800	FMT
7417 805	7432	809	FMT		7377 803	FMT NO REFS
7444 811	7447	813	FMT		7436 810	FMT
7461 815	7466	816	FMT		7456 814	FMT
7477 830	7504	831	FMT		7472 823	FMT
7516 833	7523	835	FMT		7511 832	FMT
7545 902	7547	903	FMT		7540 840	FMT
7554 907	7554	908	FMT		7552 904	FMT
					7570 909	FMT

STATEMENT LABELS

7604 912	FMT	7614 913	FMT	7624 914	FMT
7634 915	FMT NO REFS	7652 916	FMT	7656 917	FMT
7681 918	FMT	7664 919	FMT	7672 996	FMT
7674 999	FMT	7677 2000	FMT	7701 2001	FMT
7703 2002	FMT	7712 2003	FMT	7722 2004	FMT
7725 2005	FMT	7734 2006	FMT	7747 2007	FMT
7752 2008	FMT	7770 2009	FMT NO REFS	7776 2010	FMT
10001 2011	FMT	10004 2012	FMT		

COMMON BLOCKS LENGTH

COMA	1165
COMB	13
MANEUV	4316
GTARG	11
COMP	73
EXTRA	72
ANG	4
PK	162
MISO	14
DELT	300
COMU	5

STATISTICS

PROGRAM LENGTH	46378	2679
BUFFER LENGTH	45408	2400
CN LABELED COMMON LENGTH	137678	5135

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60	*-24.8,-215.4,-394.9,-553.8,-683.8,-778.3,-832.3,-843.-809.8, *734.5,-621.-475.2,-300.6,-118.2,74.6,263.338.590.3,711.8, *795.2/ DATAI2DEM(I,11)I=1,271/70.-191.4,-372.8,-536.8,-669.-768.4, *-827.8,-844.1,-816.5,-746.4,-637.6,-495.5,-327.6,-142.7,49.6, *239.4,416.6,572.3,698.1,787.6,836.2,861.2,802.4,722.603.9,454.4, *231.3/ DATAI2DEM(I,12)I=1,271/27*0.0/ DATAI2DEM(I,12)I=1,271/815.7,844.828.4,769.7,670.9,537.3,375.7, *134.5,2.-188.4,-369.9,-532.3,-667.-757.-827.1,-844.2,-817.3, *-748.-639.7,-498.1,-330.6,-145.9,46.4,236.3,413.8,569.9,696.3/ DATAI2DEM(I,12)I=1,271/210.6,28.-16.-347.4,-512.8,-651.5, *-726.3,-821.3,-844.5,-823.2,-759.2,-655.6,-517.9,-353.3,-170.3, *21.6,212.3,392.551.3,681.9,777.1,831.8,843.2,810.7,736.1,623.2, *677.8/ DATAI2DEM(I,13)I=1,271/70.-159.9,314.456.8,583.588.1,768.4, *820.8,843.5,835.8,797.3,730.9,637.6,521.2,385.9,236.7,78.9,-81.7, *-239.4,-388.4,-523.3,-639.4,-732.2,-798.6,-836.2,-843.4,-820.2/ DATAI2DEM(I,13)I=1,271/844.5,829.2,783.9,710.3,610.9,489.5,350.4, *198.5,39.5,-120.9,-277.-423.-553.8,-664.5,-751.1,-810.6,-840.8, *-840.5,-809.8,-749.9,-662.8,-551.7,-420.6,-274.4,-118.2,42.3, *281.2/ DATAI2DEM(I,13)I=1,271/27*0.0/ DATAI2DEM(I,14)I=1,271/0.-64.3,-128.2,-191.4,-233.4,-314.5, *-372.8,-429.4,-483.5,-534.8,-583.-627.8,-669.-706.3,-739.5, *-768.4,-792.8,-812.6,-827.8,-838.1,-843.5,-864.1,-839.8,-830.6, *-816.5,-797.8,-774.4/ DATAI2DEM(I,14)I=1,271/793.5,791.2,784.3,772.9,757.7,735.5,712.-, *583.3,650.6,614.1,574.1,530.7,484.3,435.3,383.2,339.2,273.3,215.8, *157.9,7.37.1,-23.3,-83.6,-14.5,-202.5,-260.3,-316.6/ DATAI2DEM(I,14)I=1,271/298.8,288.2,285.5,281.3,275.5,268.1,259.2, *246.7,236.8,223.5,209.1,193.2,176.3,158.3,139.5,119.8,99.5,78.5, *57.2,35.6,13.5,-8.5,-30.4,-52.2,-73.7,-94.7,-115.2/ DATAI2DEM(I,15)I=1,271/27*0.0/ DATAI2DEM(I,15)I=1,271/944.5,814.9,787.2,699.8,607.8,488.4,-24.8, *-246.4,-458.6,-522.9,-591.1,-656.3,-711.8,-768.3,-814.1,-860.1,-900.7,-951.7, *-363.7,-150.7,4.4,293.4,491.7,655.3,772.5,835.1,838.6,782.9,671.8/ DATAI2DEM(I,15)I=1,271/0.-222.6,-429.4,-605.8,-739.5,-820.8, *-844.1,-807.7,-714.2,-570.2,-385.9,-174.3,49.6,270.4,71.4,639.4, *762.1,331.7,841.2,791.9,686.5,532.7,734.1,1,125.5,-99.-316.6,-511.7/ DATAI2DEM(I,16)I=1,271/0.-64.3,128.2,191.4,253.4,314.372.8, *629.4,483.5,534.8,583.6,627.8,669.705.3,739.5,768.4,792.8,812.6, *827.8,833.1,843.5,844.1,839.8,830.6,816.5,797.8,774.4/ DATAI2DEM(I,16)I=1,271/793.5,791.2,784.3,772.9,757.7,735.5,712.-, *683.3,650.6,614.1,574.1,530.7,484.3,435.3,383.2,339.2,273.3,215.8, *157.9,7.37.1,-23.3,-83.6,-14.5,-202.5,-260.3,-316.6/ DATAI2DEM(I,16)I=1,271/288.8,288.2,285.5,281.3,275.5,268.1,259.2, *248.7,236.8,223.5,209.1,193.2,176.3,158.3,139.5,119.8,99.5,78.5, *57.2,35.6,13.5,-8.5,-30.4,-52.2,-73.7,-94.7,-115.5/ DATAI2DEM(I,17)I=1,271/27*0.0/ DATAI2DEM(I,17)I=1,271/444.5,839.322.5,795.3,757.7,710.3,653.5, *531.3,517.4,435.7,350.4,261.4,157.1,71.6,-24.8,-120.3,-215.5, *-337.2,-394.3,-477.4,-553.8,-622.9,-683.3,-735.9,-778.3,-810.6, *-832.3/ DATAI2DEM(I,17)I=1,271/0.-96.3,-191.4,-283.9,-372.8,-456.8, *-534.8,-605.3,-659.-723.4,-766.4,-803.3,-827.8,-841.4,-844.1, *-835.3,-816.5,-786.6,-746.5,-696.5,-637.6,-570.2,-495.5,-416.3,
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BUCK DATA ONE 74774 OPT=1 FINH 4.2475348 01/12/76 14.30.25. PAGE 3

115 *327.6,-236.7,-142.7/ DATAIDEM(I,18)I=1,271/70.0/ J

*768.4,-920.8,-843.5,-835.8,-797.8,-730.9,-637.6,-521.2,-385.9,
*236.7,-78.3,81.7,239.6,388.4,523.3,639.4,732.2,798.6,836.2,843.4,
*20.2/

120 DATAIDEM(I,18)I=1,271/784.5,829.2,783.9,710.3,610.9,489.5,350.4,
*193.5,39.5,-120.3,-277.8,-423.5,-553.8,-664.5,-751.1,-810.6,-840.8,
*840.5,-809.8,-749.3,-662.8,-551.7,-420.6,-276.4,-118.2,42.3,
*201.2/

125 DATAIDEM(I,18)I=1,271/727*0.0/ R
DATAIDEM(I,19)I=1,271/0.0,128.3,254.1,375.1,488.8,593.2,686.3,
*765.2,831.3,880.5,913.9,927.9,925.9,904.4,866.4,811.9,741.8,657.5,
*50.5,452.9,336.5,213.7,86.8,-41.7,-159.5,-294.5,-412.9/
DATAIDEM(I,19)I=1,271/872.9,864.5,839.6,798.5,742.3,671.7,588.3,
*493.5,380.4,277.8,150.9,40.8,-80.8,-199.2,-314.7,-424.1,-525.4,
*615.6,-396.1,-752.1,-813.6,-849.5,-859.1,-972.1,-858.2,-828.2,
*781.9/

130 DATAIDEM(I,19)I=1,271/317.7,314.7,305.6,290.7,270.2,244.5,214.1,
*179.7,141.7,101.1,58.6,14.9,-29.1,-72.5,-114.5,-154.4,-191.2,
*225.4,-253.3,-277.8,-296.1,-309.2,-316.3,-317.4,-312.4,-301.4,
*284.6/

135 DATAIDEM(I,20)I=1,271/0.0,-96.3,-191.6,-284.9,-375.1,-461.2, K
*542.3,-617.6,-686.3,-747.5,-800.7,-845.2,-880.6,-906.5,-922.7,
*928.8,-925.9,-911.2,-887.6,-854.3,-811.9,-760.7,-701.3,-634.3,
*560.5,-480.7,-395.6/

140 DATAIDEM(I,20)I=1,271/328.9,923.9,908.9,884.1,849.8,805.3,754.2, J
*593.8,626.5,551.5,471.3,385.4,295.6,202.7,107.6,11.3,-85.1,-180.6,
*274.1,-364.7,-451.3,-533.1,-609.1,-678.6,-740.7,-794.9,-840.4/
DATAIDEM(I,20)I=1,271/27*0.0/

END

BLOCK DATA ONE 74774 OPT=1 FTNH 4.2+75348 01/12/76 14.30.25. PAGE 4

SYMBOLIC REFERENCE MAP (R=1)

VARIABLES	SN	TYPE	RELOCATION						
1332	ITT	INTEGER	MANEUV	10236	ITAD	INTEGER	ARRAY	MANEUV	MANEUV
10142	ITPAJ	INTEGER	MANEUV	0	ITT	INTEGER	ARRAY	MANEUV	MANEUV
10333	HAJJ	INTEGER	MANEUV	10060	TIMES	REAL	ARRAY	MANEUV	MANEUV
1	KUCH	REAL	MANEUV	7723	XOTCH	REAL	ARRAY	MANEUV	MANEUV
10055	XPRIME	REAL	MANEUV	2507	YDEN	REAL	ARRAY	MANEUV	MANEUV
7751	YOTSM	REAL	MANEUV	10056	YPRIME	REAL	ARRAY	MANEUV	MANEUV
5215	ZJEM	REAL	MANEUV	10017	ZOTCM	REAL	ARRAY	MANEUV	MANEUV
13057	ZPRIME	REAL	MANEUV						

COMMON BLOCKS LENGTH
MANEUV 4316

STATISTICS
PROGRAM LENGTH 0
CM LABELED COMMON LENGTH 103348 4316

BLOCK DATA TWO 74774 UPI=1 PTNH 4.2475348 01/12/76 14.30.35. PAGE 3

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115 DATA(ZOEM(1,34),I=1,27)/27*262.3/
DATA(XDEM(1,35),I=1,27)/27*0.0/
DATA(YDEM(1,35),I=1,27)/1013.4,988.4,914.9,796.3,538.6,449.5,
*238.2,15.3,-208.3,-221.9,-514.6,-777.1,-901.4,-981.3,-1012.9,
*994.7,-927.6,-814.9,-562.1,-476.6,-267.8,-45.8,178.5,394.5,590.1,
*757.2,687.7/
120 DATA(ZOEM(1,35),I=1,27)/0.-223.4,-435.7,-626.7,-786.8,-908.2,
*985.1,-1313.2,-991.7,-921.4,-805.7,-650.4,-463.1,-273.9,-30.5,
*193.5,408.6,602.4,767.2,894.3,977.3,1012.3,997.5,933.6,823.8,
*873.5,749.2/
125 DATA(XDEM(1,36),I=1,27)/27*0.0/
DATA(YDEM(1,36),I=1,27)/1013.4,1008.8,995.9,972.3,940.7,900.6,
*952.3,794.3,733.1,683.3,587.4,506.2,420.4,330.8,238.2,143.5,
*47.4,-49.1,-145.1,-239.8,-332.4,-421.9,-507.6,-588.7,-664.5,
*734.3,-797.4/
130 DATA(ZOEM(1,36),I=1,27)/0.-196.4,-191.9,-285.6,-376.8,-484.6,
*548.1,-626.7,-699.5,-766.1,-825.8,-877.9,-922.2,-957.8,-985.1,
*1003.2,-1012.3,-1012.2,-1002.9,-984.6,-957.3,-921.4,-877.4,-824.8,
*765.1,-698.4,-625.4/
135 DATA(XDEM(1,37),I=1,27)/0.-128.4,254.6,376.8,492.9,601.1,699.6,
*786.3,861.4,922.9,967.9,998.1,1012.2,1010.1,991.7,957.3,907.5,
*831.7,652.1,574.7,573.5,463.1,345.2,221.8,94.7,-33.8,-161.8/
DATA(YDEM(1,37),I=1,27)/1013.4,1005.2,980.8,940.7,885.4,815.8,
*733.1,633.6,533.8,420.4,300.2,175.2,47.4,-81.2,-208.4,-332.4,
*451.1,-562.3,-654.5,-756.1,-835.4,-901.4,-952.8,-988.8,-1008.9,
*1012.9,-1000.4/
140 DATA(XDEM(1,37),I=1,27)/27*0.0/
DATA(YDEM(1,38),I=1,27)/1013.4,995.9,940.7,852.3,733.1,587.4,420.4,
*238.2,47.4,-145.1,-332.4,-507.6,-634.5,-797.4,-901.4,-972.7,
*1008.9,-1006.6,-971.8,-899.8,-795.3,-662.1,-504.8,-329.3,-141.8,
*50.7,1241.4/
145 DATA(ZOEM(1,38),I=1,27)/0.-191.9,-376.8,-548.1,-599.6,-825.8,
*922.1,-935.1,-1012.3,-1002.9,-957.3,-877.7,-765.1,-625.4,-483.1,
*284.1,-34.7,198.2,246.6,468.8,757.8,848.7,984.4,1003.4,1012.1,
*984.2/
150 DATA(XDEM(1,39),I=1,27)/27*0.0/
DATA(YDEM(1,39),I=1,27)/1013.4/
DATA(ZOEM(1,39),I=1,27)/27*0.0/
DATA(XDEM(1,40),I=1,27)/0.-64.3,-128.4,-191.9,-254.6,-316.4,
*376.3,-435.7,-432.9,-548.1,-601.1,-651.7,-699.6,-744.7,-786.8,
*825.8,-861.4,-893.5,-922.2,-946.9,-967.3,-985.1,-998.1,-1007.2,
*1012.3,-1013.2,-1010.1/
155 DATA(YDEM(1,40),I=1,27)/0.64,3,123.4,191.9,254.6,316.4,376.8,
*435.7,492.9,548.1,601.1,651.7,699.6,744.7,786.8,825.8,861.4,893.5,
*922.2,946.9,967.3,985.1,998.1,1007.2,1012.3,1013.2,1010.1/
DATA(ZOEM(1,40),I=1,27)/506.7,505.7,502.6,497.5,490.4,481.4,470.4,
*464.4,442.7,426.2,407.9,388.3,366.6,343.5,319.3,293.7,266.9,239.7,
*210.2,180.5,150.1,119.1,87.6,55.8,23.7,-3.5,-40.6/
160 DATA(XDEM(1,41),I=1,27)/0.64,3,123.4,191.9,254.6,316.4,376.8,
*435.7,492.9,548.1,601.1,651.7,699.6,744.7,786.8,825.8,861.4,893.5,
*922.2,946.9,967.3,985.1,998.1,1007.2,1012.3,1013.2,1010.1/
DATA(YDEM(1,41),I=1,27)/0.64,3,123.4,191.9,254.6,316.4,376.8,
*435.7,492.9,548.1,601.1,651.7,699.6,744.7,786.8,825.8,861.4,893.5,
*922.2,946.9,967.3,985.1,998.1,1007.2,1012.3,1013.2,1010.1/
165 DATA(ZOEM(1,41),I=1,27)/506.7,505.7,502.6,497.5,490.4,481.4,470.4,
*464.4,442.7,426.2,407.9,388.3,366.6,343.5,319.3,293.7,266.9,239.7,
*210.2,180.5,150.1,119.1,87.6,55.8,23.7,-3.5,-40.6/
170 DATA(XDEM(1,41),I=1,27)/27*0.0/
DATA(YDEM(1,41),I=1,27)/1013.4,995.9,940.7,852.3,733.1,587.4,420.4,
*238.2,47.4,-145.1,-332.4,-507.6,-634.5,-797.4,-901.4,-972.7,
*1008.9,-1006.6,-971.8,-899.8,-795.3,-662.1,-504.8,-329.3,-141.8,
*50.7,1241.4/

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BLOCK DATA TWO 74774 OPT=1 FTNH 4.275348 01/12/76 14.30.35. PAGE 1

*210.2.180.5.150.1.119.1.07.6.55.0.23.7.8.5.-40.6/
END

BLOCK DATA TWO 7976 OPT#1 FTNR 42279348 01/12/76 14.30.35. PAGE 3

SYMBOLIC REFERENCE MAP (R=1)

VARIABLES	SN	TYPE	RELOCATION
10332 ITI		INTEGER	MANEUV
10142 ITRAJ		INTEGER	MANEUV
10333 MADJ		INTEGER	MANEUV
10055 XPRIME	1	REAL	MANEUV
7761 YDIGH		REAL	MANEUV
5215 ZDEM		REAL	MANEUV
10057 ZPRIME		REAL	MANEUV
10235 ITAU		INTEGER	MANEUV
0 ITT		INTEGER	MANEUV
10060 TIMES		REAL	MANEUV
7723 XDTCH		REAL	MANEUV
2507 YDEM		REAL	MANEUV
10056 YPRIME		REAL	MANEUV
10017 ZDTCH		REAL	MANEUV

COMMON BLOCKS LENGTH
MANEUV 4316

STATISTICS

PROGRAM LENGTH 08
CH LABELED COMMON LENGTH 103348 4316

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BLOCK DATA THREE
COMMON/COMA/LEVEL,IPIS,XXS(50),XDTG0,YDTG0,ZDTG0,RLB,C0SE,SPO,RI,
*GAM,EDOT,THETA,RN,
5
  *PRX(50),PPY(50),PPZ(50),TIME(50),THAS(30),XDTGHS(30)
  *YDTGHS(30),ZDTGHS(30),XMAN(4,50),XMISS(7),NT
  *XCOMP,YCOMP,ZCOMP,TANA(30),DELTA(30),VM(30),G,GGG
  *XDO,YDO,ZDO,DYG,DYG,S2,S3,S4,S5,XDM(30),ZDM(30),
  *ZLBK,SCALEP,F1,F2,F3,G1,G2,G3,XC,XZ,ZG,S1,RRR,SR,SPL,CTL,STL,
  *CPL,A1,VII,XC(30),YE(30),ZE(30),ZALT,MERR,CLA,NPA,NX,CLAA(10),
  *PHO,ARG,AAASCALE,TREAL,TNA(30),XTA,YTA,ZTA,SCALEV,QMH(10),QM
  *SA,CA,VXX(50),VMY(50),VMZ(50)
  *ECOS(17),HQTEE(17),F17(9),FC177(9)
COMMON/PRK/XDH(22),YDH(22),ZDH(22),BDHX(22),BDHY(22),BDHZ(22)
*KL(22),PI(4),SPK,SPHG,SPHS,SPH
COMMON/MAHEUV/IT,XDEM(30,45),YDEM(30,45),ZDEM(30,45),
  *XDTG(30),YDTG(30),ZDTG(30),XPRIME,YPRIME,
  *ZPRIME,ITIME(50),ITRAJ(60),ITAU(60),III,NADJ
DATA(XDEM(1,42),I=1,27)/0.,-160.2,-316.4,-464.6,-601.1,-722.5,
  *825.8,-908.2,-967.9,-1003.2,-1013.2,-997.8,-957.3,-892.7,-805.7,
  *698.4,-573.5,-434.2,-284.6,-126.7,33.8,193.5,346.3,494.4,628.,
  *745.8,844.9/
DATA(YDEM(1,42),I=1,27)/1013.4,1000.6,962.7,900.6,815.8,710.6,
  *587.4,443.5,308.2,163.5,-16.9,-176.9,-332.4,-479.5,-614.6,-734.3,
  *835.4,-915.8,972.7,-1005.4,-1012.8,-994.7,-951.6,-884.6,-795.3,
  *686.,-559.5/
DATA(ZDEM(1,42),I=1,27)/27*0.0/
DATA(XDEM(1,43),I=1,27)/0.,191.9,376.8,548.1,699.6,825.8,922.,985.66
  *1012.3,1002.9,957.3,877.7,765.1,658.4,453.1,284.1,94.7,-98.3,-287.2
  *466.,-928.,-767.2,-878.7,-958.4,-1003.4,-1012.1,-984.2/
DATA(YDEM(1,43),I=1,27)/973.8,951.1,908.6,823.3,708.1,567.4,406.1,
  *230.1,45.8,-140.2,-321.1,-490.3,-641.9,-770.2,-870.6,-939.6,-974.5
  *974.2,-938.7,-869.2,-768.2,-639.5,-487.6,-318.,-137.,69.,233.2/
DATA(ZDEM(1,43),I=1,27)/262.3,257.5,243.5,220.6,189.7,152.,108.8,
  *51.7,12.3,-37.6,-86.,-131.4,-172.,-206.4,-233.3,-251.8,-261.1,
  *261.,-231.9,-248.9,-209.8,-171.3,-138.6,-48.2,-36.7,13.1,62.5/
DATA(XDEM(1,44),I=1,27)/27*0.0/
DATA(YDEM(1,44),I=1,27)/952.3,1005.2,1008.8,962.7,869.2,733.,
  *560.7,360.9,143.3,-81.4,-302.,-507.8,-638.6,-835.5,-941.4,-1000.9,
  *1011.2,-971.8,-884.5,-753.7,-585.9,-389.2,-173.4,50.9,272.7,
  *931.2,653.9/
DATA(ZDEM(1,44),I=1,27)/346.6,128.2,-96.6,-316.5,-520.9,-699.7,
  *846.1,-346.9,-1003.2,-1010.1,-967.3,-877.,-743.5,-573.4,-375.1,
  *158.4,66.1,287.4,434.5,677.3,826.8,935.5,998.4,1012.1,976.,891.9,
  *763.9/
45
DATA(XDEM(1,45),I=1,27)/27*0.0/
DATA(YDEM(1,45),I=1,27)/777*112.8/
DATA(ZDEM(1,45),I=1,27)/27*0.0/
DATA(CLAA(1),I=1,8)/0.043,0.0435,0.0455,0.0485,0.0515,0.0559,
  *0.3477,0.053/
DATA(CMH(1),I=1,8)/0.0,0.3,0.6,0.8,0.9,1.05,1.5,2.2/
DATA(ITANA(1),I=1,28)/0.,25.1,1.7,2.2,2.5,3.4,4.5,5.6,7.,
  *7.5,9.,9.5,10.,11.,11.5,12.,13.,14.,15.,16.,17.,18.,19.,
  *20./
DATA(CELTAR(1),I=1,28)/0.,31.2,44.5,6.1418,6.1978,1.2958,1.3945,6.,
  *3870.6,6405.6,7728.1,9559.,11368.1,12263.,13115.,14580.,
  *15193.,15738.,16733.,17218.,17660.,18505.,19295.,20038.,
  *20745.,21420.,22060.,22665.,23240./

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DATA (VM(I),I=1,28)/125.,.125.,.980.,.1800.,.1930.,.1990.,.1890.,.1850.,.1840.,.1820.,.1800.,.1780.,.1630.,.1300.,.1130.,.1070.,.960.,
* 900.,.870.,.820.,.760.,.725.,.699.,.560.,.620.,.590.,.560./

DATA (XDH(I),I=1,22)/13.50,0.9,-11.3,-16.8,-13.2,-1.5,-4.2,-15.3,
* 16.2,-20.3,-6.8,-19.4,-19.4,-19.8,3.4,-1.6,-5.6,-1.6,-16.7,-12.2,
* -16.3/

DATA (VDH(I),I=1,22)/12.0,-4.,.4,0.0,0.0,0.0,-9.3,9.0./

DATA (ZDH(I),I=1,22)/1.2,6.0,3.8,2.8,-.3,-.3,3.4,5.7,-.3,3.3,
* 3.0,-1.6,-1.6,-1.6,-1.6,-2.0,3.2,1.9,-.1/

DATA (QJHX(I),I=1,22)/76.5,12.5,6.5,5.2,7.2,8.6,8.3,1.8,1.5,2.5,
* 2.5,2.2,2.2,-2.1,3.1,3.1,3.1,3.3,1.3,6.2./

DATA (JDHY(I),I=1,22)/1.7,2.2,1.7,2.2,1.3,2.2,1.3,4.7,5.9,5.3,2.3,1.1,1.9,
* 2.2,2.2,1.1,6.6,1.6,5.8,9.3,6.1/

DATA (SDHZ(I),I=1,22)/72.5,12.2,8.2,3.2,7.1,6.3,3.3,2.2,3.2,3.2,
* 1.1,1.1,-9.6,-9.6,1.9,1.4,2.1/

DATA (XLLH(I),I=1,22)/74.1,10.1,8.0,1.5,0.1,5.9,1.1/

DATA (ECOSH(I),I=1,77)/-1.-,9848,-9397,-866,-7071,-5.-,-342,
* -1736,3.0,-1736,-5.,7071,-866,-9397,9848,-996,2.1/

DATA (HR7E(I),I=1,17)/5.3568E-10,5.4385E-10,5.7854E-10,3.7351E-10,
* 1.7736E-10,6.8327E-11,4.0449E-11,2.8362E-11,2.0376E-11,2.027E-11,
* 1.8444E-11,1.568E-11,1.184E-11,8.7428E-12,5.2709E-12,3.4869E-12,1.
* 8585E-12/

DATA (F17(I),I=1,91)/.18,-.332,-.612,-.737,-.833,.92,-.97,-.9999,1.0,000/

DATA (F517(I),I=1,91)/0.0,10.741,32.223
* ,42.368,53.705,64.446,64.75,187.80,559,
* 100.0/
END

SYMBOLIC REFERENCE MAP (R=1)

VARIABLES	SN	TYPE	RELOCATION	
1621 AAA	REAL	COMA	1620 ARC	REAL
1446 AI	REAL	COMA	102 3DHK	REAL
130 BUNY	REAL	ARRAY	156 3DHZ	REAL
1732 CA	REAL	COMA	1602 CLA	REAL
1605 CLAA	REAL	ARRAY	70 COSE	REAL
1443 CPL	REAL	COMA	1441 CTL	REAL
1150 JELIAR	REAL	ARRAY	1261 JXC	REAL
1252 JVG	REAL	COMA	1263 JZG	REAL
2131 E205	REAL	ARRAY	74 EDOF	REAL
2204 FO177	REAL	ARRAY	2173 F17T	REAL
1426 F1	REAL	COMA	1425 F2	REAL
1426 F3	REAL	COMA	1254 G	REAL
73 544	REAL	COMA	1255 GGG	REAL
1427 G1	REAL	COMA	1430 S2	REAL
1431 G3	REAL	COMA	2152 H7EE	REAL
10332 III	INTEGER	MANEUV	1 IPIS	INTEGER
10235 IIAJ	INTEGER	ARRAY	10142 ITRAJ	INTEGER
9 IIT	INTEGER	MANEUV	204 KILL	INTEGER
9 L2VEL	INTEGER	COMA	10333 NADJ	INTEGER
1601 NEAR	INTEGER	COMA	1603 NPX	INTEGER
1116 NT	INTEGER	COMA	1604 NX	INTEGER
232 P	REAL	ARRAY	1617 PHO	REAL
77 Ppx	REAL	ARRAY	161 PPY	REAL
243 Pp2	REAL	ARRAY	1700 3H	REAL
1635 Q41	REAL	ARRAY	72 3I	REAL
57 RL3	REAL	COMA	1422 RLK	REAL
76 RH	REAL	COMA	1435 RRR	REAL
1701 SA	REAL	COMA	1423 SCALEP	REAL
1622 SCALET	REAL	COMA	1665 SCALEV	REAL
217 3P45	REAL	PK	849 SPHG	REAL
216 3P45	REAL	PK	1548 SPL	REAL
241 3P41	REAL	PK	71 SPO	REAL
1437 SR	REAL	COMA	1442 STL	REAL
1435 S1	REAL	COMA	1264 S2	REAL
1255 S3	REAL	COMA	1266 S4	REAL
1237 S5	REAL	COMA	1122 TANA	REAL
75 THETAL	REAL	COMA	325 TIME	REAL
10050 TIMES	REAL	ARRAY	1624 TNA	REAL
407 TMA5	REAL	ARRAY	1623 TREAL	REAL
1216 VM	REAL	ARRAY	1703 VMX	REAL
1765 VNY	REAL	ARRAY	2047 VMZ	REAL
1445 VTI	REAL	COMA	1432 XC	REAL
1117 XCO4P	REAL	COMA	1 XDER	REAL
9 XOH	REAL	ARRAY	1270 XDM	REAL
1256 XDJ	REAL	COMA	7723 XOTGM	REAL
445 XOTGMS	REAL	ARRAY	64 XOTGO	REAL
1446 XE	REAL	ARRAY	577 XMAN	REAL
1107 XMI55	REAL	ARRAY	10055 XPRIME	REAL
1632 XTA	REAL	COMA	2 XXS	REAL
1433 YC	REAL	COMA	1120 YCOHP	REAL
2537 YCE4	REAL	ARRAY	26 YOH	REAL
1326 YJ4	REAL	ARRAY	1257 YDO	REAL
7751 YOTGM	REAL	ARRAY	503 YOTGMS	REAL
55 YOTGO	REAL	COMA	1504 YE	REAL

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BLOCK DATA THREE				74774	OPT=1	FINH 4-2875348	01/12/78	14-30-00-	PAGE
RELOCATION									
VARIABLES	SN	TYPE	REAL	MANEUV	1663	YTA	REAL	COMA	
10056	YPRIME	REAL	REAL	COMA	1434	ZC	REAL	COMA	
1600	ZALT	REAL	REAL	COMA	5215	ZDEM	REAL	COMA	
1121	ZCOMP	REAL	REAL	COMA	1354	ZDM	REAL	COMA	
54	ZCH	REAL	REAL	COMA	10017	ZDTCH	REAL	COMA	
1250	ZOO	REAL	REAL	COMA	66	ZDTGO	REAL	COMA	
541	ZDTGMS	REAL	REAL	COMA	10057	ZPRIME	REAL	COMA	
1542	ZE	REAL	REAL	COMA					
1664	ZTA	REAL	REAL	COMA					
COMMON BLOCKS									
COMA	1165								
PK	152								
MANEUV	4316								
STATISTICS									
PROGRAM LENGTH	DB	0							
CM LABELLED COMMON LENGTH	132138	5643							

SUBROUTINE INIT 74774 OPT=1 FINH 4.275348 .01/12/76 14.30.45. PAGE 1

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SUBROUTINE INIT
COMMON/EXTRA/NPTS,DX,XTERM,KKK,AS,SEO,SC,ASEO,R,SCALEL,VVVV,C1,
*XLCS,YLOS,ZLOS,CJ,CX,CY,CLZ,TRP,XX(50),THE
COMMON/CDMA/LEVEL,IPTS,XXS(50),XDY(50),YDTG,ZDTG,RLB,COSE,SP0,RI,
*GAN,EDOT,THEVAL,RN,
*PPX(50),PPY(50),PPZ(50),TIME(50),THAS(30),XDTGMS(30)
*YDTGMS(30),ZDTGMS(30),XMAN(4,50),XMISS(7),NI
*XCMP,VCOMP,ZCOMP,TAVA(30),DELTA(30),VM(30),G:GGG
*XXO,YJO,ZJO,DXG,DYG,DZG,S2,S3,S4,S5,XDM(30),YDM(30),ZDM(30),
*RLUK,SCALEP,FI,FZ,FS,G1,G2,G3,XG,YG,ZG,SI,RRR,SR,SPL,CIL,STL,
*CPL,A1,VII,XE(30),YE(30),ZE(30),ZALT,NERR,CLA,NPX,NX,CLAA(10),
*PRQ,ARG,AAA,SCALET,TREAL,TMA(30),XTA,YTA,ZTA,SCALEV,QMH(10),QH
*SA,CA,VXX(50),VAY(50),VMZ(50)
*ECSS(17),NRTEE(17),F17(19),FCI77(9)
COMMON /COM3/XD,YD,ZD,XDTG,YDTG,ZDTG,XDEF,YDEF,ZDEF,ZZZ
*XDCE,YDCE,ZDCE
COMMON/COMP/TS1,I99,I88,CLMS(10),CLS1(10),CLS2(10),NSAM,Q1,Q2,Q3,
*Z4,Q5,Z6,W1,W2,W3,W4,W5,W6,IET,IPLANE,ICON,S2P1,A2P1,A1P1,
*S2P2,S1P2,A2P2,A1P2,S2P3,S1P3,A2P3,A1P3,S2P4,S1P4,A2P4,A1P4,S2P5,
*S1P5,A2P5,A1P5,S2P6,S1P6,A2P6,A1P6
COMMON/MAHEUW/ITT,XDEM(30,45),YDEM(30,45),ZDEM(30,45),
*XDTG(30),YDTG(30),ZDTG(30),ZDTGM(30),XPRI,YE,YPRIME,
*ZPRIME,IMES(50),ITRAJ(60),ITAU(60),IIII,NAOJ
COMMON/GTARG/FAFYA,FZ,FY,FZB,FZC,FYC,FZC,AT,VI
DATA RTD,DTR/57.2957795,0.0174532/
C*** GENERATE THE DISTANCE TABLE FOR COLLECTING DATA POINTS
SCALEP=20.*(102.375)/(1.*GGG)
STPHENPTS
UIF=(XTERM*(STPN-1.*DX)-((20.*100.)/
1(1.*GGG))
IF(LJIF,GE.0.) GO TO 47
NADJ=NPTS
GO TO 48
47 TR=RTD/STPHENPTS
NADJ=NPTS-IFX(ARC)-1
48 CONTINUE
JO 20 I=1,NADJ
INDEX=NADJ-I+1
XI = I - 1
XX(INDEX) = XTERM + (XI*DX)
XX(INDEX) = XX(INDEX)
20 CONTINUE
C*** WRITE OUT RANGE TABLE
IF(IISI,NE.1) PRINT 820, NPTS,DX,XTERM
IF(IISI,EQ.1) GO TO 21
PRINT 800
PRINT 700
PRINT 830
PRINT 705
PRINT 303
PRINT 822, (XX(I),XXS(I),I=1,NADJ)
PRINT 830
21 CONTINUE
XD=XDM(I)
YD=YDM(I)
ZD=ZDM(I)
XUX=XU

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```
YDY=YD
ZD=ZD
CALL GUID
XJTG=XJTG
YJTG=YJTG
ZJTG=ZJTG
PRINT 856,XD,YD,ZD,XDTG,YDTG,ZDTG
ARG = SQRT (XD**2 + YD**2)
IF (KKK.EQ.1) GO TO 65
SC = AS*DIR
65 SC=AS*DIR
ASEO = SE0 * RTO
IF (IT.NE.1) PRINT 807,ASEO
C*** SCALE INITIAL LAUNCH CONDITIONS
RFEET = RI
RIER
GAMEG
75 C*** TRANSFORM MANEUVER VECTORS TO LAUNCH COORDINATES AND SCALE THEM
IF (ISL.EQ.1) GO TO 56
PRINT 802
PRINT 913
PRINT 800
PRINT 907
80 CONTINUE
DO 70 I = 1,NT
XD=XDM(I)
YD=YDM(I)
ZD=ZDM(I)
CALL GUID
XDTG(I) = XDTG
YDTG(I) = YDTG
ZDTG(I) = ZDTG
XDTGSH(I)=XDTGSH(I)
YDTGSH(I)=YDTGSH(I)
ZDTGSH(I)=ZDTGSH(I)
IF (ISL.NE.1) PRINT 908, THA(I),XDM(I),YDM(I),ZDM(I)
70 CONTINUE
XD=XDX
YD=YDY
ZD=ZDZ
IF (ISL.EQ.1) GO TO 76
PRINT 911
PRINT 800
PRINT 907
PRINT 800
DO 75 I=1,NT
PRINT 908, THA(I),XDTGSH(I),YDTGSH(I),ZDTGSH(I)
75 CONTINUE
76 CONTINUE
C CALCULATE INITIAL TARGET ANGLE OF ATTACK
AAA=1115.89*0.003896*ZZZ
ARGEO.63003*ZZZ
PHGEO.00237692*EXP(ARG)
DM=VVVV/AAA
HPX=Z
VX=8
CALL INTERP (QM,3MH,CLAA,NX,NPX,CLA,NERR)
```



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115 HT=13500.0
    ST=248.0
    XEU=XE(1)
    YEU=YET(1)
    ZEUS=ZE(1)
120 ATZ=HT*SQRT(XEU**2+YEU**2+ZEUS**2)/(PH0*(VVVV**2)*ST*CLX**32.174)
    C CALCULATE INITIAL COSE
    CI=COS(AT)
    SI=SIN(AT)
125 S9=SQRT(XD**2+YD**2)
    COSE=(S1*(ZD*CI-S9*SI)-(CI*(ZD*SI+S9*SI)*(XD**2+YD**2))/VVVV
    S11=COSE
    CO=COSE**2
130 C CALCULATE INITIAL APPARENT PLUME LENGTH-TO-BREADTH RATIO
    PLB=CLX*SQRT(1.-CO)
    C CALCULATE INITIAL LOS
    XLOS=-R*S2
    YLOS=-R*S4
    ZLOS=R*STL
135 C CALCULATE HORIZON REFERENCE VECTOR
    ARG=YCOZ/SORT(XLOS**2+YLOS**2)
    BET=ACOS(ARG)
    IF(XLOS.LT.0.0) CY=-SIN(BET)
    IF(XLOS.GE.0.0) CY=SIN(BET)
    CX=-COS(BET)
140 C CALCULATE INITIAL TARGET CENTERLINE UNIT VECTOR
    CLX=XD*(CI*ZD*SI/SORT(XD**2+YD**2))/
    1VVVV
    CLY=YD*(CI*ZD*SI/SORT(XD**2+YD**2))/
    1VVVV
    CLZ=(ZD*CI-S2RT(XD**2+YD**2))/SI/1VVVV
    C CALCULATE INITIAL PLUME ROTATION ANGLE
    B91=(1E99*8E7+2E8*8E1)*81*(Z99*31+XLOS*CLZ)*CY
    ARG=SQRT(YLOS*CLZ-ZLOS*CLY)**2+(ZLOS*CLX-XLOS*CLZ)**2
    150 *+(XLOS*CLY-YLOS*CLX)**2)
    ARG=ARG1/ARG2
    THE=ACOS(ARG)
    ARG=XLOS*CLY-YLOS*CLX
    IF(ARG.LT.0) GO TO 80
    IF(1E-4-1.570796326) GO TO 85
    TRP=THE-4.71238898
    GO TO 90
    80 TRP=1.570796326=THE
    GO TO 90
    85 TRP=1.570796326=THE
    90 SPD=TRP
    NX=17
    MPX=2
    CALL INTFRP(111,ECOS,HRTEE,NX,NPX,HRZE,HERZ)
    HC7F1=1.039-675*HRZE*EXP(-2.341*ALOG(RFEET/22965.8311))
    155 PIIRS52=ATAN(57/PLD)
    P2IR3S=22.5*RL0/RFEET
    AT7=((P2IR3S**2)*SIN(PIIRSS1))/(Z-0*(COS(PIIRSS/2-0))**2)
    PJTUI=0.1*EXP(1.003258*ALOG(AT7))
    170 FIT=HC7F1/PJTUI
    NX=9

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175      IIPX=2
          CALL INTERP (F17,F17T,FCI77,NX,NPX,FCI7,NERRI)
          RN=FCI7
          700 FORMAT(10X,35H RANGE=10-GO TABLE FOR DATA COLLECTION)
          705 FORMAT(22X,9H RANGE,FT,5X,13H SCALED RANGE)
          800 FORMAT('11H0)
          806 FORMAT(10X,6H XOTEO =F10.2,7H FT/SEC,5X,8H YOTEO =F10.2,7H FT/SEC,
          *5X,8H ZOTEO =F10.2,7H FT/SEC,10X,9H XDTLO =F10.2,7H FT/SEC,5X,
          *8H YDTLO =F10.2,7H FT/SEC,5X,8H ZDTLO =F10.2,7H FT/SEC)
          807 FORMAT(10X,17H CROSSING ANGLE =F7.2,4H DEG,5X,13H DIVE ANGLE =
          *F7.2,4H DEG)
          820 FORMAT(10X,7H NPTS =I3,4X,5H DX =F6.2,3H FT,4X,8H XTERM =F7.2,
          *3H FT)
          822 FORMAT(10X,F10.2,5X E15-8)
          907 FORMAT (1H0 4X 35H TIME 15H 20-MANEUVER YU MANEJVER
          *15H 20-MANEUVER)
          908 FORMAT(1X F10.4, 3(3X F8.2,4X))
          910 FORMAT(10X,24H EARTH-FIXED COORDINATES)
          911 FORMAT(10X,19H LAUNCH COORDINATES)
          912 FORMAT(9E16,8)
          RETURN
          END
    
```

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74774 OPT=1

SUBROUTINE INIT

VARIABLES	SN	TYPE	RELOCATION	1666	2MM	REAL	ARRAY	COMA
1700 QM	REAL	COMA				REAL	ARRAY	COMA
42 I1	REAL	COMP		43 Q2		REAL		COMP
44 I3	REAL	COMP		45 Q4		REAL		COMP
46 Q5	REAL	COMP		47 Q6		REAL		COMP
10 R	REAL	EXTRA		1007 RFEET		REAL		COMA
72 RI	REAL	COMA		67 RLB		REAL		COMA
1422 RLK	REAL	COMA		76 RN		REAL		COMA
1436 RRR	REAL	COMA		514 RTD		REAL		COMA
1701 SA	REAL	COMA		6 SC		REAL		EXTRA
11 SCALEL	REAL	EXTRA		1423 SCALEP		REAL		COMA
1622 SCALEY	REAL	COMA		1665 SCALEV		REAL		COMA
5 SEJ	REAL	EXTRA		1440 SPL		REAL		COMA
71 SPJ	REAL	COMA		1437 SR		REAL		COMA
1011 ST	REAL	REAL		1442 SFL		REAL		COMA
777 STP4	REAL	REAL		1435 SI		REAL		COMA
62 S1P1	REAL	COMP		55 S1P2		REAL		COMP
72 S1P3	REAL	COMP		76 S1P4		REAL		COMP
102 S1P5	REAL	COMP		105 S1P6		REAL		COMP
1264 S2	REAL	COMA		61 S2P1		REAL		COMP
55 S2P2	REAL	COMP		71 S2P3		REAL		COMP
75 S2P4	REAL	COMP		101 S2P5		REAL		COMP
105 S2P6	REAL	COMP		1265 S3		REAL		COMA
1266 S4	REAL	COMA		1267 S5		REAL		COMA
1015 S9	REAL	REAL		1122 TAMA		REAL	ARRAY	COMA
107 THE	REAL	EXTRA		75 THETAL		REAL	ARRAY	COMA
325 TIME	REAL	ARRAY		10060 TIMES		REAL	ARRAY	MANEUV
1624 TMA	REAL	ARRAY		407 TMA5		REAL	ARRAY	COMA
1623 TREAL	REAL	COMA		24 TRP		REAL		EXTRA
1216 VM	REAL	COMA		1703 VMX		REAL	ARRAY	COMA
1755 VHY	REAL	ARRAY		2047 VMZ		REAL	ARRAY	COMA
12 VT	REAL	GTARG		1445 VTI		REAL		COMA
12 VVVV	REAL	EXTRA		1010 WT		REAL		EXTRA
50 W1	REAL	COMP		51 W2		REAL		COMP
92 W3	REAL	COMP		83 W4		REAL		COMP
54 W5	REAL	COMP		55 W6		REAL		COMP
1432 XC	REAL	COMA		1117 XCOMP		REAL		COMA
0 XD	REAL	COMB		12 XDDE		REAL		COMB
6 XDEF	REAL	COMB		1 XDEM		REAL	ARRAY	MANEUV
1270 XDM	REAL	ARRAY		1256 XDO		REAL	ARRAY	COMA
3 XDTG	REAL	COMB		7723 XDTGM		REAL	ARRAY	MANEUV
445 XDTGMS	REAL	COMA		64 XDTGO		REAL		COMA
1004 XDX	REAL	ARRAY		1446 XE		REAL	ARRAY	COMA
1012 XEU	REAL	REAL		1001 XI		REAL		COMA
14 XLOS	REAL	EXTRA		577 XHAN		REAL	ARRAY	COMA
1107 XMISS	REAL	COMA		10055 XPRIME		REAL	MANEUV	MANEUV
1682 XTA	REAL	COMA		2 XTERM		REAL	EXTRA	EXTRA
25 XX	REAL	ARRAY		2 XXS		REAL	ARRAY	COMA
1433 YC	REAL	COMA		1120 YCOMP		REAL	COMA	COMA
1 YD	REAL	COMB		13 YDOE		REAL	COMB	COMB
7 YDEF	REAL	COMB		2507 YDEM		REAL	ARRAY	MANEUV
1320 YC4	REAL	ARRAY		1257 YOO		REAL	COMA	COMA
4 YDTG	REAL	COMB		7761 YDTGM		REAL	ARRAY	MANEUV
503 YDTGMS	REAL	COMA		65 YDTGO		REAL	COMA	COMA
1005 YDY	REAL	ARRAY		1504 YE		REAL	ARRAY	COMA
1013 YEJ	REAL	REAL		15 YLOS		REAL	EXTRA	EXTRA
10056 YPRIME	REAL	MANEUV		1663 YTA		REAL	COMA	COMA
1600 YZLT	REAL	COMA		1434 ZC		REAL		COMA

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VARIABLES	SN	TYPE	RELOCATION
1121 ZCOMP	REAL	COMB	COMB
14 ZODE	REAL	COMB	COMB
5215 ZDEM	REAL	ARRAY	ARRAY
1260 ZOO	REAL	COMB	COMB
10017 ZOTGM	REAL	ARRAY	ARRAY
56 ZOTGO	REAL	COMB	COMB
1542 ZE	REAL	ARRAY	ARRAY
16 ZLOS	REAL	EXTRA	MANEUV
1654 ZTA	REAL	COMB	COMB

FILE NAMES	MODE
OUTPUT	FMT

EXTERNALS	TYPE	ARGS
ACOS	REAL	1 LIBRARY
ATAN	REAL	1 LIBRARY
COS	REAL	1 LIBRARY
GUID	REAL	0
SIN	REAL	1 LIBRARY

INLINE FUNCTIONS	TYPE	ARGS
IFIX	INTEGER	1
INTRIN	INTRIN	

STATEMENT LABELS	73	21	16	47
3 20	120	65	144	56
22 48	0	75	230	76
0 70	414	85	416	90
411 80	647	705	654	800
641 700	700	207	710	820
556 305	722	907	732	908
717 922	743	911	747	912
736 910				

COMMON BLOCKS	LENGTH
EXTRA	72
COMA	1165
COMB	13
COMP	73
MANEUV	4316
OTRG	11

STATISTICS	PROGRAM LENGTH	10338	539
CM-LABELED COMMON LENGTH	130228	5650	

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SUBROUTINE LETH

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COMMON/PK7/XDH(22),YDH(22),ZDH(22),BDHX(22),BDHY(22),BDHZ(22)
* KILL(22),P(4),SPK,SPHG,SPHS,SPH
COMMON/MSD/XM(3),YM(3),ZM(3),RM(3),NOMT,IGN
COMMON/MAUEV/IT,XDEN(30,45),YDEM(30,45),ZDEM(30,45),
* XDTCH(30),YDTCH(30),ZDTCH(30),XPRIME,YPRIME,
* ZPRIME,TIMES(50),ITRAJ(60),ITAU(60),III,NADJ
COMMON/DEL/PPXS(50),PPYS(50),PPZS(50),VXXS(50),VYYS(50),VMZS(50)
COMMON/GIARG/FXA,FYA,FZA,FXB,FYB,FZB,FXG,FYG,FZG,AT,VT
COMMON/CCOR/COSA,COSB,COSC,YA,ZA
COMMON/COMP/ISI,199,188,CLMS(10),CLS(10),CLSS(10),NSAM,Q1,Q2,Q3,
* Q4,Q5,Q6,M1,M2,M3,M4,M5,M6,IFT,IPLAN,ICON,S2P1,S1P1,A2P1,A1P1,
* S2P2,S1P2,A2P2,A1P2,S2P3,S1P3,A2P3,A1P3,S2P4,S1P4,A2P4,A1P4,S2P5,
* S1P5,A2P5,A1P5,S2P6,S1P6,A2P6,A1P6
* COSA=(1./ZA)/SQRT((1./ZA)**2+(YA/ZA)**2+1.)
* COSB=(YA/ZA)/SQRT((1./ZA)**2+(YA/ZA)**2+1.)
* COSC=1./SQRT((1./ZA)**2+(YA/ZA)**2+1.)
SSX=0.0
SSY=0.0
SSZ=0.0
JJ=J=1,NADJ
SSX=SSX+VMXST(J)
SSY=SSY+VMYS(J)
SSZ=SSZ+VMZS(J)
4 CONTINUE
ADJ=FLGAT(NADJ)
C*** AVERAGE LAUNCH COORDINATES OF RELATIVE VELOCITY VECTORS OVER DATA
C COLLECTION RANGE
CJUL5=(SSX/ADJ)
CJUL6=(SSY/ADJ)
CJUL7=(SSZ/ADJ)
C*** GENERALIZED TARGET COORDINATES OF AVERAGE RELATIVE VELOCITY VECTOR
C REFERENCED TO ORIGIN AT TAILPIPE
CJUL5=FXA+CJUL5*FYA+CJUL5*FZA+CJUL7
CJUL6=FXB+CJUL6*FYB+CJUL6*FZB+CJUL7
CJUL7=FXG+CJUL7*FYG+CJUL7*FZG+CJUL7
C1=COS(AT)
S1=SIN(AT)
C*** TARGET FIXED COORDINATES OF AVERAGE RELATIVE VELOCITY VECTOR
C REFERENCED TO ORIGIN AT TAILPIPE
CARL5=CJUL7*C1+CJUL5*S1
CARL6=CJUL6
CARL7=CJUL5*C1-CJUL7*S1
C*** TARGET FIXED COORDINATES OF AVERAGE INERTIAL MISSILE VELOCITY
C VECTOR
C REFERENCED TO ORIGIN AT TAILPIPE
VMI=(CJUL7*VT)*C1+CJUL5*S1
VM2=CJUL6
VM3=CJUL5*C1-(CJUL7*VT)*S1
C*** GENERALIZED TARGET COORDINATES OF POSITION VECTOR OF LAST DATA
C POINT
C REFERENCED TO ORIGIN AT TAILPIPE
XAI=FXA+PPXS(NADJ)+FYA+PPYS(NADJ)+FZA+PPZS(NADJ)
ZAI=FXC+PPXS(NADJ)+FYC+PPYS(NADJ)+FZC+PPZS(NADJ)
YAI=FXJ+PPXS(NADJ)+FYB+PPYS(NADJ)+FZB+PPZS(NADJ)
C*** TARGET FIXED COORDINATES OF POSITION VECTOR OF LAST DATA POINT
C REFERENCED TO ORIGIN AT TAILPIPE

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XAIMU=ZAI*CI+XAI*S1
YAIMU=YAI
60  ZAIMU=XAI*CI-ZAI*S1
C*** DISTANCE BETWEEN LAST DATA POINT AND XF-YF PLANE PIERCING POINT
C   REFERENCED TO ORIGIN AT TAILPIPE
D1=SRIT((XAIMU-ZM(1)/ZA)**2+(YAIMU-YM(1)/ZM(1))**2)
**ZAI*2)
55  C*** COMPONENTS OF UNIT VECTOR IN DIRECTION FROM XF-YF PLANE PIERCING
C   POINT TO POSITION OF LAST DATA POINT
C   REFERENCED TO ORIGIN AT TAILPIPE
AA=(XAIMU-ZM(1)/ZA)/D1
BB=(YAIMU-YM(1)/ZM(1))/D1
CC=ZAIMU/D1
70  IF(COSA/ABS(COSA)-NE.AA/ABS(AA)) COSA=-COSA
IF(COSB/ABS(COSB)-NE.BB/ABS(BB)) COSB=-COSB
IF(COSG/ABS(COSG)-NE.CC/ABS(CC)) COSG=-COSG
C*** COSINE OF THETA
COST=AA*COSA+BB*COSB+CC*COSG
75  C*** DISTANCE BETWEEN PK MODEL AIM POINT AND XF-YF PLANE PIERCING POINT
C   REFERENCED TO ORIGIN AT TAILPIPE
D2=D1*COST
C*** TARGET FIXED COORDINATES OF PK MODEL AIM POINT
80  C   REFERENCED TO ORIGIN AT CG
XAIM=D2*COSA-ZM(1)/ZA-19.5
YAIM=D2*COSB+YM(1)/ZM(1)
ZAIM=D2*COSG
IF((S1-E).1) GO TO 300
PRINT 333,XAIM,YAIM,D2,ZAIM,D1,AA,BB,CC,COST,D2
85  PRINT 999,COSA,COSB,COSG
300  CONTINUE
NELIPS=22
VSHELL=SGRT(VM1**2+VM2**2+VM3**2)
90  BUX=VMI/VSHELL
BUTE=VMZ/VSHELL
BUE=VMY/VSHELL
IF((S1-EQ.1) GO TO 301
PRINT 999,COOL5,COOL6,COOL7,COUL5,COUL6,COUL7,C1,S1
95  PRINT 999,CARL5,CARL6,CARL7,VM1,VM2,VM3,XAI,YAI,ZAI
PRINT 999,XAIM,YAIM,ZAIM,VSHELL,BUX,BUY,BUZ
301  CONTINUE
TSTAO=10J.
MPEN=0
100  DO 444 N=1,NELIPS
CAY1=(XAIM-XJH(CH)/78DHX(H)
CAY3=(YAIM-YOH(H)/78DHY(H)
CAY5=(ZAIM-ZOH(H)/78DHZ(H)
CAY2=CARL5/8DHX(H)
CAY4=CARL6/8DHY(H)
CAY6=CARL7/8DHZ(H)
CAY7=CAY2**2+CAY3**2+CAY5**2+CAY6**2
CAY8=2.*(CAY1+CAY2+CAY3+CAY4+CAY5+CAY6)
CAY9=CAY1**2+CAY3**2+CAY5**2-1.
TEMP1=(CAY8*0.5)/CAY7
TEMP2=CAY9/CAY7
105  CAY7=CAY7+TEMP1**2-TEMP2
110  DISORI=TEMP1**2-TEMP2
IF(DISCRI)444,445,445
445  ITRIAL=ITRIAL+1(JTSCRI)

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115 IF (IRIAL-ISTAB) 466, 444, 444

446 ISTAB=ITPIAL

MPEN=M

447 CONTINUE

DO 460 M=1, 4

460 P(M)=0

461 P(1)=1

IF (MPEN) 461, 461, 462

GO TO 500

462 IF (KILLT*MPEN) 471, 471, 472

471 P(2)=1

GO TO 500

472 ITI=ISTAB

M=MPEN

XS=XAIM+CARLS*ITI

YS=YAIM+CARLS*ITI

ZS=ZAIM+CARLS*ITI

AN=2*(XS-XOH(M))/ (BOHX(M)**2)

BN=2*(YS-YOH(M))/ (BOHY(M)**2)

CN=2*(ZS-ZOH(M))/ (BOHZ(M)**2)

CSANG=(-AN*OXY-BN*BUY-CN*BUZ)/SQRT (AN**2+BN**2+CN**2)

IF (CSANG=-1.74) 481, 481, 482

481 P(3)=1

GO TO 500

482 P(4)=1

500 CONTINUE

PRINT 101, P(1), P(2), P(3), P(4)

SPK=SPK+P(4)

SPHG=SPHG+P(3)

SPHS=SPHS+P(2)

SPN=SPN+P(1)

101 FORMAT(1H6, 7H

=, F6.4, 3X, 7H

=, F6.4, 3X, 13H

=, F6.4, 3X, 16H

999 FORMAT(101X, E11.4)

RETURN

END

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SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
I LETH

VARIABLES	SN	TYPE	RELOCATION	524	ADJ	REAL	GTARG
522 AA	REAL			11	AT	REAL	GTARG
613 AN	REAL			70	AP2	REAL	COMP
74 AP1	REAL	COMP		100	AP4	REAL	COMP
104 AP3	REAL	COMP		110	AP6	REAL	COMP
53 AP5	REAL	COMP		67	A2P2	REAL	COMP
73 AP7	REAL	COMP		77	A2P4	REAL	COMP
103 AP9	REAL	COMP		107	A2P6	REAL	COMP
553 B3	REAL			102	B0HK	REAL	ARRAY PK
130 B4Y	REAL	ARRAY PK		156	B0MZ	REAL	ARRAY PK
614 BN	REAL			564	BUX	REAL	
535 B0Y	REAL			566	B0Z	REAL	
535 CARL5	REAL			536	CARL6	REAL	
537 CARL7	REAL			572	CAY1	REAL	
575 CAY2	REAL			573	CAY3	REAL	
576 CAY4	REAL			574	CAY5	REAL	
577 CAY6	REAL			600	CAY7	REAL	
601 CAY8	REAL			602	CAY9	REAL	
556 CC	REAL			3	CLNS	REAL	ARRAY COMP
15 CLS1	REAL	ARRAY COMP		27	CLS2	REAL	ARRAY COMP
415 CN	REAL			525	COOL5	REAL	
526 COOL6	REAL			527	COOL7	REAL	
2 COSA	REAL	COMD		1	COSB	REAL	COMD
2 COS3	REAL	COMD		555	COST	REAL	
616 CSANG	REAL			530	COUL5	REAL	
531 COUL6	REAL			532	COUL7	REAL	
533 C1	REAL			605	CLSCRI	REAL	
531 J1	REAL			556	J2	REAL	
0 FPA	REAL	GTARG		3	FXB	REAL	GTARG
6 FPC	REAL	GTARG		1	FYA	REAL	GTARG
4 FFB	REAL	GTARG		7	FYC	REAL	GTARG
2 FZ1	REAL	GTARG		5	FZB	REAL	GTARG
10 FZC	REAL	GTARG		15	ICN	INTEGER	MISD
50 ICCV	INTEGER	COMP		55	IPT	INTEGER	COMP
10332 III	INTEGER	MANEUV		57	IPLANE	INTEGER	COMP
0 ISI	INTEGER	COMP		10236	ITAU	INTEGER	MANEUV
10142 ITRAJ	ARRAY	MANEUV		0	ITI	INTEGER	MANEUV
2 I88	INTEGER	COMP		1	I99	INTEGER	COMP
523 J	INTEGER			204	KILL	INTEGER	ARRAY PK
571 M	INTEGER			570	MPEN	INTEGER	
10333 NAJJ	INTEGER	MANEUV		562	NELIPS	INTEGER	
14 NOPT	INTEGER	MISD		41	NSAM	INTEGER	COMP
232 P	REAL	PK		0	PPXS	REAL	DEL
62 P0Y3	REAL	ARRAY		144	PPZ5	REAL	DEL
42 Q1	REAL	COMP		43	32	REAL	COMP
44 Q3	REAL	COMP		45	36	REAL	COMP
46 Q5	REAL	COMP		47	36	REAL	COMP
11 RM	REAL	ARRAY		237	SPHG	REAL	PK
240 SP4S	REAL	PK		236	SPK	REAL	PK
241 SP4	REAL	PK		520	SSX	REAL	
421 37	REAL			522	SSZ	REAL	

SUBROUTINE LETH				FINH 4.2+75348				01/12/76 14.30.55.				PAGE 5			
VARIABLES				RELOCATION											
SN	TYPE	REAL	REAL	62	SIP1	REAL	REAL	62	SIP1	REAL	REAL	62	SIP1	REAL	REAL
534	S1	REAL	REAL	72	SIP3	REAL	REAL	72	SIP3	REAL	REAL	72	SIP3	REAL	REAL
56	S1P2	REAL	REAL	102	SIP5	REAL	REAL	102	SIP5	REAL	REAL	102	SIP5	REAL	REAL
76	S1P4	REAL	REAL	61	S2P1	REAL	REAL	61	S2P1	REAL	REAL	61	S2P1	REAL	REAL
109	S1P5	REAL	REAL	71	S2P3	REAL	REAL	71	S2P3	REAL	REAL	71	S2P3	REAL	REAL
65	S2P2	REAL	REAL	101	S2P5	REAL	REAL	101	S2P5	REAL	REAL	101	S2P5	REAL	REAL
75	S2P6	REAL	REAL	603	TEMP1	REAL	REAL	603	TEMP1	REAL	REAL	603	TEMP1	REAL	REAL
105	S2P8	REAL	REAL	10060	TIMES	REAL	REAL	10060	TIMES	REAL	REAL	10060	TIMES	REAL	REAL
604	TEMP2	REAL	REAL	606	TRIAL	REAL	REAL	606	TRIAL	REAL	REAL	606	TRIAL	REAL	REAL
557	TSAB	REAL	REAL	226	VMS	REAL	REAL	226	VMS	REAL	REAL	226	VMS	REAL	REAL
507	TTT	REAL	REAL	372	VM2S	REAL	REAL	372	VM2S	REAL	REAL	372	VM2S	REAL	REAL
310	VMS	REAL	REAL	541	VM2	REAL	REAL	541	VM2	REAL	REAL	541	VM2	REAL	REAL
540	VM1	REAL	REAL	563	VMSHELL	REAL	REAL	563	VMSHELL	REAL	REAL	563	VMSHELL	REAL	REAL
542	VM3	REAL	REAL	50	M1	REAL	REAL	50	M1	REAL	REAL	50	M1	REAL	REAL
12	VF	REAL	REAL	52	M3	REAL	REAL	52	M3	REAL	REAL	52	M3	REAL	REAL
51	M2	REAL	REAL	54	M5	REAL	REAL	54	M5	REAL	REAL	54	M5	REAL	REAL
53	M4	REAL	REAL	543	XAI	REAL	REAL	543	XAI	REAL	REAL	543	XAI	REAL	REAL
55	M5	REAL	REAL	546	XAIMD	REAL	REAL	546	XAIMD	REAL	REAL	546	XAIMD	REAL	REAL
557	XAIM	REAL	REAL	0	XOH	REAL	REAL	0	XOH	REAL	REAL	0	XOH	REAL	REAL
1	XDEM	REAL	REAL	0	XH	REAL	REAL	0	XH	REAL	REAL	0	XH	REAL	REAL
7723	XOTGM	REAL	REAL	610	XS	REAL	REAL	610	XS	REAL	REAL	610	XS	REAL	REAL
10055	XP-IME	REAL	REAL	545	YAI	REAL	REAL	545	YAI	REAL	REAL	545	YAI	REAL	REAL
3	YA	REAL	REAL	547	YAIMD	REAL	REAL	547	YAIMD	REAL	REAL	547	YAIMD	REAL	REAL
550	YAIM	REAL	REAL	26	YOH	REAL	REAL	26	YOH	REAL	REAL	26	YOH	REAL	REAL
2507	YDEM	REAL	REAL	3	YN	REAL	REAL	3	YN	REAL	REAL	3	YN	REAL	REAL
7751	YOTGM	REAL	REAL	611	YS	REAL	REAL	611	YS	REAL	REAL	611	YS	REAL	REAL
10056	YP-IME	REAL	REAL	544	ZAI	REAL	REAL	544	ZAI	REAL	REAL	544	ZAI	REAL	REAL
4	Z4	REAL	REAL	550	ZAIMD	REAL	REAL	550	ZAIMD	REAL	REAL	550	ZAIMD	REAL	REAL
561	ZAIM	REAL	REAL	54	ZOH	REAL	REAL	54	ZOH	REAL	REAL	54	ZOH	REAL	REAL
5215	ZDEM	REAL	REAL	6	ZH	REAL	REAL	6	ZH	REAL	REAL	6	ZH	REAL	REAL
10017	ZOTGM	REAL	REAL	612	ZS	REAL	REAL	612	ZS	REAL	REAL	612	ZS	REAL	REAL
10057	ZP-IME	REAL	REAL												
FILE NAMES				MODE											
OUTPUT				FMT											
EXTERNALS				TYPE											
COS				REAL											
SORT				REAL											
				1 LIBRARY											
				1 LIBRARY											
INLINE FUNCTIONS				TYPE											
ABS				REAL											
				1 INTRIN											
				FLOAT											
				1 INTRIN											
STATEMENT LABELS															
0 4				475 101				FMT							
236 301				306 444											
0 446				0 450											
317 462				0 471				INACTIVE							
0 481				367 482											
507 999				FMT											
COMMON BLOCKS				LENGTH											
PK				152											
MISJ				14											
MANEUV				4316											
DELT				303											
STARC				11											
COMJ				5											

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SUBROUTINE LETH 74774 OPT=1 FTNH 4.2+75348 01/12/76 14.30.55. PAGE 6

COMMON BLOCKS LENGTH
COMP 73

STATISTICS

PROGRAM LENGTH 6178 399
CM LABELED COMMON LENGTH 114218 4881

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SUBROUTINE QCLIN 74774 OPT=1 FINH 4.2475348 01/12/78 14.31.02. PAGE 1

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SUBROUTINE QCLIN
COMMON/COMP/ISI199,I88,CLMS(IU),CLSI(IU),CLSZ(IU),NSAM,Q1,Q2,Q3,
*J4,J5,Q6,M1,M2,M3,M4,M5,M6,IFT,IPLANE,ICON,S2P1,SIP1,A2P1,AIP1,
*S2P2,SIP2,A2P2,AIP2,S2P3,SIP3,A2P3,AIP3,S2P4,SIP4,A2P4,AIP4,S2P5,
*SIP5,A2P5,AIP5,S2P6,SIP6,A2P6,AIP6
*JIP5,A2P5,AIP5,S2P6,SIP6,A2P6,AIP6
C CALCULATE CONTROL LIMITS
S2P1=M1*CLSZ(NSAM)
SIP1=M1*CLSI(NSAM)
A2P1=J1*M1*CLMS(NSAM)
AIP1=J1*M1*CLMS(NSAM)
S2P2=M2*CLSZ(NSAM)
SIP2=M2*CLSI(NSAM)
A2P2=J2*M2*CLMS(NSAM)
AIP2=J2*M2*CLMS(NSAM)
S2P3=M3*CLSZ(NSAM)
SIP3=M3*CLSI(NSAM)
A2P3=J3*M3*CLMS(NSAM)
AIP3=J3*M3*CLMS(NSAM)
S2P4=M4*CLSZ(NSAM)
SIP4=M4*CLSI(NSAM)
A2P4=J4*M4*CLMS(NSAM)
AIP4=J4*M4*CLMS(NSAM)
S2P5=M5*CLSZ(NSAM)
SIP5=M5*CLSI(NSAM)
A2P5=J5*M5*CLMS(NSAM)
AIP5=J5*M5*CLMS(NSAM)
S2P6=M6*CLSZ(NSAM)
SIP6=M6*CLSI(NSAM)
A2P6=J6*M6*CLMS(NSAM)
AIP6=J6*M6*CLMS(NSAM)
RETURN
END
```


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SUBROUTINE QCLIN 7474 OPT=1 FINH 4.2475348 01/12/76 14.31.02. PAGE 2

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 QCLIN

VARIABLES	SN	TYPE	RELOCATION
64 AIP1	70	REAL	COMP
74 AIP3	100	REAL	COMP
106 AIP5	110	REAL	COMP
63 A2P1	67	REAL	COMP
73 A2P3	77	REAL	COMP
103 A2P5	107	REAL	COMP
3 CLS2	15	REAL	COMP
27 CLS2	60	REAL	COMP
56 IFT	57	INTEGER	COMP
0 ISI	2	INTEGER	COMP
1 I99	41	INTEGER	COMP
42 Q1	43	REAL	COMP
44 Q3	45	REAL	COMP
66 Q5	47	REAL	COMP
62 SIP1	66	REAL	COMP
72 SIP3	76	REAL	COMP
102 SIP5	106	REAL	COMP
51 S2P1	63	REAL	COMP
71 S2P3	73	REAL	COMP
101 S2P5	103	REAL	COMP
50 W1	51	REAL	COMP
52 W3	53	REAL	COMP
54 W5	55	REAL	COMP
COMMON BLOCKS	LENGTH		
COMP	73		

STATISTICS
PROGRAM LENGTH 568 46
COMMON LABELLED COMMON LENGTH 1118 73

SUBROUTINE GUID 7474 0P11 FINH 4-2-75398 01/12/76 14-31-06 PAGE 1

SUBROUTINE GUID

C** THIS SUBROUTINE TRANSFORMS EARTH FIXED TO LAUNCH COORDINATES.

COMMON /ANG/SINCO,COSCO,SINSCO,COSSCO

COMMON /COMB/XD,YD,ZD,XDTG,YDTG,ZDTG,XDEF,YDEF,ZDEF,ZZZ

*XDOE,YDOE,ZDOE

C***

XDTG = XD * COSCO * COSSCO + YD * COSCO * SINSCO - ZD * SINCO

YDTG = -XD * SINSCO + YD * COSSCO

ZDTG = XD * SINCO * COSSCO + YD * SINCO * SINSCO + ZD * COSCO

C***

RETURN

END

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SUBROUTINE GUID 74774 OPT=1 FTNH 4-2-75348 01/12/76 14.31.06. PAGE 2

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 GUID

VARIABLES	SN	TYPE	RELOCATION
3 COSSCO	REAL	ANG	ANG
2 SINSCO	REAL	ANG	ANG
0 XU	REAL	COMB	COMB
6 XDEF	REAL	COMB	COMB
1 YD	REAL	COMB	COMB
7 YDEF	REAL	COMB	COMB
2 ZU	REAL	COMB	COMB
10 ZDEF	REAL	COMB	COMB
11 ZZZ	REAL	COMB	COMB
1 COSSO	REAL	ANG	ANG
0 SINSD	REAL	ANG	ANG
12 XDDE	REAL	COMB	COMB
3 XDTC	REAL	COMB	COMB
13 YDDE	REAL	COMB	COMB
4 YDTC	REAL	COMB	COMB
14 ZDDE	REAL	COMB	COMB
5 ZDTC	REAL	COMB	COMB

COMMON BLOCKS	LENGTH
ANG	4
COMB	13

STATISTICS	21B	17
PROGRAM LENGTH	21B	17
CM LABELED COMMON LENGTH	21B	17

SUBROUTINE KSCALE 74774 OPT=1 FTN 4.2475348 01/12/76 14.31.11. PAGE 1

SUBROUTINE KSCALE, RETURNS(ZI)

C*** THIS ROUTINE GIVES THE ESTIMATED TIME AT 1000 FT-T0-GO (T-PRIME)

C*** AND THE VALUE OF GAMMA THAT WILL NOT ALLOW ANALOG OVERLOAD (GAMA).

C*** THEY DETERMINE THE VARIABLE SCALE FACTOR EQUATION. THE RETURNED

C*** VALUES ARE G FOR T-PRIME AND GGG FOR GAMA.

COMMON/COMMON/LEVEL,IPIS,XXS(50),XDTGO,YDTGO,ZDTGO,RLB,COSE,SP0,RI,

*GAM,EDOT,THETA,3N,

*PPX(50),PPY(50),PPZ(50),TIME(50),THAS(30),XDTGMS(30)

*YDTGMS(30),ZDTGMS(30),XMAN(4,50),XMISS(7),NT

*XCOMP,YCOMP,ZCOMP,TAN1(30),DELTA(30),VM(30),G,GGG

*X00,Y00,Z00,DXG,DYG,DZG,S2,S3,S4,S5,XDM(30),YDM(30),ZDM(30),

*RLDK,SCALEP,F1,F2,F3,G1,G2,G3,XG,YG,ZG,S1,RRR,SR,SPL,CTL,STL,

*CPL,A1,V1,XE(30),YE(30),ZE(30),ZALT,NERX,CLA,NPX,NX,CLAA(10),

*PHO,ARG,AAA,SCALE1,THEAL,TMA(30),XTA,YTA,ZTA,SCALEV,QNM(10),QM

*SA,CA,VHX(50),VMY(50),VMZ(50)

*ECOST(17),HRTVE(17),FI(19),FCI(77(9))

COMMON/COMP/IS1,I99,I88,CLMS(10),CLS1(10),CLS2(10),NSAM,Q1,Q2,Q3,

*T5,Z5,Q5,W1,W2,A3,M4,M5,M6,I1,I1PLANE,ICON,S2P1,S1P1,A2P1,A1P1,

*S2P2,S1P2,A2P2,A1P2,S2P3,S1P3,A2P3,A1P3,S2P4,S1P4,A2P4,A1P4,S2P5,

*S1P5,A2P5,A1P5,S2P6,S1P6,A2P6,A1P6

C*** BEGIN CONVERGING SEARCH FOR T-PRIME AT 1000 FT-T0-GO.

R=RI

DC=1.

AN=0.

G=0.

10 G=G+JG

ARG1=G*SQR(YDTGO**2+ZDTGO**2)

ARG2=R+G*XDTGO-1000.

THETA2=ATAN2(ARG1,ARG2)

NPX=2

IF (G<GT-20) GO TO 20

NR=24

CALL INTERP(G,TAMA,DELTA,NS,NPX,OR,NERZ)

VALUE=R-OR*COS(THETA2)+G*XDTGO-1000.

A=ABS(VALUE)

IF (A<LT-20.) GO TO 40

IF (VALUE<GT-0.) GO TO 10

AN=AN+1.

G=G-UG

DC=.1/AN

GO TO 10

20 PRINT 30

30 FORMAT(IX,35H T-PRIME IS GREATER THAN 20 SECONDS)

40 RETURN ZI

40 CONTINUE

IF (ISI.NE.1) PRINT 53,G,DR

50 FORMAT(10X,10H T-PRIME =F10.4,4H SEC,5X,26H DELTA AT 1000 FT TO G

*G =F10.2,3H FT)

C*** BEGIN CONVERGING SEARCH FOR GAMA.

C

C

C

C

C

C

C

C

C

C

C

C

SUBROUTINE KSCALE 7474 OPT=1 FINH 4.275348 01/12/76 14.31.11. PAGE 2

```

60 GG=0.
   SG=GG*0.5
   AS=XDTGO*XDTGO
   CALL INTERP(GG,YAMA,DELTA,R,NB,NPX,DR,NERR)
   CALL INTERP(GG,YAMA,VM,NB,NPX,V,NERR)
   G2=XDTGO*(20000.-3*DR*COS(THETA2))-20000.-V*COS(THETA2)
   C=IR-DR*COS(THETA2)*(20000.-R*DR*COS(THETA2))
   VALUE=A*GG*G3+B*GG+C
   AA=ABS(VALUE)
   IF(AA.LT.10000.) GO TO 70
   IF (VALUE.GT.0.) GO TO 60
   AN=AA*1.
   GG=GG-JG
   JG=.1/AN
   GO TO 60
70 CONTINUE
   IF (ISI.NE.1) PRINT 80,GG
80 FORMAT(1X,25H T AT GAMA MIN OVERLOAD =F10.4,4H SEC)
   IF (ISI.NE.1) PRINT 90,DR
90 FORMAT(1X,30H DELTA AT GAMA MIN OVERLOAD =F10.1,3H FT)
   IF (ISI.NE.1) PRINT 95,V
95 FORMAT(1X,26H VN AT GAMA MIN OVERLOAD =F10.1,7H FY/SEC)
   A1=20000./((DR*COS(THETA2))-R-XDTGO*GG)
   GGG=-(1.-A1)*G/G3
   IF (ISI.NE.1) PRINT 96,GGG
96 FORMAT(1X,8H GAMA = F10.4)
   A2=0.48/(1.+GGG)
   PRINT 97,A2
97 FORMAT(1X,31H SMALLEST BIT A/D RESOLUTION = F10.4,2X,3H FT)
   RETURN
   ENO

```


SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

VARIABLES SN TYPE RELOCATION

353 A	REAL	360 AA	REAL
1621 AAA	REAL	344 AN	REAL
1620 ARG	REAL	345 ARG1	REAL
345 ARG2	REAL	1444 A1	REAL
54 A1P1	REAL	70 A1P2	REAL
74 A1P3	REAL	100 A1P4	REAL
104 A1P5	REAL	110 A1P6	REAL
351 A2	REAL	63 A2P1	REAL
57 A2P2	REAL	73 A2P3	REAL
77 A2P4	REAL	103 A2P5	REAL
107 A2P5	REAL	356 B	REAL
357 C	REAL	1702 CA	REAL
1602 CLA	REAL	1505 CLAA	REAL
3 CLMS	REAL	15 CLS1	REAL
27 CLS2	REAL	70 COSE	REAL
1443 CPL	REAL	1441 CTL	REAL
1150 DELTAR	REAL	343 JG	REAL
351 DR	REAL	1261 JXG	REAL
1262 DYG	REAL	1263 JZG	REAL
2131 ECOS	REAL	74 EDO1	REAL
2204 FC177	REAL	2173 F17T	REAL
1426 F1	REAL	1425 F2	REAL
1426 F3	REAL	1254 J	REAL
73 GA4	REAL	354 GG	REAL
1255 GGG	REAL	1427 G1	REAL
1430 G2	REAL	1431 G3	REAL
2152 HAT7EE	REAL	60 ICON	INTEGER
56 IFT	INTEGER	57 IPLANE	INTEGER
1 IPTS	INTEGER	0 I91	INTEGER
2 I98	INTEGER	1 I99	INTEGER
0 LEVEL	INTEGER	350 NB	INTEGER
1601 MEQR	INTEGER	1503 NPX	INTEGER
41 NS4	INTEGER	1116 NT	INTEGER
1604 HX	INTEGER	1617 PHO	REAL
77 PPX	REAL	161 PPY	REAL
243 PPZ	REAL	1700 QH	REAL
1666 QH4	REAL	42 Q1	REAL
43 Q2	REAL	44 Q3	REAL
45 Q4	REAL	46 Q5	REAL
47 Q6	REAL	342 R	REAL
72 RI	REAL	67 RLB	REAL
1422 RLK	REAL	76 RN	REAL
1436 RFP	REAL	1701 SA	REAL
1423 SCALP	REAL	1622 SCALET	REAL
1653 SCALP	REAL	1440 SPL	REAL
71 SPD	REAL	1437 SR	REAL
1442 STL	REAL	1435 S1	REAL
52 S1P1	REAL	66 S1P2	REAL
72 S1P3	REAL	76 S1P4	REAL
102 S1P5	REAL	106 S1P6	REAL
1254 S2	REAL	61 S2P1	REAL

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SUBROUTINE KSCALE 74774 OPT=1 FINH 4.2+75348 01/12/76 14.31.11. PAGE 4

VARIABLES	SN	TYPE	RELOCATION
65 S2P2	REAL	COMP	REAL
75 S2P4	REAL	COMP	REAL
105 S2P6	REAL	COMP	REAL
1266 S4	REAL	COMP	REAL
1172 TANA	REAL	COMP	REAL
347 THETA2	REAL	COMP	REAL
1824 TNA	REAL	COMP	REAL
1623 TREAL	REAL	COMP	REAL
352 VALUE	REAL	COMP	REAL
1703 VMX	REAL	COMP	REAL
2047 VMZ	REAL	COMP	REAL
50 M1	REAL	COMP	REAL
52 M3	REAL	COMP	REAL
54 M5	REAL	COMP	REAL
1432 XC	REAL	COMP	REAL
1270 XDM	REAL	COMP	REAL
445 XDTGMS	REAL	COMP	REAL
1446 XE	REAL	COMP	REAL
1107 XMISS	REAL	COMP	REAL
2 XN3	REAL	COMP	REAL
1123 YCJMP	REAL	COMP	REAL
1257 YQO	REAL	COMP	REAL
65 YDIGO	REAL	COMP	REAL
1583 YTA	REAL	COMP	REAL
1434 ZC	REAL	COMP	REAL
1364 ZDM	REAL	COMP	REAL
541 ZDTGMS	REAL	COMP	REAL
1542 ZE	REAL	COMP	REAL
J ZI	REAL	COMP	REAL

FILE NAMES MODE OUTPUT FMT

EXTERNALS TYPE ARGUS 7 1 LIBRARY 1 LIBRARY

INLINE FUNCTIONS TYPE ARGUS 1 INTRIN

STATEMENT LABELS	52	20	225	30	FMT
11 10	241	50	65	60	FMT
56 40	256	80	270	90	FMT
133 70	314	96	323	97	FMT
302 95					FMT

COMMON BLOCKS LENGTH 1165 73

STATISTICS PROJAM LENGTH 3628 242 CM LABELED COMMON LENGTH 23268 1238

SUBROUTINE PRIME
COMMON/COMAZ/LEVEL,PTS,XXS(50),XDTG,XDTG0,ZDTG0,RLB,C0SE,SP0,RI,
*CAM,ED01,THETA,RN,
*PPX(50),PPY(50),PPZ(50),TIME(50),THRS(30),XDTGHS(30)

*XDTGHS(30),ZDTGHS(30),XMAN(4,50),XMISS(7),NT
*XCOMP,YCOMP,ZCOMP,TAY(30),DELTAR(30),VM(30),G,GGG
*X00,Y00,Z00,DXG,DYG,DZG,S2,33,34,35,X04(30),Y04(30),Z04(30),
*RLB,SCALEP,F1,F2,F3,G1,G2,G3,XG,YG,ZG,S1,R2R,SR,SPL,CIL,STL,
*CPL,A1,VII,XE(30),YE(30),ZE(30),ZAL1,NER3,CLA,NPX,NX,CLAA(10),
*PARG,PAR,SCALET,REAL,TY(30),XTA,YTA,ZTA,SCALEV,QHM(10),QM
*SA,CA,VMX(50),VMY(50),VMZ(50)
*ECOS(17),HR7EE(17),F17T(9),FC177(9)

COMMON/MANEU/III,XDEM(30,45),YDEM(30,45),ZDEM(30,45),
*XDTG(30),YDTG(30),ZDTG(30),XPRIME,YPRIME,
*ZPRIME,TIME(50),ITRAJ(60),ITAU(60),III,NADJ
COMMON/ANG/ SIN50,COS50,SIN30,COS30
COMMON/DEL/PPXS(50),PPYS(50),PPZS(50),VMXS(50),VMYS(50),VMZS(50)
COMMON/CONB/XD,YD,ZD,XDTG,YDTG,ZDTG,XDEF,YDEF,ZDEF,ZZZ
*X0UE,Y0UE,Z0UE
COMMON/MU/ COSMJ1,SINMJ1,COSMJ2,SINMJ2,COSMJ3,SINMJ3
COMMON/HISD/XH(3),YH(3),ZH(3),RH(3),NOPT,ICN
COMMON/COMP/TS1,T99,TS8,CLMS(10),CLSI(10),CLSZ(10),NSAM,CL,TZT03,
*Z4,Q5,Q6,M1,M2,M3,M4,M5,M6,IFT,IPLANE,ICCN,S2P1,S1P1,A2P1,A1P1,
*S2P2,S1P2,A2P2,A1P2,S2P3,S1P3,A2P3,A1P3,S2P4,S1P4,A2P4,A1P4,S2P5,
*S1P5,A2P5,A1P5,S2P6,S1P6,A2P6,A1P6
REAL MU1,MU2,MU3
DATA RTD,OTR/57.9957795,0.01745329/

50 CONTINUE
TLAST = TIMES(NADJ)
TFIRST = TIMES(1)
ISPAN = TLAST - FIRST
THALF = (FIRST + TSPAN) / 2.
C*** INTERP RETURNS THESE VALUES FROM TAU ADJUSTED TARGET VELOCITY=TIME
C*** MANEUVER TABLE IN EARTH FIXED COORDINATES
CALL INTERP (TLAST,THA,ZDM,NT,NPX,ZDEL,NERR)
CALL INTERP (TFIRST,THA,ZDM,NT,NPX,ZDEL,NERR)
XDEL = (XDEL - XDEF) / TSPAN
CALL INTERP (TLAST,THA,YDM,NT,NPX,YDEL,NERR)
CALL INTERP (TFIRST,THA,YDM,NT,NPX,YDEL,NERR)
YDEL = (YDEL - YDEF) / TSPAN
CALL INTERP (TLAST,THA,ZDM,NT,NPX,ZDEL,NERR)
CALL INTERP (TFIRST,THA,ZDM,NT,NPX,ZDEL,NERR)
Z0UE = (ZDEL - ZDEF) / TSPAN - 32.174
C*** COMPONENTS OF AERODYNAMIC ACCELERATION IN EARTH FIXED COORDINATES
X0 = XDEL
Y0 = YDEL
Z0 = Z0UE
C*** TRANSFORM THESE TO LAUNCH COORDINATES
CALL GUID
C*** COMPONENTS OF AERODYNAMIC ACCELERATION IN LAUNCH COORDINATES
X0TG = XDTG
Y0TG = YDTG
Z0TG = ZDTG
C*** DEFINE X-Y- AND Z0TG
CALL INTERP (THALF,THA,XDTG,NT,NPX,X0TG5,NERR)
C*** INTERP RETURNS THESE VALUES FROM TAU ADJUSTED TARGET VELOCITY=TIME
C*** MANEUVER TABLE IN LAUNCH COORDINATES.

55

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CALL INTERP (THALF,TMA,YDTGM,NT,NPX,YDTG5,NERR)
 CALL INTERP (THALF,TMA,ZDTGM,NT,NPX,ZDTG5,NERR)

60 C*** CALCULATE THE ANGLES USED FOR THE T-MATRIX

51 IF(ZDTG5.EQ.0.0) MU1=ATAN2(YDTG5,ZDTG5)

IF(ZDTG5.EQ.0.0.AND.YDTG5.EQ.0.0) MU1=0.0

IF(ZDTG5.EQ.0.0.AND.YDTG5.EQ.0.0) MU1=90.*DTR

IF(ZDTG5.EQ.0.0.AND.YDTG5.LT.0.0) MU1=270.*DTR

52 IF(XDTG5.GT.0.0) GO TO 53

IF(XDTG5.LT.0.0) GO TO 54

GO TO 55

53 IF(YDTG5.EQ.0.0.AND.ZDTG5.EQ.0.0) MU2=270.*DTR

ARG=SQRT(YDTG5**2+ZDTG5**2)

IF(YDTG5.NE.0.0.OR.ZDTG5.NE.0.0) MU2=360.*DTR-ATAN2(XDTG5,ARG)

GO TO 55

54 IF(YDTG5.EQ.0.0.AND.ZDTG5.EQ.0.0) MU2=90.*DTR

ARG=SQRT(YDTG5**2+ZDTG5**2)

IF(YDTG5.NE.0.0.OR.ZDTG5.NE.0.0) MU2=-ATAN2(XDTG5,ARG)

55 CONTINUE

C*** DEFINE THE VALUES USED IN THE T-MATRIX

COSHUI = COS(MUI)

SINHUI = SIN(MUI)

COSHU2 = COS(MU2)

SINHU2 = SIN(MU2)

ARG1=ZDGTG*SINHUI-YDGTG*COSHUI

ARG2=XDGTG*COSHU2-YDGTG*SINHUI*SINHUI+ZDGTG*COSHUI*SINHUI

MU3=ATAN2(ARG1,ARG2)

COSHU3 = COS(MU3)

SINHUI = SIN(MU3)

IF(ICN.NE.1.AND.III.EQ.1) GO TO 70

IF(I31.EQ.1) GO TO 70

PRINT 952,LEVEL,XDGTG,YDGTG,ZDGTG,XDTG5,YDTG5,ZDTG5

70 CONTINUE

C*** CHANGE RADIANS TO DEGREES FOR PRINT OUT

MU1 = MU1 * RTD

MU2 = MU2 * RTD

MU3 = MU3 * RTD

IF(I31.EQ.1) GO TO 90

IF(ICN.EQ.1.OR.III.NE.1) PRINT 901,MU1,MU2,MU3

90 CONTINUE

862 FORMAT(10X,53H MANEUVER WAS IN PROGRESS AT TIME OF DATA COLLECTION

*/10X,8H LEVEL =,F10.4X,8H XDTG =,F10.4X,8H YDGTG =,F10.4X,

*/3H ZDGTG =,F10.4X,8H XDTG5 =,F10.4X,8H YDTG5 =,F10.4X,

*/3H ZDTG5 =,F10.4X

901 FORMAT(10X,10X,6H MU1 = F8.2,5X,6H MU2 = F8.2,5X,6H MU3 = F8.2)

RETURN

END

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SUBROUTINE PRIME 74774 OPT=1

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
I PRIVE

VARIABLES	SN	TYPE	RELOCATION	1620	ARG	REAL	COMA
1621 AAA	REAL	COMA		1620	ARG	REAL	COMA
1633 ARG1	REAL	COMA		434	ARG2	REAL	COMA
1644 A1	REAL	COMA		64	A1P1	REAL	COMA
1655 A1P2	REAL	COMA		74	A1P3	REAL	COMA
1666 A1P4	REAL	COMA		104	A1P5	REAL	COMA
1677 A1P6	REAL	COMA		63	A2P1	REAL	COMA
1688 A2P2	REAL	COMA		73	A2P3	REAL	COMA
1699 A2P4	REAL	COMA		103	A2P5	REAL	COMA
1710 A2P6	REAL	COMA		1702	CA	REAL	COMA
1721 CL1	REAL	COMA		1505	CL1A	REAL	COMA
1732 CL2	REAL	COMA		15	CLS1	REAL	COMA
1743 CL3	REAL	COMA		70	COSE	REAL	COMA
1754 COSMU1	REAL	COMA		2	COSMU2	REAL	COMA
1765 COSMU3	REAL	COMA		3	COSMU3	REAL	COMA
1776 COSMU4	REAL	COMA		1443	CPL	REAL	COMA
1787 CTR	REAL	COMA		1160	DELTA	REAL	COMA
1798 DTR	REAL	COMA		1261	DXG	REAL	COMA
1809 DYG	REAL	COMA		1263	JLG	REAL	COMA
1820 ECGS	REAL	COMA		74	E00T	REAL	COMA
1831 FC177	REAL	COMA		2173	F177	REAL	COMA
1842 F1	REAL	COMA		1425	F2	REAL	COMA
1853 F3	REAL	COMA		1254	J	REAL	COMA
1864 G1	REAL	COMA		1255	G6G	REAL	COMA
1875 G2	REAL	COMA		1430	G2	REAL	COMA
1886 G3	REAL	COMA		2152	H27EE	REAL	COMA
1897 ICH	REAL	COMA		60	ICON	REAL	COMA
1908 IFT	REAL	COMA		10332	111	REAL	COMA
1919 IFT	REAL	COMA		1	IPTS	REAL	COMA
1930 IFT	REAL	COMA		10236	1TAU	REAL	COMA
1941 IFT	REAL	COMA		0	111	REAL	COMA
1952 IFT	REAL	COMA		1	199	REAL	COMA
1963 IFT	REAL	COMA		413	101	REAL	COMA
1974 IFT	REAL	COMA		415	MU3	REAL	COMA
1985 IFT	REAL	COMA		1601	NERR	REAL	COMA
1996 IFT	REAL	COMA		1603	NPX	REAL	COMA
2007 IFT	REAL	COMA		1116	NT	REAL	COMA
2018 IFT	REAL	COMA		1617	PHO	REAL	COMA
2029 IFT	REAL	COMA		0	PPXS	REAL	COMA
2040 IFT	REAL	COMA		62	PPYS	REAL	COMA
2051 IFT	REAL	COMA		144	PPZS	REAL	COMA
2062 IFT	REAL	COMA		1666	3NH	REAL	COMA
2073 IFT	REAL	COMA		43	12	REAL	COMA
2084 IFT	REAL	COMA		45	24	REAL	COMA
2095 IFT	REAL	COMA		47	26	REAL	COMA
2106 IFT	REAL	COMA		67	RL9	REAL	COMA
2117 IFT	REAL	COMA		11	3H	REAL	COMA
2128 IFT	REAL	COMA		1436	RRR	REAL	COMA
2139 IFT	REAL	COMA		1701	SA	REAL	COMA
2150 IFT	REAL	COMA		1622	SCALET	REAL	COMA
2161 IFT	REAL	COMA		1	SINMU1	REAL	COMA
2172 IFT	REAL	COMA		5	SINMU3	REAL	COMA

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FINH 4.2+75348

7474 OPT=1

SUBROUTINE PRIME

VARIABLES	SN	TYPE	RELOCATION	ANG	0	SINSO	REAL	ANG
2 SINSCO	REAL	REAL	REAL	REAL	71 SPO	REAL	REAL	ANG
1440 SPL	REAL	REAL	REAL	REAL	1442 STL	REAL	REAL	COMA
1437 SR	REAL	REAL	REAL	REAL	52 S1P1	REAL	REAL	COMA
1435 SI	REAL	REAL	REAL	REAL	72 S1P3	REAL	REAL	COMP
56 S1P2	REAL	REAL	REAL	REAL	102 S1P5	REAL	REAL	COMP
76 S1P6	REAL	REAL	REAL	REAL	1264 S2	REAL	REAL	COMP
106 S1P5	REAL	REAL	REAL	REAL	55 S2P2	REAL	REAL	COMP
51 S2P1	REAL	REAL	REAL	REAL	75 S2P4	REAL	REAL	COMP
71 S2P3	REAL	REAL	REAL	REAL	105 S2P6	REAL	REAL	COMP
101 S2P5	REAL	REAL	REAL	REAL	1266 S4	REAL	REAL	COMA
1265 S3	REAL	REAL	REAL	REAL	1122 TAMA	REAL	REAL	COMA
1267 S5	REAL	REAL	REAL	REAL	421 THALF	REAL	REAL	COMA
417 IFIRST	REAL	REAL	REAL	REAL	325 TIME	REAL	REAL	COMA
75 THETAL	REAL	REAL	REAL	REAL	416 TLAST	REAL	REAL	COMA
10050 TIMES	REAL	REAL	REAL	REAL	407 THAS	REAL	REAL	COMA
1524 TMA	REAL	REAL	REAL	REAL	420 TSPAN	REAL	REAL	COMA
1623 TREAL	REAL	REAL	REAL	REAL	1703 VMX	REAL	REAL	COMA
1216 VM	REAL	REAL	REAL	REAL	1765 VMY	REAL	REAL	COMA
226 VMXS	REAL	REAL	REAL	REAL	2047 VMZ	REAL	REAL	COMA
310 VHS	REAL	REAL	REAL	REAL	1445 VTI	REAL	REAL	COMA
372 VHS	REAL	REAL	REAL	REAL	51 A2	REAL	REAL	COMP
50 M1	REAL	REAL	REAL	REAL	53 M4	REAL	REAL	COMP
52 M3	REAL	REAL	REAL	REAL	55 A6	REAL	REAL	COMP
54 M5	REAL	REAL	REAL	REAL	1117 XCOMP	REAL	REAL	COMP
1432 XC	REAL	REAL	REAL	REAL	12 XDDE	REAL	REAL	COMB
0 XD	REAL	REAL	REAL	REAL	6 XDEF	REAL	REAL	COMB
425 XUDTG	REAL	REAL	REAL	REAL	1 XDEM	REAL	REAL	MANEUV
422 XDEL	REAL	REAL	REAL	REAL	1256 XDO	REAL	REAL	COMA
1270 XDM	REAL	REAL	REAL	REAL	7723 XDTGM	REAL	REAL	MANEUV
3 XDTG	REAL	REAL	REAL	REAL	64 XDTGO	REAL	REAL	COMA
445 XDTGMS	REAL	REAL	REAL	REAL	1445 XE	REAL	REAL	COMA
430 XDTG5	REAL	REAL	REAL	REAL	577 XMAN	REAL	REAL	COMA
0 XM	REAL	REAL	REAL	REAL	10055 XPRIME	REAL	REAL	MANEUV
1107 XMISS	REAL	REAL	REAL	REAL	8 XAS	REAL	REAL	COMA
1692 XTA	REAL	REAL	REAL	REAL	1120 YCOMP	REAL	REAL	COMA
1433 X6	REAL	REAL	REAL	REAL	13 YODE	REAL	REAL	COMB
1 YD	REAL	REAL	REAL	REAL	7 YDEF	REAL	REAL	COMB
426 YDGTG	REAL	REAL	REAL	REAL	2507 YUEM	REAL	REAL	MANEUV
423 YJEL	REAL	REAL	REAL	REAL	1257 YDO	REAL	REAL	COMA
1326 YDM	REAL	REAL	REAL	REAL	7761 YDTGM	REAL	REAL	MANEUV
4 YDTG	REAL	REAL	REAL	REAL	65 YDTGO	REAL	REAL	COMA
503 YDTGMS	REAL	REAL	REAL	REAL	1504 YE	REAL	REAL	COMA
431 YDTG5	REAL	REAL	REAL	REAL	10056 YPRIME	REAL	REAL	MANEUV
3 YH	REAL	REAL	REAL	REAL	1600 ZALT	REAL	REAL	COMA
1653 YTA	REAL	REAL	REAL	REAL	1121 ZCOMP	REAL	REAL	COMA
1434 ZC	REAL	REAL	REAL	REAL	14 ZODE	REAL	REAL	COMB
2 ZD	REAL	REAL	REAL	REAL	10 ZDEF	REAL	REAL	COMB
427 ZDGTG	REAL	REAL	REAL	REAL	5215 ZDEM	REAL	REAL	MANEUV
424 ZD-L	REAL	REAL	REAL	REAL	1260 ZDO	REAL	REAL	COMA
1354 ZJ1	REAL	REAL	REAL	REAL	10017 ZDTGM	REAL	REAL	COMA
5 ZDTG	REAL	REAL	REAL	REAL	66 ZDTGO	REAL	REAL	COMA
541 ZDTGMS	REAL	REAL	REAL	REAL	1542 ZE	REAL	REAL	COMA
432 ZDTG5	REAL	REAL	REAL	REAL	10057 ZPRIME	REAL	REAL	MANEUV
6 ZH	REAL	REAL	REAL	REAL	11 ZZ	REAL	REAL	COMB
1664 ZTA	REAL	REAL	REAL	REAL				

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FINR 6.2475368

OPT=1

74/76

SUBROUTINE PRIME

FILE NAMES MODE
OUTPUT FMT

EXTERNALS TYPE ARGS
STANZ REAL 2 LIBRARY
GUID 0
SIN REAL 1 LIBRARY

STATEMENT LABELS
0 50 INACTIVE 0 51 INACTIVE 0 52 INACTIVE
106 53 131 54 131 55
206 70 221 90 354 862 FMT
403 301 FMT

COMMON BLOCKS LENGTH
COMA 1165
MANEUV 4316
ANG 4
DELT 300
COMU 13
NU 6
MISO 14
COMP 73

STATISTICS
PROGRAM LENGTH 4358 285
CM LABELED COMMON LENGTH 134038 5091

77 = C034U1 *C034U2

SUBROUTINE MISCON 74774 OPT=1 FTNH 4.2+75368 01/12/76 14.31.22. PAGE 1

SUBROUTINE MISCON

C THIS SUBROUTINE CALCULATES THE MISS DISTANCES IN THE TARGET
C COORDINATE SYSTEM

5 C
C
C
COMMON/HISD/XN(3),YN(3),ZN(3),RN(3),N,ICN
COMMON/DELTA/X(50),Y(50),Z(50),VX(50),VY(50),VZ(50)
COMMON /RNU/ COSMU1,SINMU1,COSMU2,SINMU2,COSMU3,SINMU3
COMMON /COMB/XD,YD,ZD,XDTG,YDTG,ZDTG,XDEF,YDEF,ZDEF,ZZZ

10 *XDE,YDE,ZDE
COMMON/NAMEUW/ITT,XDEM(30,45),YDEM(30,45),ZDEM(30,45),
XDTG(30),YDTG(30),ZDTG(30),XPRIME,YPRIME,
ZPRIME,TINES(50),ITRAJ(60),ITAU(60),III,NADJ
C3-MON/COMA/LEVEL,IPFS,XKS(50),XDTGO,YDTGO,ZDTGO,RLB,COSE,SPGR,RI,
*GAF,EDUT,THETAL,N,

15 *PXX(50),PPY(50),PPZ(50),TINE(50),THAS(30),XDTGMS(30)
*YDTGMS(30),ZDTGMS(30),XMAN(4,50),XMISS(7),NT
*XCMP,YCOMP,ZCOMP,TAMA(30),DELTA(30),VM(30),G,GG6
*XJO,YJO,ZJO,DYG,DZG,S2,S3,S4,S5,XDM(30),YDM(30),ZDM(30),
*RLK,SCALEP,FI,F2,F3,G1,G2,G3,XG,YG,ZG,ISI,KRRR,SR,SPL,CTL,STL,
*CPL,A1,VII,XE(30),YE(30),ZE(30),ZALT,NER3,CLAN,XPX,NX,CLAA(10),
*PHJ,ARG,AAA,SCALET,TREAL,THA(30),XTA,YTA,ZTA,SCALEV,QHH(10),QM
*S4,C3,VHX(50),VNY(50),VMZ(50)

25 *CJCS(17),HR7EE(17),F17(19),FC177(19)
COMMON/STAR/FA,FYA,FZA,FXB,FYB,FZB,FXC,FYC,FZC,AT,VT
COMMON/COMD/COSA,COSB,CJSCGYA,ZA
COMMON/COMP/IS1,199,188,CLMS(10),CLS1(10),CLS2(10),NSAM,Q1,Q2,Q3,
*S4,25,26,27,28,29,30,31,32,33,34,35,36,37,38,39,40,41,42,43,44,45,46,47,48,49,50,51,52,53,54,55,56,57,58,59,60,61,62,63,64,65,66,67,68,69,70,71,72,73,74,75,76,77,78,79,80,81,82,83,84,85,86,87,88,89,90,91,92,93,94,95,96,97,98,99,100,101,102,103,104,105,106,107,108,109,110,111,112,113,114,115,116,117,118,119,120,121,122,123,124,125,126,127,128,129,130,131,132,133,134,135,136,137,138,139,140,141,142,143,144,145,146,147,148,149,150,151,152,153,154,155,156,157,158,159,160,161,162,163,164,165,166,167,168,169,170,171,172,173,174,175,176,177,178,179,180,181,182,183,184,185,186,187,188,189,190,191,192,193,194,195,196,197,198,199,200,201,202,203,204,205,206,207,208,209,210,211,212,213,214,215,216,217,218,219,220,221,222,223,224,225,226,227,228,229,230,231,232,233,234,235,236,237,238,239,240,241,242,243,244,245,246,247,248,249,250,251,252,253,254,255,256,257,258,259,260,261,262,263,264,265,266,267,268,269,270,271,272,273,274,275,276,277,278,279,280,281,282,283,284,285,286,287,288,289,290,291,292,293,294,295,296,297,298,299,300,301,302,303,304,305,306,307,308,309,310,311,312,313,314,315,316,317,318,319,320,321,322,323,324,325,326,327,328,329,330,331,332,333,334,335,336,337,338,339,340,341,342,343,344,345,346,347,348,349,350,351,352,353,354,355,356,357,358,359,360,361,362,363,364,365,366,367,368,369,370,371,372,373,374,375,376,377,378,379,380,381,382,383,384,385,386,387,388,389,390,391,392,393,394,395,396,397,398,399,400,401,402,403,404,405,406,407,408,409,410,411,412,413,414,415,416,417,418,419,420,421,422,423,424,425,426,427,428,429,430,431,432,433,434,435,436,437,438,439,440,441,442,443,444,445,446,447,448,449,450,451,452,453,454,455,456,457,458,459,460,461,462,463,464,465,466,467,468,469,470,471,472,473,474,475,476,477,478,479,480,481,482,483,484,485,486,487,488,489,490,491,492,493,494,495,496,497,498,499,500,501,502,503,504,505,506,507,508,509,510,511,512,513,514,515,516,517,518,519,520,521,522,523,524,525,526,527,528,529,530,531,532,533,534,535,536,537,538,539,540,541,542,543,544,545,546,547,548,549,550,551,552,553,554,555,556,557,558,559,560,561,562,563,564,565,566,567,568,569,570,571,572,573,574,575,576,577,578,579,580,581,582,583,584,585,586,587,588,589,590,591,592,593,594,595,596,597,598,599,600,601,602,603,604,605,606,607,608,609,610,611,612,613,614,615,616,617,618,619,620,621,622,623,624,625,626,627,628,629,630,631,632,633,634,635,636,637,638,639,640,641,642,643,644,645,646,647,648,649,650,651,652,653,654,655,656,657,658,659,660,661,662,663,664,665,666,667,668,669,670,671,672,673,674,675,676,677,678,679,680,681,682,683,684,685,686,687,688,689,690,691,692,693,694,695,696,697,698,699,700,701,702,703,704,705,706,707,708,709,710,711,712,713,714,715,716,717,718,719,720,721,722,723,724,725,726,727,728,729,730,731,732,733,734,735,736,737,738,739,740,741,742,743,744,745,746,747,748,749,750,751,752,753,754,755,756,757,758,759,760,761,762,763,764,765,766,767,768,769,770,771,772,773,774,775,776,777,778,779,780,781,782,783,784,785,786,787,788,789,790,791,792,793,794,795,796,797,798,799,800,801,802,803,804,805,806,807,808,809,810,811,812,813,814,815,816,817,818,819,820,821,822,823,824,825,826,827,828,829,830,831,832,833,834,835,836,837,838,839,840,841,842,843,844,845,846,847,848,849,850,851,852,853,854,855,856,857,858,859,860,861,862,863,864,865,866,867,868,869,870,871,872,873,874,875,876,877,878,879,880,881,882,883,884,885,886,887,888,889,890,891,892,893,894,895,896,897,898,899,900,901,902,903,904,905,906,907,908,909,910,911,912,913,914,915,916,917,918,919,920,921,922,923,924,925,926,927,928,929,930,931,932,933,934,935,936,937,938,939,940,941,942,943,944,945,946,947,948,949,950,951,952,953,954,955,956,957,958,959,960,961,962,963,964,965,966,967,968,969,970,971,972,973,974,975,976,977,978,979,980,981,982,983,984,985,986,987,988,989,990,991,992,993,994,995,996,997,998,999,1000,1001,1002,1003,1004,1005,1006,1007,1008,1009,1010,1011,1012,1013,1014,1015,1016,1017,1018,1019,1020,1021,1022,1023,1024,1025,1026,1027,1028,1029,1030,1031,1032,1033,1034,1035,1036,1037,1038,1039,1040,1041,1042,1043,1044,1045,1046,1047,1048,1049,1050,1051,1052,1053,1054,1055,1056,1057,1058,1059,1060,1061,1062,1063,1064,1065,1066,1067,1068,1069,1070,1071,1072,1073,1074,1075,1076,1077,1078,1079,1080,1081,1082,1083,1084,1085,1086,1087,1088,1089,1090,1091,1092,1093,1094,1095,1096,1097,1098,1099,1100,1101,1102,1103,1104,1105,1106,1107,1108,1109,1110,1111,1112,1113,1114,1115,1116,1117,1118,1119,1120,1121,1122,1123,1124,1125,1126,1127,1128,1129,1130,1131,1132,1133,1134,1135,1136,1137,1138,1139,1140,1141,1142,1143,1144,1145,1146,1147,1148,1149,1150,1151,1152,1153,1154,1155,1156,1157,1158,1159,1160,1161,1162,1163,1164,1165,1166,1167,1168,1169,1170,1171,1172,1173,1174,1175,1176,1177,1178,1179,1180,1181,1182,1183,1184,1185,1186,1187,1188,1189,1190,1191,1192,1193,1194,1195,1196,1197,1198,1199,1200,1201,1202,1203,1204,1205,1206,1207,1208,1209,1210,1211,1212,1213,1214,1215,1216,1217,1218,1219,1220,1221,1222,1223,1224,1225,1226,1227,1228,1229,1230,1231,1232,1233,1234,1235,1236,1237,1238,1239,1240,1241,1242,1243,1244,1245,1246,1247,1248,1249,1250,1251,1252,1253,1254,1255,1256,1257,1258,1259,1260,1261,1262,1263,1264,1265,1266,1267,1268,1269,1270,1271,1272,1273,1274,1275,1276,1277,1278,1279,1280,1281,1282,1283,1284,1285,1286,1287,1288,1289,1290,1291,1292,1293,1294,1295,1296,1297,1298,1299,1300,1301,1302,1303,1304,1305,1306,1307,1308,1309,1310,1311,1312,1313,1314,1315,1316,1317,1318,1319,1320,1321,1322,1323,1324,1325,1326,1327,1328,1329,1330,1331,1332,1333,1334,1335,1336,1337,1338,1339,1340,1341,1342,1343,1344,1345,1346,1347,1348,1349,1350,1351,1352,1353,1354,1355,1356,1357,1358,1359,1360,1361,1362,1363,1364,1365,1366,1367,1368,1369,1370,1371,1372,1373,1374,1375,1376,1377,1378,1379,1380,1381,1382,1383,1384,1385,1386,1387,1388,1389,1390,1391,1392,1393,1394,1395,1396,1397,1398,1399,1400,1401,1402,1403,1404,1405,1406,1407,1408,1409,1410,1411,1412,1413,1414,1415,1416,1417,1418,1419,1420,1421,1422,1423,1424,1425,1426,1427,1428,1429,1430,1431,1432,1433,1434,1435,1436,1437,1438,1439,1440,1441,1442,1443,1444,1445,1446,1447,1448,1449,1450,1451,1452,1453,1454,1455,1456,1457,1458,1459,1460,1461,1462,1463,1464,1465,1466,1467,1468,1469,1470,1471,1472,1473,1474,1475,1476,1477,1478,1479,1480,1481,1482,1483,1484,1485,1486,1487,1488,1489,1490,1491,1492,1493,1494,1495,1496,1497,1498,1499,1500,1501,1502,1503,1504,1505,1506,1507,1508,1509,1510,1511,1512,1513,1514,1515,1516,1517,1518,1519,1520,1521,1522,1523,1524,1525,1526,1527,1528,1529,1530,1531,1532,1533,1534,1535,1536,1537,1538,1539,1540,1541,1542,1543,1544,1545,1546,1547,1548,1549,1550,1551,1552,1553,1554,1555,1556,1557,1558,1559,1560,1561,1562,1563,1564,1565,1566,1567,1568,1569,1570,1571,1572,1573,1574,1575,1576,1577,1578,1579,1580,1581,1582,1583,1584,1585,1586,1587,1588,1589,1590,1591,1592,1593,1594,1595,1596,1597,1598,1599,1600,1601,1602,1603,1604,1605,1606,1607,1608,1609,1610,1611,1612,1613,1614,1615,1616,1617,1618,1619,1620,1621,1622,1623,1624,1625,1626,1627,1628,1629,1630,1631,1632,1633,1634,1635,1636,1637,1638,1639,1640,1641,1642,1643,1644,1645,1646,1647,1648,1649,1650,1651,1652,1653,1654,1655,1656,1657,1658,1659,1660,1661,1662,1663,1664,1665,1666,1667,1668,1669,1670,1671,1672,1673,1674,1675,1676,1677,1678,1679,1680,1681,1682,1683,1684,1685,1686,1687,1688,1689,1690,1691,1692,1693,1694,1695,1696,1697,1698,1699,1700,1701,1702,1703,1704,1705,1706,1707,1708,1709,1710,1711,1712,1713,1714,1715,1716,1717,1718,1719,1720,1721,1722,1723,1724,1725,1726,1727,1728,1729,1730,1731,1732,1733,1734,1735,1736,1737,1738,1739,1740,1741,1742,1743,1744,1745,1746,1747,1748,1749,1750,1751,1752,1753,1754,1755,1756,1757,1758,1759,1760,1761,1762,1763,1764,1765,1766,1767,1768,1769,1770,1771,1772,1773,1774,1775,1776,1777,1778,1779,1780,1781,1782,1783,1784,1785,1786,1787,1788,1789,1790,1791,1792,1793,1794,1795,1796,1797,1798,1799,1800,1801,1802,1803,1804,1805,1806,1807,1808,1809,1810,1811,1812,1813,1814,1815,1816,1817,1818,1819,1820,1821,1822,1823,1824,1825,1826,1827,1828,1829,1830,1831,1832,1833,1834,1835,1836,1837,1838,1839,1840,1841,1842,1843,1844,1845,1846,1847,1848,1849,1850,1851,1852,1853,1854,1855,1856,1857,1858,1859,1860,1861,1862,1863,1864,1865,1866,1867,1868,1869,1870,1871,1872,1873,1874,1875,1876,1877,1878,1879,1880,1881,1882,1883,1884,1885,1886,1887,1888,1889,1890,1891,1892,1893,1894,1895,1896,1897,1898,1899,1900,1901,1902,1903,1904,1905,1906,1907,1908,1909,1910,1911,1912,1913,1914,1915,1916,1917,1918,1919,1920,1921,1922,1923,1924,1925,1926,1927,1928,1929,1930,1931,1932,1933,1934,1935,1936,1937,1938,1939,1940,1941,1942,1943,1944,1945,1946,1947,1948,1949,1950,1951,1952,1953,1954,1955,1956,1957,1958,1959,1960,1961,1962,1963,1964,1965,1966,1967,1968,1969,1970,1971,1972,1973,1974,1975,1976,1977,1978,1979,1980,1981,1982,1983,1984,1985,1986,1987,1988,1989,1990,1991,1992,1993,1994,1995,1996,1997,1998,1999,2000,2001,2002,2003,2004,2005,2006,2007,2008,2009,2010,2011,2012,2013,2014,2015,2016,2017,2018,2019,2020,2021,2022,2023,2024,2025,2026,2027,2028,2029,2030,2031,2032,2033,2034,2035,2036,2037,2038,2039,2040,2041,2042,2043,2044,2045,2046,2047,2048,2049,2050,2051,2052,2053,2054,2055,2056,2057,2058,2059,2060,2061,2062,2063,2064,2065,2066,2067,2068,2069,2070,2071,2072,2073,2074,2075,2076,2077,2078,2079,2080,2081,2082,2083,2084,2085,2086,2087,2088,2089,2090,2091,2092,2093,2094,2095,2096,2097,2098,2099,2100,2101,2102,2103,2104,2105,2106,2107,2108,2109,2110,2111,2112,2113,2114,2115,2116,2117,2118,2119,2120,2121,2122,2123,2124,2125,2126,2127,2128,2129,2130,2131,2132,2133,2134,2135,2136,2137,2138,2139,2140,2141,2142,2143,2144,2145,2146,2147,2148,2149,2150,2151,2152,2153,2154,2155,2156,2157,2158,2159,2160,2161,2162,2163,2164,2165,2166,2167,2168,2169,2170,2171,2172,2173,2174,2175,2176,2177,2178,2179,2180,2181,2182,2183,2184,2185,2186,2187,2188,2189,2190,2191,2192,2193,2194,2195,2196,2197,2198,2199,2200,2201,2202,2203,2204,2205,2206,2207,2208,2209,2210,2211,2212,2213,2214,2215,2216,2217,2218,2219,2220,2221,2222,2223,2224,2225,2226,2227,2228,2229,2230,2231,2232,2233,2234,2235,2236,2237,2238,2239,2240,2241,2242,2243,2244,2245,2246,2247,2248,2249,2250,2251,2252,2253,2254,2255,2256,2257,2258,2259,2260,2261,2262,2263,2264,2265,2266,2267,2268,2269,2270,2271,2272,2273,2274,2275,2276,2277,2278,2279,2280,2281,2282,2283,2284,2285,2286,2287,2288,2289,2290,2291,2292,2293,2294,2295,2296,2297,2298,2299,2300,2301,2302,2303,2304,2305,2306,2307,2308,2309,2310,2311,2312,2313,2314,2315,2316,2317,2318,2319,2320,2321,2322,2323,2324,2325,2326,2327,2328,2329,2330,2331,2332,2333,2334,2335,2336,2337,2338,2339,2340,2341,2342,2343,2344,2345,2346,2347,2348,2349,2350,2351,2352,2353,2354,2355,2356,2357,2358,2359,2360,2361,2362,2363,2364,2365,2366,2367,2368,2369,2370,2371,2372,2373,2374,2375,2376,2377,2378,2379,2380,2381,2382,2383,2384,2385,2386,2387,2388,2389,2390,2391,2392,2393,2394,2395,2396,2397,2398,2399,2400,2401,2402,2403,2404,2405,2406,2407,2408,2409,2410,2411,2412,2413,2414,2415,2416,2417,2418,2419,2420,2421,2422,2423,2424,2425,2426,2427,2428,2429,2430,2431,2432,2433,2434,2435,2436,2437,2438,2439,2440,2441,2442,2443,2444,2445,2446,2447,2448,2449,2450,2451,2452,2453,2454,2455,2456,2457,2458,2459,2460,2461,2462,2463,2464,2465,2466,2467,2468,2469,2470,2471,2472,2473,2474,2475,2476,2477,2478,2479,2480,2481,2482,2483,2484,2485,2486,2487,2488,2489,2490,2491,2492,2493,249

```

        FXC = FX
        FYC = FY
        FZC = FZ
    60      19 CONTINUE
            IF(IIT.EQ.1.OR.VVVV.LT.338.0).AND.IS1.NE.1) PRINT 67
            IF(IIT.NE.1.OR.VVVV.GE.338.0).AND.IS1.NE.1) PRINT 66
            DO 1 I=1,N
                UX = X(I)
                UY = Y(I)
                UZ = Z(I)
    65      C*** NEXT CARD IS TAPE SPECIFIC FOR IIT=1 FOR STATIONARY TARGET
            IF(IIT.EQ.1) GO TO 30
            IF(VVVV.LT.338.0) GO TO 30
            C TRANSFORM (MISSILE MINUS TARGET) LAUNCH COORDINATES TO GENERALIZED
            C TARGET COORDINATES
            C REFERENCED TO ORIGIN AT TAILPIPE
            XT(1) = FXA*DX + FYA*DY + FZA*DZ
            YT(1) = FXB*DX + FYB*DY + FZB*DZ
            ZT(1) = FXC*DX + FYC*DY + FZC*DZ
            C CALCULATE TARGET ANGLE OF ATTACK
            AAA=1116.89+0.003894*ZZZ
            VT=SQRT(XDEF**2+YDEF**2+ZDEF**2)
            ARG=0.00003*ZZZ
            PHO=0.00237692*EXP(ARG)
            QH=VT/AAA
            HPX=Z
            NX=8
            CALL INTERP (QH,PHO,CLAA,NX,HPX,CLAA,NERX)
            AT=18500.0
            ST=248.0
            AT=2.*MT*SQRT(XDDE**2+YDDE**2+ZDDE**2)/(PHO*VT*VT*ST*CLA*32.174)
            IF(IS1.EQ.1) GO TO 5
            IF(ICN.EQ.1.AND.I.EQ.1) PRINT 25,AT
    70      9 CONTINUE
            AT=4*PHO
            XS=XT(1)
            YS=YT(1)
            ZS=ZT(1)
    75      C TRANSFORM GENERALIZED TARGET COORDINATES TO TARGET FIXED COORDINATES
            C REFERENCED TO ORIGIN AT TAILPIPE
            XT(1)=ZS*COS(AT)*XS*SIN(AT)
            YT(1)=YS
            ZT(1)=XS*COS(AT)-ZS*SIN(AT)
            GO TO 4
    80      C TRANSFORM MISSILE LAUNCH COORDINATES TO TARGET EARTH FIXED
            C COORDINATES. TARGET IS STATIONARY OR MOVING AT LESS THAN 338 FT/SEC
            30 XT(1)=UX*S2-DY*SPL+DZ*S3
            YT(1)=UX*S4+DY*CPL+DZ*S5
            ZT(1)=DX*STL+DZ*GTL
            4 CONTINUE
            IF(IS1.NE.1) PRINT 15,XT(1),YT(1),ZT(1)
    85      15 FORMAT(13X,E11.4)
            SHX=SHX+AT(1)
            1 SMX2=SMX2+XT(1)*XT(1)
            C
            DO 20 I=1,N
                T(I) = YT(I)
    90
    100
    110
    120
    130
    140
    150
    160
    170
    180
    190
    200
    210
    220
    230
    240
    250
    260
    270
    280
    290
    300
    310
    320
    330
    340
    350
    360
    370
    380
    390
    400
    410
    420
    430
    440
    450
    460
    470
    480
    490
    500
    510
    520
    530
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    610
    620
    630
    640
    650
    660
    670
    680
    690
    700
    710
    720
    730
    740
    750
    760
    770
    780
    790
    800
    810
    820
    830
    840
    850
    860
    870
    880
    890
    900
    910
    920
    930
    940
    950
    960
    970
    980
    990
    
```

115 20 CONTINUE
C CALCULATE COEFFICIENTS FOR MISSILE PATH PROJECTIONS IN TARGET FIXED

C COORDINATES

C REFERENCED TO ORIGIN AT TAILPIPE

21 SMT=0.0

SMT=0.

DO 2 I=1,N

SMT=SMT+T(I)

2 SMT=SMT+T(I)*T(I)

D=KN*SMX2-SMX*SMX

U=(SMT*SMX2-SMX*SMX)/D

A=(KN*SMX-SMT*SMX)/D

C

II=II+1

99 GO TO(10,11),II

C YF-AXIS INTERCEPT AND SLOPE OF PATH PROJECTION IN XF-YF PLANE

C REFERENCED TO ORIGIN AT TAILPIPE

10 Y4(1)=B

Y4=A

C

102 DO 3 I=1,N

T(I)=Z(I)

3 CONTINUE

GO TO 21

C ZF-AXIS INTERCEPT AND SLOPE OF PATH PROJECTION IN XF-ZF PLANE

C REFERENCED TO ORIGIN AT TAILPIPE

11 ZH(1)=B

Z4=A

C

C XF-AXIS COORDINATE OF PATH PIERCING POINT IN XF-YF PLANE

C REFERENCED TO ORIGIN AT TAILPIPE

X4(1)=-Z4(1)/Z4

C YF-AXIS COORDINATE OF PATH PIERCING POINT IN XF-YF PLANE

C REFERENCED TO ORIGIN AT TAILPIPE

Y4(2)=Y4(1)+Y4*XM(2)

C

C XF-AXIS COORDINATE OF PATH PIERCING POINT IN XF-ZF PLANE

C REFERENCED TO ORIGIN AT TAILPIPE

X4(3)=-Y4(1)/Y4

C ZF-AXIS COORDINATE OF PATH PIERCING POINT IN XF-ZF PLANE

C REFERENCED TO ORIGIN AT TAILPIPE

Z4(3)=Z4(1)+Z4*XM(3)

C

X4(1)=0.

Z4(2)=0.

Y4(3)=0.

C CALCULATE NEAREST APPROACH TO ORIGIN IN YF-ZF, XF-YF AND XF-ZF PLANES

C REFERENCED TO ORIGIN AT TAILPIPE

DO 15 I=1,3

155 X4(I)=SQR(X4(I)*X4(I)+Y4(I)*Y4(I)+Z4(I)*Z4(I))

DX=DX

C

25 FORMAT(10X,25H TARGET ANGLE OF ATTACK =,F5.2,3X,25H DEGT

66 FORMAT(10X,50H TARGET FIXED COORDINATES OF MISSILE REFERENCED TO

10H TAILPIPE,77)

67 FORMAT(10X,43H TARGET EARTH FIXED COORDINATES OF MISSILE,77)

C

SUBROUTINE MISCOM 74774 OPT=1

FINH 4.2475308

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PAGE

RETURN
END

SUBROUTINE HISCON 74774 OPT=1 FYNH 4.2+75348 01/12/75 14.31.22. PAGE 3

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
1 HISCON

VARIABLES	SN	TYPE	RELOCATION	1621	AAA	REAL	COMA
1523 ARG	4	REAL	COMA	4	AS	REAL	EXTRA
7 ASE0	11	REAL	EXTRA	11	AT	REAL	GTARG
1446 A1	64	REAL	COMA	64	A1P1	REAL	COMP
70 A1P2	74	REAL	COMP	74	A1P3	REAL	COMP
100 A1P4	104	REAL	COMP	104	A1P5	REAL	COMP
110 A1P6	63	REAL	COMP	63	A2P1	REAL	COMP
57 A2P2	73	REAL	COMP	73	A2P3	REAL	COMP
77 A2P4	103	REAL	COMP	103	A2P5	REAL	COMP
107 A2P5	661	REAL	COMP	661	3	REAL	COMP
1702 CA	1602	REAL	COMA	1602	CLA	REAL	COMA
1605 CLA3	3	REAL	COMA	3	CLMS	REAL	COMP
15 CLS1	27	REAL	COMP	27	CLS2	REAL	COMP
22 CLV	23	REAL	EXTRA	23	CLZ	REAL	EXTRA
17 CO	0	REAL	EXTRA	0	COSA	REAL	COMP
1 COSB	70	REAL	COMA	70	COSB	REAL	COMA
2 COSG	0	REAL	COMD	0	COSMU1	REAL	MU
2 COSMU2	4	REAL	MU	4	COSMU3	REAL	MU
1443 CPL	1441	REAL	COMA	1441	CTL	REAL	COMA
20 CX	21	REAL	EXTRA	21	CY	REAL	EXTRA
13 C1	460	REAL	EXTRA	460	J	REAL	EXTRA
436 JDX	1160	REAL	DELTA	1160	DELTA	REAL	COMA
435 DTR	1	REAL	REAL	1	DX	REAL	EXTRA
1251 DAG	447	REAL	COMA	447	DY	REAL	REAL
1252 JYG	450	REAL	COMA	450	DZ	REAL	REAL
1263 JZG	2131	REAL	COMA	2131	ECOS	REAL	COMA
74 EDO1	2204	REAL	COMA	2204	FC177	REAL	COMA
2173 F177	443	REAL	COMA	443	FX	REAL	GTARG
0 FXA	3	REAL	GTARG	3	FXH	REAL	REAL
6 FHB	444	REAL	GTARG	444	FY	REAL	REAL
1 FYA	4	REAL	GTARG	4	FYB	REAL	GTARG
7 FYC	445	REAL	GTARG	445	FZ	REAL	GTARG
2 FZA	5	REAL	GTARG	5	FZB	REAL	GTARG
10 FZC	1424	REAL	GTARG	1424	F1	REAL	COMA
1425 F2	1425	REAL	COMA	1425	F3	REAL	COMA
1254 G	73	REAL	COMA	73	GAM	REAL	COMA
1255 GGG	1427	REAL	COMA	1427	G1	REAL	COMA
1430 G2	1431	REAL	COMA	1431	G3	REAL	COMA
2152 H87EE	446	REAL	ARRAY	446	I	REAL	COMA
15 ICLN	60	INTEGER	MISO	60	ICON	INTEGER	COMP
56 IFT	437	INTEGER	COMP	437	II	INTEGER	COMP
10332 III	57	INTEGER	MANEUV	57	IPLANE	INTEGER	COMP
1 IPTS	0	INTEGER	COMA	0	ISI	INTEGER	COMP
10236 ITAU	10142	INTEGER	ARRAY	10142	ITRAJ	INTEGER	MANEUV
0 IIT	2	INTEGER	MANEUV	2	I8A	INTEGER	COMP
1 I93	3	INTEGER	COMP	3	KKK	INTEGER	EXTRA
0 LEVEL	14	INTEGER	COMA	14	N	INTEGER	MISO
10333 MADJ	1601	INTEGER	MANEUV	1601	NERR	INTEGER	COMA
0 APTS	1603	INTEGER	EXTRA	1603	VFX	INTEGER	COMA
41 NSAM	1116	INTEGER	COMP	1116	NT	INTEGER	COMA
1604 NX	1617	INTEGER	COMA	1617	PHO	REAL	COMA

VARIABLES	SN	TYPE	RELOCATION	161	PPY	REAL	ARRAY	COMA
77 PPX	REAL	COMA		1700	1M	REAL		COMA
243 PPZ	REAL	COMA		42	11	REAL		COMA
1666 QMH	REAL	COMA		46	13	REAL		COMA
43 72	REAL	COMA		46	15	REAL		COMA
45 24	REAL	COMA		10	2	REAL		COMA
47 16	REAL	COMA		67	RLB	REAL		COMA
72 21	REAL	COMA		11	3M	REAL		COMA
1422 RL3K	REAL	COMA		1436	RRR	REAL	ARRAY	MISD
76 RN	REAL	COMA		6	SC	REAL		COMA
1701 SE	REAL	COMA		1423	SCALEP	REAL		COMA
11 SCALEL	REAL	COMA		1665	SCALEV	REAL		COMA
1622 SCLET	REAL	COMA		1	SINHUI	REAL		MU
5 SE0	REAL	COMA		5	SINHUI3	REAL		MU
3 SINMU2	REAL	MU		441	SMX	REAL		MU
455 SMI	REAL			442	SMX2	REAL		COMA
477 SPYT	REAL	COMA		71	SPO	REAL		COMA
1440 SPL	REAL	COMA		452	ST	REAL		COMA
1437 SR	REAL	COMA		1435	31	REAL		COMA
1442 STL	REAL	COMA		66	SIP2	REAL		COMA
52 SIP1	REAL	COMA		76	SIP4	REAL		COMA
72 SIP3	REAL	COMA		106	SIP6	REAL		COMA
102 SIP5	REAL	COMA		61	SIP1	REAL		COMA
1254 S2	REAL	COMA		71	SIP3	REAL		COMA
65 S2P2	REAL	COMA		101	S2P5	REAL		COMA
75 S2P4	REAL	COMA		1265	S3	REAL		COMA
109 S2P6	REAL	COMA		1267	S5	REAL		COMA
1255 S4	REAL	COMA		1122	TAMA	REAL	ARRAY	COMA
463 T	REAL	EXTRA		75	THETAL	REAL		COMA
107 TMC	REAL	COMA		10060	TIMES	REAL	ARRAY	MANEUV
325 T1YE	REAL	COMA		407	TMAS	REAL	ARRAY	COMA
1624 TMA	REAL	COMA		24	TRP	REAL		EXTRA
1623 TSCALE	REAL	COMA		1703	VHX	REAL	ARRAY	COMA
1216 VM	REAL	COMA		1789	VHY	REAL	ARRAY	COMA
328 VHX	REAL	DELT		2847	VHZ	REAL	ARRAY	COMA
318 VHY	REAL	DELT		12	VT	REAL		STAR
372 VHZ	REAL	DELT		12	VVVV	REAL		EXTRA
1445 VTI	REAL	COMA		50	W1	REAL		COMA
451 W1	REAL	COMA		52	W3	REAL		COMA
51 W2	REAL	COMA		54	W5	REAL		COMA
53 W4	REAL	COMA		0	X	REAL	ARRAY	DELT
55 W6	REAL	COMA		1117	XCOMP	REAL		COMA
1432 XC	REAL	COMA		12	XODE	REAL		COMB
0 XD	REAL	COMB		1	XDCM	REAL	ARRAY	MANEUV
6 XDEF	REAL	COMB		1256	XDO	REAL		COMA
1270 XDM	REAL	COMA		7723	XDTGM	REAL	ARRAY	MANEUV
3 XDTG	REAL	COMB		64	XDTGO	REAL		COMA
445 XDTGHS	REAL	COMA		14	XLOS	REAL		EXTRA
1446 XE	REAL	COMA		577	XMAN	REAL	ARRAY	COMA
0 XM	REAL	COMA		440	XN	REAL		COMA
1137 X11S	REAL	MISD		453	XS	REAL		COMA
1035 X21ME	REAL	COMA		1562	XTA	REAL		COMA
545 XT	REAL	MANEUV		25	XX	REAL	ARRAY	EXTRA
2 XTFRM	REAL	EXTRA		62	Y	REAL	ARRAY	DELT
2 XYS	REAL	COMA		1433	YC	REAL		COMA
3 YA	REAL	COMA		1	YD	REAL		COMB
1123 YCOMP	REAL	COMA		7	YDEF	REAL		COMB
13 YDE	REAL	COMB						

VARIABLES	SN	TYPE	RELOCATION	1326	YDM	REAL	ARRAY	COMA
2507 YDM	REAL	MANEUV	4 YDTG	REAL	COMB			
1257 YJO	REAL	COMA	503 YDTGMS	REAL	COMA			
7761 YDTG	REAL	MANEUV	1504 YE	REAL	COMA			
55 YDTGO	REAL	COMA	3 YH	REAL	MISD			
15 YLOS	REAL	EXTRA	454 YS	REAL				
10056 YPOME	REAL	MANEUV	1663 YTA	REAL	COMA			
627 YT	REAL	ARRAY	4 ZA	REAL	COMD			
144 Z	REAL	ARRAY	1434 ZC	REAL	COMA			
1600 ZALT	REAL	COMA	2 ZU	REAL	COMB			
1121 ZCOMP	REAL	COMA	10 ZDEF	REAL	COMB			
14 ZOC	REAL	COMB	1364 ZDM	REAL	COMA			
5215 ZDEM	REAL	MANEUV	5 ZDTG	REAL	COMB			
1260 ZDO	REAL	COMA	541 ZDTGMS	REAL	COMA			
10017 ZDTJM	REAL	MANEUV	1542 ZE	REAL	COMA			
56 ZDTJO	REAL	COMA	6 ZH	REAL	HISD			
16 ZLOS	REAL	EXTRA	455 ZS	REAL				
10057 ZPOME	REAL	MANEUV	1664 ZTA	REAL	COMA			
711 ZT	REAL	ARRAY						
11 ZZZ	REAL	COMB						

FILE NAMES	MODE
OUTPUT	FMT

EXTERNALS	TYPE	ARGS
COS	REAL	1 LIBRARY
INTERP	REAL	7
SORT	REAL	1 LIBRARY

INLINE FUNCTIONS	TYPE	ARGS
FLOAT	REAL	1 INTRIN

STATEMENT LABELS	0	1	2	3
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230	163	303	10
314	372	46	19
20	256	375	25
213	403	414	67
0 99	0 102	0	155

COMMON BLOCKS	LENGTH
HISJ	14
DEL	300
MU	6
COMB	13
MANEUV	4316
COMA	1165
GTARG	11
COMD	5
COMP	73
EXTRA	72

STATISTICS	7738	507
PROGRAM LENGTH	135278	5975
CM LABELED COMMON LENGTH		

C SUBROUTINE MEAN(AXM,AYM,AZM,ARM,NR, SX,SY,SZ,SS)
C THIS SUBROUTINE CALCULATES THE MEAN AND STANDARD DEVIATION
C OF THE MISS DISTANCES

5 C
C COM407COMP7SI,I99,I88,CLMST(I0),CLS1(I10),CLM2(I10),NSAM,I1,Q2,Q3,
*24,Q5,Q6,W1,W2,W3,W4,W5,W6,I7,I,PLANE,ICON,S2P1,SIP1,A2P1,AIP1,
*S2P2,SIP2,A2P2,AIP2,S2P3,SIP3,A2P3,AIP3,S2P4,SIP4,A2P4,AIP4,S2P5,
*SIP5,A2P5,AIP5,S2P6,SIP6,A2P6,AIP6

10 DIMENSION AX(20),AY(20),AZ(20),ARM(20)
XNR=FLOAT(NR)
XNN=SQRT(XNR/(XNR-1.))
J=0

15 C
C 9 SS=0.
SVS=0.
J=J+1

20 C
C 18 I=1,NR
GO TO (11,12,13,14),J
11 DUM=AXM(I)

25 C
C 12 DUM=AYM(I)
GO TO 15
13 DUM=AZM(I)
GO TO 15

30 C
C 14 DUM=ARM(I)
15 SS=SS+DUM
16 SVS=SVS + DUM*DUM

35 C
C MEAN
SS=SS/XNR
SVS=SVS/XNR

40 C
C STANDARD DEVIATION
DOU=SVS-SS*SS
DSDO=ABS(DOU)

45 C
C SVS=SQRT(DO001)*XNN
GO TO (21,22,23,24),J
21 SX=SS
SVX=SVS

50 C
C 22 SY=SS
SVY=SVS
GO TO 3

55 C
C 23 SZ=SS
SVZ=SVS
GO TO 9

60 C
C 24 PRINT 34
PRINT 35, SX,SY,SZ,SS

65 C
C PRINT 36, SVX,SVY,SVZ,SVS
IF(I99.NE.1) GO TO 45
IF(PLANE.EQ.0) GO TO 45
IF(PLANE.EQ.1) GO TO 40
IF(PLANE.EQ.2) GO TO 41

SUBROUTINE MEAN

74774 OH=1

FTNH 4.2+75348

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IF (IPLANE.EQ.3) GO TO 42
40 IF (SVY.GI.S2P1.OR.SVY.LI.S1P1) IFT=1
IF (SVZ.GI.S2P2.OR.SVZ.LI.S1P2) IFT=1
IF (SV.GI.A2P1.OR.SV.LI.A1P1) IFT=1
IF (SZ.GI.A2P2.OR.SZ.LI.A1P2) IFT=1
GO TO 45

41 IF (SVX.GI.S2P3.OR.SVX.LI.S1P3) IFT=1
IF (SVY.GI.S2P4.OR.SVY.LI.S1P4) IFT=1
IF (SX.GI.A2P3.OR.SX.LI.A1P3) IFT=1
IF (SV.GI.A2P4.OR.SV.LI.A1P4) IFT=1
GO TO 45

42 IF (SVX.GI.S2P5.OR.SVX.LI.S1P5) IFT=1
IF (SVZ.GI.S2P6.OR.SVZ.LI.S1P6) IFT=1
IF (SX.GI.A2P5.OR.SX.LI.A1P5) IFT=1
IF (SZ.GI.A2P6.OR.SZ.LI.A1P6) IFT=1

45 CONTINUE
RETURN

C

34 FORMAT(15X2HXT8X2HXT8X2HXT8X2HRH)

35 FORMAT(75X4HMEANCF10.3)

36 FORMAT(3X6HST DEV4F10.4)

END

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
3 MEAN

VARIABLES SN TYPE RELOCATION

0	ARM	REAL	ARRAY	F.P.	0	AXH	REAL	..	ARRAY	F.P.
0	AYH	REAL	..	F.P.	0	AZM	REAL	..	ARRAY	F.P.
64	A1P1	REAL	..	COMP	70	A1P2	REAL	COMP
74	A1P3	REAL	..	COMP	100	A1P4	REAL	COMP
104	A1P5	REAL	..	COMP	110	A1P6	REAL	COMP
53	A2P1	REAL	..	COMP	67	A2P2	REAL	COMP
73	A2P3	REAL	..	COMP	77	A2P4	REAL	COMP
103	A2P5	REAL	..	COMP	107	A2P6	REAL	COMP
3	CLMS	REAL	..	COMP	15	CLS1	REAL	COMP
27	CLS2	REAL	..	COMP	272	D00	REAL	COMP
273	D000	REAL	..	COMP	271	D00	REAL	COMP
270	I	INTEGER	..	COMP	50	ICON	INTEGER	COMP
56	IFT	INTEGER	..	COMP	57	IPLANE	INTEGER	COMP
0	ISI	INTEGER	..	COMP	2	I88	INTEGER	COMP
1	I99	INTEGER	..	COMP	266	J	INTEGER	COMP
0	NR	INTEGER	..	F.P.	41	NSAM	INTEGER	COMP
42	Q1	REAL	..	COMP	43	Q2	REAL	COMP
44	Q3	REAL	..	COMP	45	Q4	REAL	COMP
46	Q5	REAL	..	COMP	47	Q6	REAL	COMP
0	SS	REAL	..	F.P.	267	SVS	REAL	COMP
274	SVX	REAL	..	COMP	275	SVY	REAL	COMP
276	SVZ	REAL	..	COMP	0	SK	REAL	F.P.
0	SY	REAL	..	F.P.	0	SZ	REAL	F.P.
52	S1P1	REAL	..	COMP	66	S1P2	REAL	COMP
72	S1P3	REAL	..	COMP	76	S1P4	REAL	COMP
102	S1P5	REAL	..	COMP	106	S1P6	REAL	COMP
61	S2P1	REAL	..	COMP	65	S2P2	REAL	COMP
71	S2P3	REAL	..	COMP	75	S2P4	REAL	COMP
101	S2P5	REAL	..	COMP	105	S2P6	REAL	COMP
50	W1	REAL	..	COMP	51	W2	REAL	COMP
52	W3	REAL	..	COMP	53	W4	REAL	COMP
54	W5	REAL	..	COMP	55	W6	REAL	COMP
265	XNH	REAL	..	COMP	264	XNR	REAL	COMP

FILE NAMES MODE
OUTPUT FMTEXTERNALS TYPE ARGS
SORT REAL 1 LIBRARYINLINE FUNCTIONS TYPE ARGS
ROS REAL 1 INTRIN

STATEMENT LABELS

23	9	43	11	45	12
47	13	51	14	52	15
0	18	77	21	103	22
107	23	113	24	251	34
255	35	260	36	130	40
155	41	202	42	226	45

COMMON BLOCKS LENGTH
COMP 73

STATISTICS

PROGRAM LENGTH	3218	209
CM LABELED COMMON LENGTH	1118	73


```

SUBROUTINE INTERP(X,XT,YT,NX,NPX,Y,NERR)
  C
  C DESCRIPTION
  C THIS ROUTINE USES THE LAGRANGE INTERPOLATION FORMULA TO
  C CALCULATE THE VALUE YF(X) FROM THE FUNCTION TABLE YF(XI)
  C F(XI(I)). THE TABLE OF INDEPENDENT VARIABLES MUST BE IN
  C INCREASING ORDER BUT DO NOT HAVE TO BE EVENLY SPACED. IF THE
  C DESIRED ARGUMENT X IS NOT IN THE INDEPENDENT VARIABLE TABLE,
  C THE ROUTINE WILL EXTRAPOLATE USING THE NEAREST POINTS TO THE
  C UNKNOWN VALUE. THE DEGREE OF THE INTERPOLATION FORMULA IS A
  C VARIABLE AND MAY BE SELECTED BY THE USER.
  C
  C INPUT
  C 1 X THE INDEPENDENT VARIABLE X
  C 2 XT TABLE OF INDEPENDENT X VALUES. MUST BE IN
  C INCREASING ORDER.
  C 3 YT TABLE OF DEPENDENT Y VALUES. YT(I)=F(XT(I))
  C 4 NX NUMBER OF POINTS IN XT.
  C 5 NPX NUMBER OF POINTS USED IN THE INTERPOLATING FORMULA
  C WITH XT AS THE INDEPENDENT VARIABLE TABLE. (NPX=2)
  C IS THE DEGREE OF THE INTERPOLATION FORMULA USED.
  C
  C OUTPUT
  C 1 Y THE INTERPOLATED DEPENDENT VALUE. Y=F(X)
  C 2 NERR NERR=0 IF XT(I) .LE. X .LE. XT(NX)
  C NERR = 1 IF X .LT. XT(1)
  C NERR = 2 IF X .GT. XT(NX)
  C
  C DIMENSION XT(1),YT(1)
  C NERR = 0
  C NP=NPX
  C IF (NX .LT. NP) NP = NX
  C NS = (NX+169)/76
  C IH = NP/2
  C I = 1
  C IF (XT(I) - X)30,20,10
  C 10 NERR = 1
  C 12 NERR = 1
  C 13 NERR = 2
  C 20 Y = YT(I)
  C 30 I = NX
  C 50 L = IH + 1
  C IF (XT(I) - X)13,20,30
  C 13 = NS+L
  C IF (NX-IS)58,58,52
  C 52 DO 54 I=1,NX,NS
  C IF (XT(I) - X)54,20,56
  C 54 L = I
  C 60 TO 58
  C 56 L = I - NS
  C 58 DO 50 I=L,NX
  C IF (XT(I) - X)160,20,70
  C 60 CONTINUE
  C 70 K = I - IH
  C Y = K + NP - 1
  C Y = 0.0
  C IF (IH - NX)90,90,80
  
```



```
      80 N = NX  
      K = NX-NP+1  
      90 DO 120 J=K,N  
      P = 1.0  
      00 110 I=K,N  
      IF (I-J)100,110,100  
      100 P = P * (X - XT(I)) / (XT(J) - XT(I))  
      110 CONTINUE  
      120 Y = Y + YT(J)*P  
      999 RETURN  
      END
```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
J INTERP

VARIABLES	SN	TYPE	RELOCATION	153	154	155	156	157	158	159	160	161	162	163	164	165	166	167	168	169	170	171	172	173	174	175	176	177	178	179	180	181	182	183	184	185	186	187	188	189	190	191	192	193	194	195	196	197	198	199	200	201	202	203	204	205	206	207	208	209	210	211	212	213	214	215	216	217	218	219	220	221	222	223	224	225	226	227	228	229	230	231	232	233	234	235	236	237	238	239	240	241	242	243	244	245	246	247	248	249	250	251	252	253	254	255	256	257	258	259	260	261	262	263	264	265	266	267	268	269	270	271	272	273	274	275	276	277	278	279	280	281	282	283	284	285	286	287	288	289	290	291	292	293	294	295	296	297	298	299	300	301	302	303	304	305	306	307	308	309	310	311	312	313	314	315	316	317	318	319	320	321	322	323	324	325	326	327	328	329	330	331	332	333	334	335	336	337	338	339	340	341	342	343	344	345	346	347	348	349	350	351	352	353	354	355	356	357	358	359	360	361	362	363	364	365	366	367	368	369	370	371	372	373	374	375	376	377	378	379	380	381	382	383	384	385	386	387	388	389	390	391	392	393	394	395	396	397	398	399	400	401	402	403	404	405	406	407	408	409	410	411	412	413	414	415	416	417	418	419	420	421	422	423	424	425	426	427	428	429	430	431	432	433	434	435	436	437	438	439	440	441	442	443	444	445	446	447	448	449	450	451	452	453	454	455	456	457	458	459	460	461	462	463	464	465	466	467	468	469	470	471	472	473	474	475	476	477	478	479	480	481	482	483	484	485	486	487	488	489	490	491	492	493	494	495	496	497	498	499	500	501	502	503	504	505	506	507	508	509	510	511	512	513	514	515	516	517	518	519	520	521	522	523	524	525	526	527	528	529	530	531	532	533	534	535	536	537	538	539	540	541	542	543	544	545	546	547	548	549	550	551	552	553	554	555	556	557	558	559	560	561	562	563	564	565	566	567	568	569	570	571	572	573	574	575	576	577	578	579	580	581	582	583	584	585	586	587	588	589	590	591	592	593	594	595	596	597	598	599	600	601	602	603	604	605	606	607	608	609	610	611	612	613	614	615	616	617	618	619	620	621	622	623	624	625	626	627	628	629	630	631	632	633	634	635	636	637	638	639	640	641	642	643	644	645	646	647	648	649	650	651	652	653	654	655	656	657	658	659	660	661	662	663	664	665	666	667	668	669	670	671	672	673	674	675	676	677	678	679	680	681	682	683	684	685	686	687	688	689	690	691	692	693	694	695	696	697	698	699	700	701	702	703	704	705	706	707	708	709	710	711	712	713	714	715	716	717	718	719	720	721	722	723	724	725	726	727	728	729	730	731	732	733	734	735	736	737	738	739	740	741	742	743	744	745	746	747	748	749	750	751	752	753	754	755	756	757	758	759	760	761	762	763	764	765	766	767	768	769	770	771	772	773	774	775	776	777	778	779	780	781	782	783	784	785	786	787	788	789	790	791	792	793	794	795	796	797	798	799	800	801	802	803	804	805	806	807	808	809	810	811	812	813	814	815	816	817	818	819	820	821	822	823	824	825	826	827	828	829	830	831	832	833	834	835	836	837	838	839	840	841	842	843	844	845	846	847	848	849	850	851	852	853	854	855	856	857	858	859	860	861	862	863	864	865	866	867	868	869	870	871	872	873	874	875	876	877	878	879	880	881	882	883	884	885	886	887	888	889	890	891	892	893	894	895	896	897	898	899	900	901	902	903	904	905	906	907	908	909	910	911	912	913	914	915	916	917	918	919	920	921	922	923	924	925	926	927	928	929	930	931	932	933	934	935	936	937	938	939	940	941	942	943	944	945	946	947	948	949	950	951	952	953	954	955	956	957	958	959	960	961	962	963	964	965	966	967	968	969	970	971	972	973	974	975	976	977	978	979	980	981	982	983	984	985	986	987	988	989	990	991	992	993	994	995	996	997	998	999	1000	1001	1002	1003	1004	1005	1006	1007	1008	1009	1010	1011	1012	1013	1014	1015	1016	1017	1018	1019	1020	1021	1022	1023	1024	1025	1026	1027	1028	1029	1030	1031	1032	1033	1034	1035	1036	1037	1038	1039	1040	1041	1042	1043	1044	1045	1046	1047	1048	1049	1050	1051	1052	1053	1054	1055	1056	1057	1058	1059	1060	1061	1062	1063	1064	1065	1066	1067	1068	1069	1070	1071	1072	1073	1074	1075	1076	1077	1078	1079	1080	1081	1082	1083	1084	1085	1086	1087	1088	1089	1090	1091	1092	1093	1094	1095	1096	1097	1098	1099	1100	1101	1102	1103	1104	1105	1106	1107	1108	1109	1110	1111	1112	1113	1114	1115	1116	1117	1118	1119	1120	1121	1122	1123	1124	1125	1126	1127	1128	1129	1130	1131	1132	1133	1134	1135	1136	1137	1138	1139	1140	1141	1142	1143	1144	1145	1146	1147	1148	1149	1150	1151	1152	1153	1154	1155	1156	1157	1158	1159	1160	1161	1162	1163	1164	1165	1166	1167	1168	1169	1170	1171	1172	1173	1174	1175	1176	1177	1178	1179	1180	1181	1182	1183	1184	1185	1186	1187	1188	1189	1190	1191	1192	1193	1194	1195	1196	1197	1198	1199	1200	1201	1202	1203	1204	1205	1206	1207	1208	1209	1210	1211	1212	1213	1214	1215	1216	1217	1218	1219	1220	1221	1222	1223	1224	1225	1226	1227	1228	1229	1230	1231	1232	1233	1234	1235	1236	1237	1238	1239	1240	1241	1242	1243	1244	1245	1246	1247	1248	1249	1250	1251	1252	1253	1254	1255	1256	1257	1258	1259	1260	1261	1262	1263	1264	1265	1266	1267	1268	1269	1270	1271	1272	1273	1274	1275	1276	1277	1278	1279	1280	1281	1282	1283	1284	1285	1286	1287	1288	1289	1290	1291	1292	1293	1294	1295	1296	1297	1298	1299	1300	1301	1302	1303	1304	1305	1306	1307	1308	1309	1310	1311	1312	1313	1314	1315	131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SUBROUTINE FLIGHT
INTEGER PIN(4),POUT(4),SL5,SL0
REAL MAN,MISS,MISSED
COMMON/CONA/LEVEL,IPTS,XXS(50),XDTG0,YDTG0,ZDTG0,RLB,COSE,SP0,
*RI,GAM,EQOT,THETAL,RN,PPX(50),PPY(50),PPZ(50),TIME(50),TS(30),
XDTGNS(30),YDTGNS(30),ZDTGNS(30),MAN(4,50),MISSED(7),NT,XCOMP,
*YCOMP,ZCOMP,TAN(30),DELTA(30),VM(30),G,GGG,XDO,YDO,ZDO,DYG,DYG,
*DG,S2,S3,S4,S5,XDM(30),YDM(30),ZDM(30),RLBK,SCALEP,FI,F2,F3,G1,
*G2,G3,XC,YC,ZC,S1,RRR,SR,SPL,CTL,STL,CPL,A1,VII,XE(30),YE(30),
*ZE(30),ZALT,NERR,CLA,NPX,NX,CLAA(10),PHO,ARG,AAA,SCALEY,IREAL,
*THA(30),XTA,YTA,ZTA,SCALEV,MM(10),QM,SA,CA,VMA(50),VMT(50),
*VNZ(50),ECOS(17),HRYEE(17),FI7(9),FCI7(9)
COMMON/CONA/MPATH,LOOP1,LOOP2,DASF(11),ADSF(10),INFLRT,LTHAX
COMMON/ADCL2/
*IAIDIR1,IAIDIR2,IAIDIR3,IAIDIR4,IAIDIR5,IAIDIR6,
*IAIDIR7,IAIDIR8,IAIDIR9,IAIDIR10
COMMON/IDIS2/IN
JAN,ON
COMMON/DAC1/49,
*DAOUT1,DAOUT2,DAOUT3,DAOUT4,DAOUT5,DAOUT6,
*DAOUT7,DAOUT8,DAOUT9,DAOUT10,DAOUT11
COMMON/IDIS2/IOFF
NAMELIST/TEST/LEVEL,IPTS,XXS,XDTG0,YDTG0,ZDTG0,RLB,COSE,SP0,
IRI,GAM,EQOT,THETAL,RN,PPX,PPY,PPZ,TIME,TS,
XDTGNS,YDTGNS,ZDTGNS,MAN,MISSED,NT,XCOMP,
ZCOMP,ZCOMP,TAN,DELTA,VM,G,GGG,XDO,YDO,ZDO,DYG,DYG,
DG,S2,S3,S4,S5,XDM,YDM,ZDM,RLBK,SCALEP,FI,F2,F3,G1,
G2,G3,XC,YC,ZC,S1,RRR,SR,SPL,CTL,STL,CPL,A1,VII,XE,YE,
ZE,ZALT,NERR,CLA,NPX,NX,CLAA,PHO,ARG,AAA,SCALEY,IREAL,
THA,XTA,YTA,ZTA,SCALEV,MM,QM,SA,CA,VMA,VMT,
VNZ,ECOS,HRYEE,FI7,FCI7,
MPATH,LOOP1,LOOP2,DASF,ADSF,INFLRT,LTHAX

CHECK AND PRINT TRUNK SET-UP
PIN(1)=3RV13
PIN(2)=3RV15
PIN(3)=3RV60
PIN(4)=3RV61
LEN=4
CALL PATSTAT(PIN,POUT,LEN)
WRITE(6,1000) (PIN(I),POUT(I),I=1,4)

SAVE INITIAL CONDITIONS FOR RESTARTING PROGRAM
SAVE1=XDTG0
SAVE2=YDTG0
SAVE3=ZDTG0
SAVE4=RLB
SAVE5=COSE
SAVE6=SP0
SAVE7=RI
SAVE8=GAM
SAVE9=EQOT
SAVE10=THETAL
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SAVE11=RN

RESERVE HYBRID EQUIPMENT

5 PAUSE "GO TO RESERVE HYBRID EQUIPMENT".

CALL RESERVE(IERR)

WRITE(6,2000) IERR

IF(IERR.NE.0) GO TO 5

PRE REAL TIME INITIALIZATION

NPATH=1

LOOP1=0

LOOP2=0

INFLRT=-1

LTMAX=0

LEVEL=-7

XOIGO=SAVE1

YOIGO=SAVE2

ZTOGO=SAVE3

RLG =SAVE4

COSE =SAVE5

SPO =SAVE6

RI =SAVE7

CAM =SAVE8

LOOT =SAVE9

THETAL=SAVE10

RN=SAVE11

INITIALIZATION OF DIGITAL TO ANALOG SCALE FACTORS

DASF(1)=1./20000.

DASF(2)=1./20000.

DASF(3)=1./20000.

DASF(4)=1./100.

DASF(5)=1./10.

DASF(6)=1./100.

DASF(7)=1./200000.

DASF(8)=1./100.

JASF(9)=1./60.

DASF(10)=1./1000.

DASF(11)=1./1000.

INITIALIZATION OF ANALOG TO DIGITAL SCALE FACTORS

AOSF(1)=2000.

AOSF(2)=2000.

AOSF(3)=2000.

AOSF(4)=10.

AOSF(5)=20000.

AOSF(6)=20000.

AOSF(7)=20000.

AOSF(8)=20000.

AOSF(9)=20000.

AOSF(10)=20000.

2000 FORMAT(//,*, RESERVATION ERROR CODE = *,020)
3000 FORMAT(//,*, REAL TIME STATUS = *,020)
4000 FORMAT(//,*, WAIT LOOP EXECUTED *,18,*, TIMES *)
5000 FORMAT(//,*, REAL TIME LOOP EXECUTED *,18,*, TIMES *)
11000 FORMAT(//,*, MAXIMUM LOOP TIME = *,15,*, MICROSECONDS *)
END

175

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS

1 FLIGHT

VARIABLES	SN	TYPE	RELOCATION	16	ASDF	REAL	ARRAY	COMH
1621 AAA	REAL	COMH		16	ASDF	REAL		COMH
1620 APG	REAL	COMH		672	ASDF	REAL		COMH
1444 A1	REAL	COMH		1702	CA	REAL		COMH
1602 CLA	REAL	COMH		1605	CLAA	REAL	ARRAY	COMH
70 CGSE	REAL	COMH		1443	CPL	REAL		COMH
1441 CTL	REAL	COMH		502160	DAOUT1	REAL		COMH
502171 JAOUT10	REAL	COMH		502172	DAOUT11	REAL		COMH
502151 JAOUT12	REAL	COMH		502162	DAOUT13	REAL		COMH
502163 JAOUT14	REAL	COMH		502166	DAOUT15	REAL		COMH
502155 JAOUT16	REAL	COMH		502166	DAOUT17	REAL		COMH
502167 JAOUT18	REAL	COMH		502170	JAOUT19	REAL		COMH
3 JASF	REAL	COMH	ARRAY	1160	DELTA	REAL	ARRAY	COMH
1251 JAS	REAL	COMH		1262	JYG	REAL		COMH
1253 JGS	REAL	COMH		2131	ECOS	REAL	ARRAY	COMH
74 EGOI	REAL	COMH		2204	FCI77	REAL	ARRAY	COMH
2123 F171	REAL	COMH	ARRAY	1426	F1	REAL		COMH
1425 F2	REAL	COMH		1426	F3	REAL		COMH
1254 G	REAL	COMH		73	SAM	REAL		COMH
1255 GGG	REAL	COMH		1427	G1	REAL		COMH
1430 G2	REAL	COMH		1431	G3	REAL		COMH
2152 H27EE	REAL	COMH	ARRAY	574	I	INTEGER		COMH
504001 IADINI	INTEGER	COMH		504012	IADINI1	INTEGER		COMH
504002 IADIN2	INTEGER	COMH		504003	IADIN3	INTEGER		COMH
504004 IADIN4	INTEGER	COMH		504005	IADIN5	INTEGER		COMH
504006 IADIN6	INTEGER	COMH		504007	IADIN7	INTEGER		COMH
504010 IADIN8	INTEGER	COMH		504011	IADIN9	INTEGER		COMH
710 IER	INTEGER	COMH		514000	IIN	INTEGER		COMH
39 IMPRT	INTEGER	COMH		515100	IOUT	INTEGER		COMH
1413 IAF3	INTEGER	COMH		713	ISTAT	INTEGER		COMH
712 LARA	INTEGER	COMH		573	LEN	INTEGER		COMH
0 LEVEL	INTEGER	COMH		1	LOOP1	INTEGER		COMH
2 LCO2	INTEGER	COMH		31	LTHAX	INTEGER		COMH
577 M3H	REAL	COMH	ARRAY	671	MISS	REAL	*UNDEF	COMH
1107 MISSED	REAL	COMH	ARRAY	1601	NERR	INTEGER		COMH
0 NPAH	INTEGER	COMH		1603	NPX	INTEGER		COMH
1116 N1	INTEGER	COMH		1604	NX	INTEGER		COMH
1617 PHO	REAL	COMH		714	PIN	INTEGER	ARRAY	COMH
720 POUT	INTEGER	COMH	ARRAY	77	PPX	REAL	ARRAY	COMH
161 PPY	REAL	COMH	ARRAY	243	PPZ	REAL	ARRAY	COMH
1700 R1	REAL	COMH	COMH	1656	RNH	REAL	ARRAY	COMH
72 R1	REAL	COMH		67	RLB	REAL	ARRAY	COMH
1422 R3AK	REAL	COMH		76	RN	REAL		COMH
1436 R3B	REAL	COMH		1701	SA	REAL		COMH
575 SAVE1	REAL	COMH		706	SAVE1U	REAL		COMH
707 SAVE11	REAL	COMH		675	SAVE2	REAL		COMH
577 SAVE3	REAL	COMH		700	SAVE4	REAL		COMH
701 SAVE5	REAL	COMH		702	SAVE6	REAL		COMH
703 SAVE7	REAL	COMH		704	SAVE8	REAL		COMH
705 SAVE9	REAL	COMH		1423	SCALEP	REAL		COMH
1522 SCALET	REAL	COMH		1665	SCALEV	REAL		COMH
570 SLO	INTEGER	COMH		667	SLS	INTEGER		COMH

VARIABLES SN TYPE RELOCATION

1440 SPL	REAL	71 SPO	REAL	COMA
1437 SR	REAL	1442 STL	REAL	COMA
1435 S1	REAL	1264 S2	REAL	COMA
1263 S3	REAL	1266 S4	REAL	COMA
1267 S5	REAL	1122 TAMA	REAL	COMA
75 THETAL	REAL	325 TIME	REAL	COMA
1624 TMA	REAL	1623 TREAL	REAL	COMA
407 TS	REAL	1216 VNI	REAL	COMA
1703 VMX	REAL	1765 VNY	REAL	COMA
2047 VMZ	REAL	1445 VTI	REAL	COMA
1432 XC	REAL	1117 XCOMP	REAL	COMA
1270 XDM	REAL	1256 XDO	REAL	COMA
445 XDTGMS	REAL	64 XDTGO	REAL	COMA
1446 XE	REAL	1662 XTA	REAL	COMA
2 XXS	REAL	1433 YC	REAL	COMA
1120 YCOMP	REAL	1328 YDM	REAL	COMA
1257 YDO	REAL	503 YDTGMS	REAL	COMA
55 YDTGO	REAL	1504 YE	REAL	COMA
1663 YTA	REAL	1600 ZALT	REAL	COMA
1434 ZC	REAL	1121 ZCOMP	REAL	COMA
1364 ZDM	REAL	1260 ZOO	REAL	COMA
541 ZDTGMS	REAL	56 ZDTGO	REAL	COMA
1542 ZE	REAL	1664 ZTA	REAL	COMA
711 ZTGOO	REAL			

FILE NAMES MODE
TAPE6 MIXED

EXTERNALS TYPE ARGS

BHOLD	0	INTCHVT	2
PATSTAT	3	RESERVE	1
SIMRUN	1		

NAMELISTS

TEST

STATEMENT LABELS

44 9	125 10	134 20
611 1000 FMT	620 2000 FMT	625 3000 FMT
632 4000 FMT	640 5000 FMT	646 11000 FMT

COMMON BLOCKS LENGTH

COMA	1165
COMM	28

STATISTICS

PROGRAM LENGTH	7468	485
CH LABELED COMMON LENGTH	22478	1191


```

SUBROUTINE REALT
  INTEGER, PARAMETER, SL6
  REAL MAN, MISS, MISSED
  COMMON/COMA/LEVEL,IPIS,XXST150T,XDT50,YDT50,ZDT50,XLB,COSE,SPD,
  *RI,CAM,EDOT,TETAL,RN,PPX(50),PPY(50),TIME(50),TIS(30),
  *XDTCHS(30),YDTCHS(30),ZDTCHS(30),MAN(4,50),MISSED(7),NT,XCOMP,
  *YCOMP,ZCOMP,TAMA(30),DELTAR(30),VH(30),G,GGG,XDO,YDO,ZDO,DYG,DYG,
  *JZG,SZS3,S4,S5,XON(30),YON(30),ZON(30),G,SCALEP,F1,F2,F3,G1,
  *G2,G3,XC,YC,ZC,S1,RRR,SR,SPL,CTL,STL,CPL,A1,VII,XE(30),YE(30),
  *ZE(30),ZALT,HERK,CLA,NPX,UX,CLAA(10),PHO,ARG,AA4,SCALEP,TREAL,
  *TMA(30),XTA,YTA,ZTA,SCALEV,QNM(10),QM,SA,CA,VMX(50),VMY(50),
  *VMZ(50),ECOS(17),HRZEE(17),F17(19),FCI77(19)
  COMMON/COMH/NPATH,LOOP1,LOOP2,DASF(11),ADSF(10),INFLRT,LTMAX
  COMMON/ADG172,
  *IADIN1,IADIN2,IADIN3,IADIN4,IADIN5,IADIN6,
  *IADIN7,IADIN8,IADIN9,IADIN10
  COMMON/IOIS2/IIY
  JAM,ON
  COMMON/DA01/49,
  *DAOUT1,DAOUT2,DAOUT3,DAOUT4,DAOUT5,DAOUT6,
  *DAOUT7,DAOUT8,DAOUT9,DAOUT10,DAOUT11
  COMMON/ODIS2/100T
  JAM,OFF
  DATA HASK/3777777B/

  25 C C ABNORMAL ABORT IF SENSE LINE 15 IS HIGH
  C
  SL15=IIN.AND.2**15
  IF(SL15.NE.0)GO TO 100

  30 C C NPATH=1 -- WAITING FOR SENSE LINE 6 TO COME HIGH
  C NPATH=2 -- FLIGHT IN PROGRESS
  C
  GO TO (10,20),NPATH

  35 C C INITIALIZATION OF FLAGS AND INDICES
  C
  10 IF(INFRT.GT.0) GO TO 15
  INFRT=1
  ITT=1
  INDEX=1
  KGR=1
  ADSF1=ADSF(1)
  ADSF2=ADSF(2)
  ADSF3=ADSF(3)
  ADSF8=ADSF(8)
  ADSF9=ADSF(9)
  ADSF10=ADSF(10)
  NL1=0
  NL2=0
  NL3=0
  NL4=0
  NL5=0
  NL6=0
  IOUT=2**15+2**4

  55 C C BEGIN FLIGHT IF SENSE LINE 6 IS HIGH

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AD-A052 676

B-K DYNAMICS INC ROCKVILLE MD
SUMMARY REPORT OF STINGER CONVERSION ACTIVITIES. (U)
JUL 76

F/G 9/2

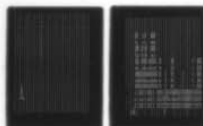
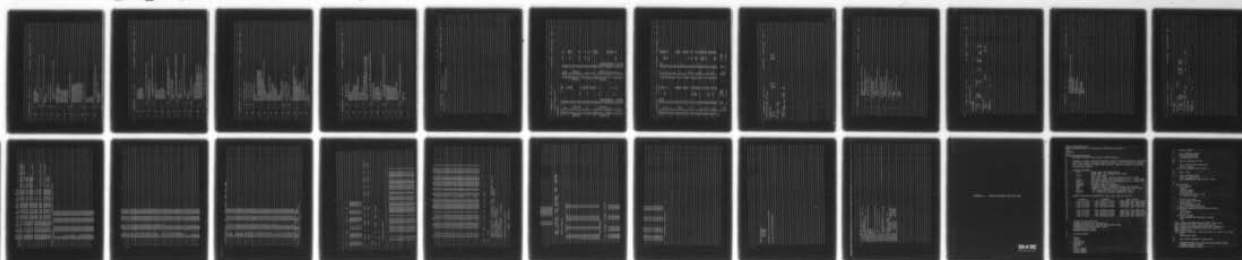
DAAH01-75-C-0194

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BKD-TR-3-206

NL

4 OF 4
AD
A052 676



END
DATE
FILMED
5-78

DDC



115 PPZ(INDEX)=DZ

TIME(INDEX)=DT

VMX(INDEX)=XDOT

VMY(INDEX)=YDOT

VMZ(INDEX)=ZDOT

MAN=7

120 C IF TIME IS GREATER THAN TPRIME, CHECK FOR MISS

C

60 IF(DY-LE.G) GO TO 50

MISS=XDOT*DX+YDOT*DY+ZDOT*DZ

125 C

C IF MISSILE HAS MISSED TARGET, STORE THE ASSOCIATED VALUES

C AND TERMINATE

C

130 IF(MISS.LE.0) GO TO 50

MISSED(1)=DX

MISSED(2)=DY

MISSED(3)=DZ

MISSED(4)=XDOT

MISSED(5)=YDOT

MISSED(6)=ZDOT

MISSED(7)=MISS

GO TO 100

140 C IF TARGET TRAJECTORY TABLE HAS BEEN EXCEEDED OR TARGET

C MANEUVER HAS NOT YET BEGUN, END LOOP

C

50 IF(LEVEL.GT.0) CALL SIMIDLE

IF(DT.LT.TS(1)) CALL SIMIDLE

LEVEL=0

145 C FIND POSITION IN TARGET TRAJECTORY TABLE FOR INTERPOLATION

C

60 IT2=IT1+1

IF(DT.LT.TS(IT2)) GO TO 70

IT1=IT1+1

IF((IT1-LT.NT).AND.(IT1-LT.30)) GO TO 60

150 C SET INDICATOR FOR TARGET TRAJECTORY TABLE EXCEEDED AND END

C THIS LOOP

C

LEVEL=7

CALL SIMIDLE

160 C INTERPOLATE TARGET MANEUVER

C

70 LIV=TS(IT2)-TS(IT1)

RATIO=(DT-TS(IT1))/LIV

XCOMP=XDOTGMS(IT1)+RATIO*(XDOTGMS(IT2)-XDOTGMS(IT1))

XC=XOM(IT1)+RATIO*(XOM(IT2)-XOM(IT1))

YCOMP=YDOTGMS(IT1)+RATIO*(YDOTGMS(IT2)-YDOTGMS(IT1))

YC=YOM(IT1)+RATIO*(YOM(IT2)-YOM(IT1))

ZCOMP=ZDOTGMS(IT1)+RATIO*(ZDOTGMS(IT2)-ZDOTGMS(IT1))

ZC=ZOM(IT1)+RATIO*(ZOM(IT2)-ZOM(IT1))

170 C COMPUTATION OF TARGET INERTIAL VELOCITY

C


```
      C      VTISQRT(XC*XC*YC*YC+ZC*ZC)
      C      CHECK FOR HELICOPTER
175      C      IF(VTI.LT.338.0) GO TO 80
      C      COMPUTATION OF COSE
180      C      ARR=.003394*ZALT+1115.89
      C      ZH=VTI/AAA
      C      NX=8
      C      CALL LINTRP(QM,CLAA,NX,NL1,RA1,CLA,NER1)
      C      CALL LINTRP(UT,TMA,XE,NT,NL2,RA2,XTA,NER2)
      C      CALL LINTRP(OT,TMA,YE,NT,NL3,RA3,YTA,NER3)
      C      CALL LINTRP(OT,TMA,ZE,NT,NL4,RA4,ZTA,NER4)
      C      PHOS=.00237692*EXPI(.00003*ZALT)
      C      TEMPN=.01745329*4.637084242*SQRT(XTA*XTA+YTA*YTA+ZTA*ZTA)
190      C      TEMPD=PHO*VTI*VII*CLA
      C      A1=TEMPN/TEMPD
      C      SA=INITIAL)
      C      GACDSTAI)
      C      RFEET=SQRT(XXX*XXX+YYY*YYY+ZZZ*ZZZ)
195      C      RRR=VTI*RFEET
      C      F1=S2*XXX-SPL*YYY+S3*ZZZ
      C      F2=S4*XXX+CPL*YYY+S5*ZZZ
      C      F3=CTL*ZZZ-STL*XXX
      C      SR=SQRT(XC*XC+YC*YC)
200      C      S1=CA+(SA/SR)*ZC
      C      G1=S1*XC
      C      G2=S1*YC
      C      G3=CA*ZC-SA*SR
      C      COSE=(F1*G1+F2*G2+F3*G3)/RRR
      C      COMPUTATION OF RLB
      C      RLB=RLJK*SQRT(1.-COSE*COSE)
      C      COMPUTATION OF RN
210      C      GO TO 75
      C      NX=17
215      C      CALL LINTRP(COSE,ECOS,HRTEE,NX,NL5,RA5,HR7E,NER5)
      C      TEMP=-2-341*ALOG(RFEET/22965.831)
      C      MC7FT=1209.675*EXP(TEMP)*HR7E
      C      PI1933=2.2*ATANT(.57RLB)
      C      PI1933=22.5*RLB/RFEET
      C      TEMPN=CINIP1IRSS)*PI1933**2
220      C      TEMPD=C.COS(PI1933/2.)***2
      C      A17=TEMPN/TEMPD
      C      PJTUI=EXP(11.003258*ALOG(AT7))/10.
      C      FI7=MC7FT/PJTUI
      C      NX=9
225      C      CALL LINTRP(FI7,FI7T,FCI7T,NX,NL6,RA6,FCI7,NER6)
      C      KN=FCI7
      C      75 CONTINUE
```

```

230      C      COMPUTATION OF SPO
          RC1=F2/3QRT(F1+F1+F2+F2)
          PCN=ACOS(RC1)
          RCX=-RC1
          RCY=SIN(PCN)
          IF(F1.GE.0) RCY=-RCY
          F11=(F2*G3-F3*G2)/VTI
          F22=(F3*G1-F1*G3)/VTI
          F33=(F1*G2-F2*G1)/VTI
          FCF=SQRT(F11*F11+F22*F22+F33*F33)
          G11=F11*RCX
          G22=F22*RCY
          G111=(G11+G22)/FCR
          T111=ACOS(G111)
          IF(F33.LT.0.) TRP=1.570796326-T111
          IF((F33.GE.0.) .AND. (T111.LE.1.570796326)) TRP=1.570796326+T111
          IF((F33.GE.0.) .AND. (T111.GT.1.570796326)) TRP=T111-4.71238898
          SPO=TRP

240      C      STORE TARGET DATA IF A RANGE TABLE ENTRY WAS REACHED THIS LOOP
          C
          C      80 IF(MAN.EQ.0) GO TO 90
          IF(IJEX.GT.50) GO TO 90
          MAN(1,INDEX)=0
          MAN(2,INDEX)=XCOMP
          MAN(3,INDEX)=YCOMP
          MAN(4,INDEX)=ZCOMP
          INDEX=INDEX+1
          IF(INDEX.GT.IPTS) GO TO 100

250      C      IF DATA COLLECTION IS NOT COMPLETE, SEND VARIABLES TO ANALOG
          C      AND END THIS LOOP
          C
          90  DAOUT1=XCOMP*OASF(1)
          DAOUT2=YCOMP*OASF(2)
          DAOUT3=ZCOMP*OASF(3)
          DAOUT4=RLB*OASF(4)
          DAOUT5=COSQ*OASF(5)
          DAOUT6=SPO*OASF(5)
          DAOUT11=XH*OASF(11)
          LTC=200-STAT(MASCT)
          IF(LTC.GT.LTMAX) LTMAX=LTC
          CALL SINTOLE

260      C      SET CONTROL LINE 7 HIGH AND TERMINATE REAL TIME
          C
          100  IOUT=128
          CALL SIMSTOP
          END

```

CARD NR. SEVERITY DETAILS DIAGNOSIS OF PROBLEM

213 I THERE IS NO PATH TO THIS STATEMENT.

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
I REAL

VARIABLES	SN	TYPE	RELOCATION	COMA	16	ADSF	REAL	ARRAY	COMM
1621 AAA	REAL				727	ADSF10	REAL		
722 ADSF1	REAL				724	ADSF3	REAL		
723 ADSF2	REAL				726	ADSF9	REAL		
725 ACSF8	REAL				776	AT7	REAL		
1620 ARG	REAL				1702	CA	REAL		COMA
1444 AL	REAL				1605	CLAA	REAL		COMA
1602 CLA	REAL				1443	CPL	REAL	ARRAY	COMA
70 COSC	REAL				1016	C111	REAL		COMA
1441 CTL	REAL				502171	JAOUT10	REAL		
502150 JAOUT11	REAL				502161	JAOUT12	REAL		
502172 JAOUT11	REAL				502163	JAOUT14	REAL		
502162 JAOUT13	REAL				502165	JAOUT15	REAL		
502154 JAOUT5	REAL				502167	JAOUT8	REAL		
502156 JAOUT7	REAL				3	DASF	REAL	ARRAY	COMM
502170 JAOUT9	REAL				752	DIV	REAL		
1153 DELTAR	REAL				740	DX	REAL		
736 DT	REAL				741	JY	REAL		
1261 JXG	REAL				742	JZ	REAL		
1262 UYG	REAL				2131	EGOS	REAL	ARRAY	COMA
1253 JZS	REAL				1002	FC17	REAL		
74 EUST	REAL				1013	FCR	REAL		
2204 FC177	REAL				2173	F17T	REAL	ARRAY	COMA
1000 F17	REAL				1010	F11	REAL		
1424 F1	REAL				1011	F22	REAL		
1425 F2	REAL				1012	F33	REAL		
1426 F3	REAL				73	GAM	REAL		COMA
1254 G	REAL				1427	G1	REAL		COMA
1255 G55	REAL				1430	G2	REAL		COMA
1414 G11	REAL				1431	G3	REAL		COMA
1015 G22	REAL				770	HR7E	REAL		
773 HC7FT	REAL				504001	IADIN1	INTEGER		
2152 HR7EE	REAL				504002	IADIN2	INTEGER		
504012 IADIN10	INTEGER				504004	IADIN4	INTEGER		
504003 IADIN3	INTEGER				504006	IADIN6	INTEGER		
504035 IADIN5	INTEGER				504010	IADIN3	INTEGER		
504037 IADIN7	INTEGER				514000	IIN	INTEGER		
504011 IADIN9	INTEGER				30	INFLRT	INTEGER		COMA
720 INEX	INTEGER				1	IPTS	INTEGER		COMA
516100 IOUT	INTEGER				751	IT2	INTEGER		
717 IT1	INTEGER				0	LEVEL	INTEGER		
721 KCK	INTEGER				2	LOOP2	INTEGER		COMA
1	LCOP1				31	LTMAX	INTEGER		COMA
1021 LTC	INTEGER				667	MASK	INTEGER		COMA
577 M21	REAL				1107	MISSD	REAL	ARRAY	COMA
715 M23	REAL				755	NER1	INTEGER		
1601 M22	INTEGER				761	NER3	INTEGER		
753 M24	INTEGER				771	NER5	INTEGER		
1033 M25	INTEGER				730	NL1	INTEGER		
731 NL2	INTEGER				732	NL3	INTEGER		
733 NL4	INTEGER				734	NL5	INTEGER		

VARIABLES	SN	TYPE	RELOCATION	D	NPATH	INTEGER	COMA
735 HL6	735	INTEGER	COMA	1115	NT	INTEGER	COMA
1603 NPX	1603	INTEGER	COMA	1617	PHO	REAL	COMA
1604 NX	1604	REAL	COMA	77	PPX	REAL	COMA
777 PJT01	777	REAL	COMA	243	PPZ	REAL	COMA
151 PPY	151	REAL	COMA	775	P2IRSS	REAL	COMA
774 P1RSS	774	REAL	COMA	1666	JMH	REAL	COMA
1700 JM	1700	REAL	COMA	754	RA1	REAL	COMA
753 RATIO	753	REAL	COMA	760	RA3	REAL	COMA
756 R42	756	REAL	COMA	787	RA5	REAL	COMA
752 R24	752	REAL	COMA	1005	RC3	REAL	COMA
1001 R45	1001	REAL	COMA	1007	RCY	REAL	COMA
1006 RCX	1006	REAL	COMA	766	RFEET	REAL	COMA
1004 R21	1004	REAL	COMA	67	RLB	REAL	COMA
72 RI	72	REAL	COMA	76	RN	REAL	COMA
1422 RLK	1422	REAL	COMA	1701	SA	REAL	COMA
1435 R55	1435	REAL	COMA	1622	SCALET	REAL	COMA
1423 SCALEP	1423	REAL	COMA	737	SXK	REAL	COMA
1655 SCALEV	1655	REAL	COMA	714	SL6	REAL	COMA
716 SL15	716	REAL	COMA	71	SPO	REAL	COMA
1640 SPL	1640	REAL	COMA	1442	STL	REAL	COMA
1437 SR	1437	REAL	COMA	1266	S2	REAL	COMA
1435 SI	1435	REAL	COMA	1266	S4	REAL	COMA
1265 S3	1265	REAL	COMA	1122	TAMA	REAL	COMA
1267 S5	1267	REAL	COMA	765	TEMPO	REAL	COMA
772 TE4P	772	REAL	COMA	75	THETA	REAL	COMA
754 TEMPN	754	REAL	COMA	1624	TMA	REAL	COMA
325 TIME	325	REAL	COMA	1020	TRP	REAL	COMA
1523 TRAL	1523	REAL	COMA	1017	T111	REAL	COMA
407 TS	407	REAL	COMA	1703	VHX	REAL	COMA
1215 VM	1215	REAL	COMA	2047	VHZ	REAL	COMA
1755 VHY	1755	REAL	COMA	713	VMAN	REAL	COMA
1445 VTI	1445	REAL	COMA	1117	XCOMP	REAL	COMA
1432 XC	1432	REAL	COMA	1256	XDO	REAL	COMA
1273 XOM	1273	REAL	COMA	1445	XE	REAL	COMA
743 XOST	743	REAL	COMA	2	XXS	REAL	COMA
84 XH160	84	REAL	COMA	1433	YC	REAL	COMA
1652 XTA	1652	REAL	COMA	1326	YDH	REAL	COMA
746 XX	746	REAL	COMA	744	YDOT	REAL	COMA
1120 YCOMP	1120	REAL	COMA	65	YOTGO	REAL	COMA
1257 YDZ	1257	REAL	COMA	1663	YIA	REAL	COMA
503 YOTJMS	503	REAL	COMA	1600	ZALT	REAL	COMA
1504 YE	1504	REAL	COMA	1121	ZCOMP	REAL	COMA
747 YYY	747	REAL	COMA	1260	ZUO	REAL	COMA
1434 ZC	1434	REAL	COMA	541	ZDTGMS	REAL	COMA
1354 ZDM	1354	REAL	COMA	1542	ZE	REAL	COMA
745 ZDOT	745	REAL	COMA	750	ZZZ	REAL	COMA
66 ZOTGO	66	REAL	COMA				
1654 ZTA	1654	REAL	COMA				

EXTENDALS	TYPE	ARGS	REAL	ALOG	REAL	1 LIBRARY
ACJ3	REAL	1 LIBRARY	REAL	ALOG	REAL	1 LIBRARY
ATAN	REAL	1 LIBRARY	REAL	ALOG	REAL	1 LIBRARY
EXP	REAL	1 LIBRARY	REAL	ALOG	REAL	1 LIBRARY
LINTRP	REAL	8	REAL	ALOG	REAL	1 LIBRARY
SI*STOP	REAL	0	REAL	ALOG	REAL	1 LIBRARY
SG*P	REAL	1 LIBRARY	REAL	ALOG	REAL	1 LIBRARY

01/12/76 14.31.39.

FTNH 4.2+75348

SUBROUTINE REALY 74774 OPT=1

INLINE FUNCTIONS TYPE ARGS
STAT NO TYPE 1 INTRIN

STATEMENT LABELS

14	10	37	15	46	20
102	30	164	40	205	50
214	60	225	70	430	75
513	80	525	90	552	100

COMMON BLOCKS LENGTH

COMMON	1165
COMMON	26

STATISTICS

PROGRAM LENGTH	10228	530
CY LABELED COMMON LENGTH	22478	1191

SUBROUTINE LINTRP 74774 OPT=1

SUBROUTINE LINTRP(X,XT,YT,NX,NL,RA,Y,NERR)

DIMENSION XT(1),YT(1)

NERR=0

IF (XT(1).GE.1).AND.(NL.LT.NX)) GO TO 10

INITIALIZE NL AND RA

NL=1

RA=(YT(2)-YT(1))/(XT(2)-XT(1))

10 IF (X.GE.XT(NL)) GO TO 30

NL IS TOO LARGE

20 IF (NL.EQ.1) GO TO 50

NL=NL-1

IF (X.LT.XT(NL)) GO TO 20

RA=(YT(NL+1)-YT(NL))/(XT(NL+1)-XT(NL))

GO TO 50

30 IF (X.LE.XT(NL+1)) GO TO 50

NL IS TOO SMALL

40 IF (NL.EQ.NX-1) GO TO 70

NL=NL+1

IF (X.GT.XT(NL+1)) GO TO 40

RA=(YT(NL+1)-YT(NL))/(XT(NL+1)-XT(NL))

50 Y=YT(NL)+RA*(X-XT(NL))

RETURN

60 NERR=1

X IS LESS THAN XT(1)

Y=YT(1)

RETURN

70 NERR=2

X IS GREATER THAN XT(NX)

Y=YT(NX)

RETURN

CND


```
FUNCTION HMFLOT(INPJT)
DATA IVLMSK/37777B/,CONVRT/.000061030881/,ISNSK/40000B/
INTER=AND(IVLMSK,INPJT)
ISGN=NOT(ISNSK,INPJT)
IF (ISGN.EQ.0) GO TO 10
ISGN=-1
INTER=COMPL(INTER)
INTER=AND(IVLMSK,INTER)
GO TO 20
10 ISGN=1
20 REAL=INTER*CONVRT
HMFLOT=REAL*ISGN
RETURN
END
```

SYMBOLIC REFERENCE MAP (R=1)

ENTRY POINTS
4 HMFLOT

VARIABLES		SN	TYPE	RELOCATION	25	HMFLOT	REAL
23	CONVRT		REAL		26	INTER	INTEGER
0	IMPJT		INTEGER	F.P.	24	ISMSK	INTEGER
27	ISGN		INTEGER		30	REAL	REAL
22	IVLSK		INTEGER				

INLINE FUNCTIONS		TYPE	ARGS	AND	NO TYPE	2	INTRIN	COMPL	NO TYPE	1	INTRIN
14	10										

STATEMENT LABELS

14 10 15 20

STATISTICS

PROGRAM LENGTH 318 25

RTSEE MAIN(0).REALT(1)
GLOBAL COMA,COMM
END

CMHOF	PROGRAM	+023402	0000002
KODER	PROGRAM	+023454	0000460
AKAKER	PROGRAM	+024144	0000414
QUITCON	PROGRAM	+024560	0000141
FLTCUT	PROGRAM	+024721	0000310
INCOME	PROGRAM	+025231	0000262
FLTIME	PROGRAM	+025313	0000153
OPEN.S2	PROGRAM	+025666	0000260
OPEN.RM	PROGRAM	+026146	0000235
PUT.SQ	PROGRAM	+026403	0001227
CLSF.RM	PROGRAM	+027632	0000023
Z.SQ	PROGRAM	+027655	0000101
SKFL.S2	PROGRAM	+027756	0000087
SYS.RH	PROGRAM	+030025	0000051
LXER.S2	PROGRAM	+030076	0000210
BRT.S2	PROGRAM	+030306	0000114
GET.SQ	PROGRAM	+030422	0000777
CHWR.SQ	PROGRAM	+031421	0000007
CTO.RH	PROGRAM	+031430	0000042
ERR.RH	PROGRAM	+031472	0000400
MCT.RH	PROGRAM	+032072	0000233
OSUB.RM	PROGRAM	+032325	0000067
CLSV.S2	PROGRAM	+032414	0000131
LBUF.S2	PROGRAM	+032545	0000133
YRCL	PROGRAM	+032700	0000030
OPCX.S2	PROGRAM	+032740	0000015
CLSF.SQ	PROGRAM	+032745	0000131
MOVE.RM	PROGRAM	+033076	0000064
KL11.RM	PROGRAM	+033162	0000042
FSU.SQ	PROGRAM	+033224	0000110
WAR.SQ	PROGRAM	+033334	0000256
ATAN	PROGRAM	+033612	0000065
ALOG	PROGRAM	+033677	0000073
EXP	PROGRAM	+033772	0000076
COJDER	PROGRAM	+034070	0000014
SIMERR.	PROGRAM	+034104	0000015
PUT.RY	COMMON	+034121	0000011
CLSV.FO	COMMON	+034132	0000007
GET.FO	COMMON	+034141	0000007
GET.BT	COMMON	+034150	0000005
SKFL.FO	COMMON	+034155	0000007
GET.RT	COMMON	+034164	0000011
CLSF.FO	COMMON	+034175	0000007
PUT.FO	COMMON	+034204	0000007
JPES.FO	COMMON	+034213	0000001
MEMC.RM	COMMON	+034214	0000003
OPEN.FO	COMMON	+034217	0000007
JMPS.RM	COMMON	+034226	0000011
CON.RM	COMMON	+034237	0000005
AGR.RH	COMMON	+034245	0000010
IO.BUF.	COMMON	+034255	0000227
LOCOR.	COMMON	+034304	0000042
2R.IO.	COMMON	+034346	0000134
MU	COMMON	+034702	0000006
UCMD	COMMON	+034710	0000005
DELT	COMMON	+034715	0000454
MISJ	COMMON	+035371	0000015
PK	COMMON	+035407	0000242
ARG	COMMON	+035551	0000004
EXTRA	COMMON	+035555	0000110
COMP	COMMON	+035765	0000111
GTARG	COMMON	+036076	0000013
MANEUV	COMMON	+036111	0010334
COMB	COMMON	+046445	0000015
COMH	COMMON	+046462	0000032
COMA	GLOBAL	+046514	0002215

***** SEGMENT REALT

[illegible]

```

*****
*** FN.GLOBAL..SEGMENT...SAFETY.....FMA
      COMA      MAIN      SAFE      +046462
      COMA      MAIN      SAFE      +046514
*****
***** CM BLANK COMMON FMA= +032053 LMA= +082053
*****

```


ISI = 0 NSAM = 2 ICON = 2 INL = 2

CLMS = 3.75000 CLS1 = 0.00000 CLS2 = 3.26700
 CLMS = 2.39400 CLS1 = 0.00000 CLS2 = 2.56800
 CLMS = 1.88000 CLS1 = 0.00000 CLS2 = 2.26600
 CLMS = 1.59600 CLS1 = 0.00000 CLS2 = 2.08900
 CLMS = 1.51000 CLS1 = 0.00000 CLS2 = 1.97000
 CLMS = 1.27700 CLS1 = .11800 CLS2 = 1.88200
 CLMS = 1.17500 CLS1 = .13500 CLS2 = 1.81500
 CLMS = 1.09400 CLS1 = .23900 CLS2 = 1.76100
 CLMS = 1.02800 CLS1 = .28400 CLS2 = 1.71600
 CLMS = .97300 CLS1 = .32200 CLS2 = 1.67800

Q1 = 0.00000 Q2 = 0.00000 Q3 = 0.00000 Q4 = 0.00000 Q5 = 0.00000 Q6 = 0.00000

W1 = 0.00000 W2 = 0.00000 W3 = 0.00000 W4 = 0.00000 W5 = 0.00000 W6 = 0.00000

NRUNS = 1

NPTS = 10 DX = 20.00000 XTERM = 100.00000

HL = 39

TABLE OF LAUNCH CONDITIONS

SET	ALTITUDE	ALTITUDE	FT	CROSSING ANGLE	DEG	INITIAL RANGE	FT
SET 1	1442.90	1442.90	FT	323.00	DEC	13123.40	FT
SET 2	2624.70	2624.70	FT	285.00	DEC	2952.80	FT
SET 3	1442.90	1442.90	FT	38.00	DEC	13123.40	FT
SET 4	1312.30	1312.30	FT	338.00	DEC	6561.70	FT
SET 5	3280.80	3280.80	FT	315.00	DEC	8202.10	FT
SET 6	3280.80	3280.80	FT	300.00	DEC	9842.50	FT
SET 7	3280.80	3280.80	FT	60.00	DEC	9842.50	FT
SET 8	2296.60	2296.60	FT	45.00	DEC	4921.30	FT
SET 9	1312.30	1312.30	FT	23.00	DEC	3608.90	FT
SET 10	1312.30	1312.30	FT	10.00	DEC	3608.90	FT
SET 11	1312.30	1312.30	FT	350.00	DEC	3937.00	FT
SET 12	2296.60	2296.60	FT	0.00	DEC	6233.60	FT
SET 13	1968.50	1968.50	FT	355.00	DEC	7545.90	FT
SET 14	1640.40	1640.40	FT	345.00	DEC	9842.50	FT
SET 15	1640.40	1640.40	FT	338.00	DEC	9842.50	FT
SET 16	328.10	328.10	FT	210.00	DEC	2624.70	FT
SET 17	328.10	328.10	FT	195.00	DEC	2624.70	FT
SET 18	328.10	328.10	FT	165.00	DEC	2624.70	FT
SET 19	2296.60	2296.60	FT	150.00	DEC	4921.30	FT
SET 20	1968.50	1968.50	FT	39.00	DEC	4921.30	FT
SET 21	1640.40	1640.40	FT	23.00	DEC	4921.30	FT

SET	22	ALTITUDE	1547	FT	CROSSING	ANGLE	5.00	EG	INITIAL	RANGE	E	721.70
SET 23	ALTITUDE	1968.50	FT	CROSSING	ANGLE	350.00	DEG	INITIAL	RANGE			
SET 24	ALTITUDE	984.20	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 25	ALTITUDE	492.10	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 26	ALTITUDE	1312.30	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 27	ALTITUDE	1640.40	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 28	ALTITUDE	1968.50	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 29	ALTITUDE	492.10	FT	CROSSING	ANGLE	225.00	DEG	INITIAL	RANGE			
SET 30	ALTITUDE	492.10	FT	CROSSING	ANGLE	240.00	DEG	INITIAL	RANGE			
SET 31	ALTITUDE	1968.50	FT	CROSSING	ANGLE	180.00	DEG	INITIAL	RANGE			
SET 32	ALTITUDE	1640.40	FT	CROSSING	ANGLE	180.00	DEG	INITIAL	RANGE			
SET 33	ALTITUDE	492.10	FT	CROSSING	ANGLE	135.00	DEG	INITIAL	RANGE			
SET 34	ALTITUDE	1968.50	FT	CROSSING	ANGLE	75.00	DEG	INITIAL	RANGE			
SET 35	ALTITUDE	1968.50	FT	CROSSING	ANGLE	30.00	DEG	INITIAL	RANGE			
SET 36	ALTITUDE	1968.50	FT	CROSSING	ANGLE	30.00	DEG	INITIAL	RANGE			
SET 37	ALTITUDE	1640.40	FT	CROSSING	ANGLE	30.00	DEG	INITIAL	RANGE			
SET 38	ALTITUDE	1312.30	FT	CROSSING	ANGLE	30.00	DEG	INITIAL	RANGE			
SET 39	ALTITUDE	984.20	FT	CROSSING	ANGLE	10.00	DEG	INITIAL	RANGE			
SET 40	ALTITUDE	1968.50	FT	CROSSING	ANGLE	345.00	DEG	INITIAL	RANGE			
SET 41	ALTITUDE	1968.50	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 42	ALTITUDE	492.10	FT	CROSSING	ANGLE	323.00	DEG	INITIAL	RANGE			
SET 43	ALTITUDE	1968.50	FT	CROSSING	ANGLE	323.00	DEG	INITIAL	RANGE			
SET 44	ALTITUDE	1312.30	FT	CROSSING	ANGLE	315.00	DEG	INITIAL	RANGE			
SET 45	ALTITUDE	328.10	FT	CROSSING	ANGLE	270.00	DEG	INITIAL	RANGE			
SET 46	ALTITUDE	2296.50	FT	CROSSING	ANGLE	195.00	DEG	INITIAL	RANGE			
SET 47	ALTITUDE	1640.40	FT	CROSSING	ANGLE	165.00	DEG	INITIAL	RANGE			
SET 48	ALTITUDE	1640.40	FT	CROSSING	ANGLE	90.00	DEG	INITIAL	RANGE			
SET 49	ALTITUDE	1640.40	FT	CROSSING	ANGLE	45.00	DEG	INITIAL	RANGE			
SET 50	ALTITUDE	1312.30	FT	CROSSING	ANGLE	45.00	DEG	INITIAL	RANGE			
SET 51	ALTITUDE	328.10	FT	CROSSING	ANGLE	30.00	DEG	INITIAL	RANGE			
SET 52	ALTITUDE	2296.50	FT	CROSSING	ANGLE	23.00	DEG	INITIAL	RANGE			
SET 53	ALTITUDE	1968.50	FT	CROSSING	ANGLE	15.00	DEG	INITIAL	RANGE			
SET 54	ALTITUDE	1968.50	FT	CROSSING	ANGLE	0.00	DEG	INITIAL	RANGE			
SET 55	ALTITUDE	328.10	FT	CROSSING	ANGLE	330.00	DEG	INITIAL	RANGE			
SET 56	ALTITUDE	492.10	FT	CROSSING	ANGLE	180.00	DEG	INITIAL	RANGE			
SET 57	ALTITUDE	328.10	FT	CROSSING	ANGLE	180.00	DEG	INITIAL	RANGE			
SET 58	ALTITUDE	492.10	FT	CROSSING	ANGLE	180.00	DEG	INITIAL	RANGE			
SET 59	ALTITUDE	3437.90	FT	CROSSING	ANGLE	53.06	DEG	INITIAL	RANGE			
SET 60	ALTITUDE	3281.00	FT	CROSSING	ANGLE	45.00	DEG	INITIAL	RANGE			

III = 0 IRSS = 1 KA = 60 ITT = 39 NOGO = 1

TAU = 0.00000

PSI LAUNCH = 315.00 DEG THETA LAUNCH = 19.47 DEG INITIAL RANGE = 9843.00 FT
 XTEO = 8551.99 FT YTEO = 5552.01 FT ZTEO = 3281.00 FT
 I-PRIME = 4.4760 SEC DELTAR AT 1000 FT TO GO = 6749.50 FT
 I-AT-GAMA MIN OVERLOAD = 1.9452 SEC
 DELTAR AT GAMA MIN OVERLOAD = 1875.8 FT
 VN-AT-GAMA MIN OVERLOAD = 1906.2 FT/SEC
 GAMA = 4.3570

SMALLEST BIT A/D RESOLUTION = .0896 FT
 NPIS = 10 DX = 20.00 FT XTERM = 100.00 FT

RANGE-TO-GO TABLE FOR DATA COLLECTION

RANGE, FT SCALED RANGE

286.00 --28000000E+03
260.00 --26000000E+03
240.00 --24000000E+03
220.00 --22000000E+03
200.00 --20000000E+03
180.00 --18000000E+03
160.00 --16000000E+03
140.00 --14000000E+03
120.00 --12000000E+03
100.00 --10000000E+03

XOTE0 = 0.00 FI/SEC YOTE0 = 1013.40 FI/SEC ZOTE0 = 0.00 FI/SEC
XOTL0 = -675.60 FI/SEC YOTL0 = 716.58 FI/SEC ZOTL0 = -238.86 FI/SEC
CROSSING ANGLE = 45.00 DEG DIVE ANGLE = 0.00 DEG

EARTH FIXED COORDINATES

TIME	XD MANEUVER	YD MANEUVER	ZD MANEUVER
0.0000	0.00	1013.40	0.00
1.0000	0.00	1013.40	0.00
2.0000	0.00	1013.40	0.00
3.0000	0.00	1013.40	0.00
4.0000	0.00	1013.40	0.00
5.0000	0.00	1013.40	0.00
6.0000	0.00	1013.40	0.00
7.0000	0.00	1013.40	0.00
8.0000	0.00	1013.40	0.00
9.0000	0.00	1013.40	0.00
10.0000	0.00	1013.40	0.00
11.0000	0.00	1013.40	0.00
12.0000	0.00	1013.40	0.00
13.0000	0.00	1013.40	0.00
14.0000	0.00	1013.40	0.00
15.0000	0.00	1013.40	0.00
16.0000	0.00	1013.40	0.00
17.0000	0.00	1013.40	0.00
18.0000	0.00	1013.40	0.00
19.0000	0.00	1013.40	0.00
20.0000	0.00	1013.40	0.00
21.0000	0.00	1013.40	0.00
22.0000	0.00	1013.40	0.00
23.0000	0.00	1013.40	0.00
24.0000	0.00	1013.40	0.00
25.0000	0.00	1013.40	0.00
26.0000	0.00	1013.40	0.00

LAUNCH COORDINATES

TIME	XD MANEUVER	YD MANEUVER	ZD MANEUVER
0.0000	-675.60	716.58	-238.86
1.0000	-675.60	716.58	-238.86
2.0000	-675.60	716.58	-238.86
3.0000	-675.60	716.58	-238.86
4.0000	-675.60	716.58	-238.86
5.0000	-675.60	716.58	-238.86
6.0000	-675.60	716.58	-238.86
7.0000	-675.60	716.58	-238.86
8.0000	-675.60	716.58	-238.86
9.0000	-675.60	716.58	-238.86

11.0000	-675.60	716.58	-238.86
12.0000	-675.60	716.58	-238.86
13.0000	-675.60	716.58	-238.86
14.0000	-675.60	716.58	-238.86
15.0000	-675.60	716.58	-238.86
16.0000	-675.60	716.58	-238.86
17.0000	-675.60	716.58	-238.86
18.0000	-675.60	716.58	-238.86
19.0000	-675.60	716.58	-238.86
20.0000	-675.60	716.58	-238.86
21.0000	-675.60	716.58	-238.86
22.0000	-675.60	716.58	-238.86
23.0000	-675.60	716.58	-238.86
24.0000	-675.60	716.58	-238.86
25.0000	-675.60	716.58	-238.86
26.0000	-675.60	716.58	-238.86

RANDOM NUMBER IS .33689963E01

TRUNK LINE PATCHING IS

V13 TO M00

V15 TO M13

V60 TO M50

V61 TO M50

RESERVATION ERROR CODE = 000000000000000000

*REAL TIME STATUS = 0000000000000000000000

HIGON SCUPE 3.9.2 HY SM 48 MAX LEVEL 7C
 14.29.51.RLP0507 FROM /G2
 14.29.53.1P 00010496 WORDS - FILE INPUT - DC 00
 14.29.57.RLPGS.1100.CM140000.RI.
 14.29.58.74.37G1300 7300 A3 PARKER J003
 14.30.09.FTHM.
 14.31.51. 19.125 CP SECONDS COMPIATION TIME
 14.31.53.SEGLOAU.
 14.31.53.LOAD(UGO)
 14.31.53.NOGO.
 14.33.24.RFL.65000.
 14.33.24.ABS.
 14.33.32. PAUSE GO TO RESERVE HYBRID EQUIPMENT
 14.33.40.G0
 14.33.41. PAUSE WAIT FOR SENSE LINE 5 HIGH
 14.34.05. GO
 14.34.05. GO
 14.34.34.G0
 14.34.39.J003 01J ENTRY REAL TIME
 14.34.51. PAUSE SET SENSE LINE 0 LOW TO RESTART
 14.36.51.T A 030 RUN
 14.36.34.G0
 14.36.35.ERROR NOJE - 4. ADDRESS = 016975
 14.36.45.INT 090-ET0000003153268
 14.36.45.JP 00036992 WORDS - FILE OUTPUT - DC 77
 14.36.45.MS 28672 WORDS (114688 MAX USED)
 14.36.45.CPA 25.579 SEC. 23.023 ADJ.
 14.36.45.I0 11.433 SEC. 6.496 ADJ.
 14.36.45.CH 930.224 KWS. 9.661 ADJ.
 14.36.45.PP 59.975 SEC. DATE 01/12/76
 14.36.45.EJ END OF JOB, G2

APPENDIX C. CODE FOR TESTING ADCS AND DACS


```

C      PIN(4)=3RV53
C      CALL RESERVE(IERR)
C      WRITE(6,1000)IERR
C      IF(IERR.NE.0)STOP
C
C      CHECK PATCHING STATUS
C
C      CALL PATSTAT(PIN,POUT,LEN)
C      DO 10 I=1,LEN
10  WRITE(6,8000)PIN(I),POUT(I)
C
C      REAL TIME
C
C      CALL SIMRUN(ISTAT)
C      WRITE(6,2000)ISTAT
C      CALL REMARK(17H JOB IN REAL TIME)
C
C
25  CONTINUE
C      CALL BHOLD
C      LINE=0
C      WRITE(6,5000)
C      IPAGE=IPAGE+1
C      IF(IPAGE.EQ.10)GO TO 20
C      I1=IOUT-MAXLINE+1
C
C      DO 30 I=I1,IOUT
C      CALL BITS(I,IBITOUT)
C      LINE=LINE+1
C      IDUMY=ISAVEIN(LINE)
C      CALL BITS(IDUMY,IBITIN)
30  WRITE(6,4000)I,IBITOUT,IDUMY,IBITIN
C      LINE=0
C      CALL SIMGO
C      GO TO 25
20  WRITE(6,3000)
C      CALL REMARK(15H RETURN TO MAIN)
C      STOP
C
1000 FORMAT(24H1RESERVATION ERROR CODE=,020)
2000 FORMAT(18H REAL TIME STATUS=,020)
3000 FORMAT(1H0,*PROGRAM TERMINATED NORMALLY*)
4000 FORMAT(10X,I10,5X,I6I1,5X,I10,5X,I6I1)
5000 FORMAT(1H1)
8000 FORMAT(/#0TRUNK  LINE PATCHING IS *,R3,* TO *,R3)
C      END
C      SUBROUTINE SUB1
C
C      REAL TIME INTERRUPT SUBROUTINE
C
C      COMMON/INTCOM/IOUT,LINE,MAXLINE,ISAVEIN(100)
C      COMMON/*IDIS2/1,IIDIS
C      COMMON/*ODIS2/1,IODIS

```



```

C      IODIS=IOUT
C      IN=IIDIS
C      LINE=LINE+1
C      ISAVEIN(LINE)=IN
C      IF(IOUT.GE.2**16-1)IOUT=0
C      IF(IOUT.LT.2**16-1)IOUT=IOUT+1
C      IF(LINE.GE.MAXLINE)CALL SIMHOLD
C      CALL SIMDLE
C      END
C      SUBROUTINE BITS(IIN,IBIT)
C      PROGRAM TO CONVERT BASE TEN TO BITS
C
C      THE LEAST SIGNIFICANT BIT IS STORED IN BIT(1)
C
C      PROGRAM VARIABLES
C          IIN          A NUMBER BASE TEN
C          IBIT(I)      I-TH BIT OF A BINARY NUMBER
C          MAXBIT       MAXIMUM BITS CONVERTED IN INPUT SENSE LINE
C
C      INTEGER OLDNUM
C      DIMENSION IBIT(16)
C      MAXBIT=16
C      DO 1 I=1,MAXBIT
1  IBIT(I)=0
C      OLDNUM=IIN
C      DO 2 I=1,MAXBIT
C      NEWNUM=OLDNUM/2
C      IBIT(I)=OLDNUM-2*NEWNUM
C      OLDNUM=NEWNUM
2  CONTINUE
C      IHALF=MAXBIT/2
C      DO 3 I=1,IHALF
C      ITEMP=IBIT(I)
C      IBIT(I)=IBIT(MAXBIT+1-I)
3  IBIT(MAXBIT+1-I)=ITEMP
C      RETURN
C      END
000000000000000000000000
C      RTREE TRDISIO(0),SUB1(1)
C      GLOBAL INTCOM
C      END
000000000000000000000000
000000000000000000000000
000000000000000000000000

```



```

WRITE(6,1000)IERR
IF (IERR.NE.0)STOP

C
C
C   REAL TIME

CALL SIMRUN(ISTAT)
WRITE(6,2000)ISTAT
CALL REMARK(17H JOB IN REAL TIME)
WRITE(6,5000)
25 CONTINUE
CALL BHOLD
LINE=LINE+1
IF (LINE.GT.MAXLINE)GO TO 50
TIMELFT=STATUS.A.3777777B
WRITE(6,4000)OUT,BACK,LOOP
WRITE(6,6000)DIFF
OUT=OUT+0.01
IF (OUT.GT.1.50)OUT=0.0
LOOP=0
CALL SIMGO
GO TO 25
50 WRITE(6,3000)
STOP

1000 FORMAT(24H1RESERVATION ERROR CODE=,020)
2000 FORMAT(18H REAL TIME STATUS=,020)
3000 FORMAT(1H0,*PROGRAM TERMINATED ON MAX LINE*)
4000 FORMAT(1X,17F7.4,I3)
5000 FORMAT(1H1)
6000 FORMAT(8X,16F7.4)
END
SUBROUTINE SUB1

C
C
C   REAL TIME INTERRUPT SUBROUTINE

COMMON/INTCOM/OUT,LOOP,BACK(16),BIGDIFF,DIFF(16),STATUS,J
COMMON/*ADC1/ 1,ADC(16)
COMMON/*DAC1/ 1,DAC(16)
IERR=0
DO 1 I=1,16
DAC(I)=OUT
1 BACK(I)=ADC(I)
C   COMPUTE DIFFERENCE IN ADC AND DAC VALUES
C
DO 2 I=1,16
DIFF(I)=ABS(OUT)-ABS(BACK(I))
IF (ABS(DIFF(I)).GT.BIGDIFF)IERR=1
2 CONTINUE
IF (IERR.EQ.0)CALL SIMHOLD
STATUS=STAT(J)
LOOP=LOOP+1
STATUS=STAT(J)
IF (LOOP.EQ.10)CALL SIMHOLD
CALL SIMIDLE
END
000000000000000000000000
RTREE TRALG10(0),SUB1(1)
GLOBAL INTCOM
END
000000000000000000000000
000000000000000000000000
000000000000000000000000

```